bt - A Realtime Beat Tracker
Final Report

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1 Primary Objective

bt is a live beat tracker — a device that reads a stream of music and, in realtime, makes a guess at its tempo.

Beat analysis is an important field of audio signal processing. It’s used in a variety of applications in the music universe. For example, DJ software finds the tempo and beat locations of the tracks in the user’s library beforehand in order to make synchronizing two playing tracks a straightforward process. It’s also used in audio-controlled lighting to generate complex displays that react to music.

Most of the time, beat analysis is done before its information is actually needed. As a result, these preprocessing algorithms (there are numerous) can be very accurate.

2 Background

Realtime tempo estimation of a live stream is a difficult problem to solve, especially compared to a pre-processing-based approach. In this case, we’re looking not only to accurately identify a best estimate for the tempo, but also to converge on that estimate as quickly as possible.

One algorithm involves trying to classify portions of a music stream as “beats” and then tries to match those beats against one of many possible tempos, eventually narrowing in on a most likely candidate. This includes creating a series of phase-locking metronomes, each running at a different tempo, and trying to match detected beats to subdivision of each metronome. It’s as though we have purchased a hundred or so physical metronomes, put someone in front of each metronome, played a stream of music, and had each person reset their metronome when they heard a beat — the difference is that we are able to measure just how far each metronomes was off from that beat and keep a running average of that value.
3 Why Dedicated Hardware?

This algorithm is more of an entertaining novelty than anything else; nobody would actually use it in a real product. But it does offer some interesting ideas with respect to parallelism. Namely, dedicated hardware offers the ability to instantiate, for example, 60 or 70 different metronomes with very precise timing, all running independently of one another. This would not be possible using conventional CPU architecture – most threaded models lose precision after just a few metronomes. Furthermore, realtime beat classification is a challenging algorithm to implement on most CPUs, even though there are often plenty of clock cycles between audio samples. Although this project does not use a frequency-aware beat classification algorithm, it one were to switch to it, one would surely desire dedicated hardware for taking large FFTs.

4 High Level Design

Figure 1 illustrates the overall architecture of the system.

The system starts off by instantiating metronomes with a wide range of tempos. The number of metronomes is limited by the resource constraints of the system. They all wait for the beat classifier to seed them with an initial guess at a beat, at which point they start running. After this initialization phase, the metronomes keep time, each at their own tempo, and when the beat classifier detects a beat in the audio, it delivers a message to all of the metronomes stating...
the likelihood that the event it just saw was a beat. The metronomes then all adjust their phase linearly with the probability that the beat classifier thought it was correct and report their current phase difference to the metronome bank controller.

In this manner, metronomes whose tempo is different from the stream’s real tempo will consistently report large phase errors, while those closer to the real tempo will report smaller phase errors. We can then use these results to generate a probability distribution for the actual tempo. Optionally, after a period of convergence, we can “zoom in” on the possible tempos, trying smaller and smaller increments around the most likely tempo until we converge on a reasonable result. This project does not include that features because enough metronomes were instantiated to fit a large range of tempos with per-BPM precision.

5 Testing

A Spartan 3A-N evaluation board was chosen as it was easily available. While this FPGA is relatively weak, it was able to perform most of the intended design without issue. It has an onboard ADC, so a small DC-biasing circuit with an audio jack was designed and attached to the board, as shown in Figures 2 and 3. The overall setup is shown in Figure 4.

Live audio was fed into the FPGA and the serial stream was read back into the computer.

The simulation testbench operated in much the same way. Samples were read from a data file and fed in with the appropriate clock subdivision. Output samples were then recorded to a new file that could be parsed with a Python script.
Figure 3: DC biasing circuit board

Figure 4: FPGA setup
6 Microarchitecture

6.1 Top Level

The top level module of bt handles inter-module communication as well as sample injection and hardware output.

6.1.1 Interface to Hardware Architecture

The hardware produces audio samples and then requires a handshake to read the sample. The underlying hardware architecture is shown in Figure 5. From the hardware side, the sample injector module provides the following signals:

<table>
<thead>
<tr>
<th>Signal</th>
<th>Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>sample</td>
<td>std_logic_vector(13 downto 0)</td>
</tr>
<tr>
<td>sample_rdy</td>
<td>std_logic</td>
</tr>
<tr>
<td>sample_rd</td>
<td>std_logic</td>
</tr>
</tbody>
</table>

bt therefore waits for input sample_rdy to go high, at which point it captures sample and asserts sample_rd = '1' for one clock cycle. It enqueues the sample to the beat classifier's input FIFO through its put method.

The output of the top module is a FIFO that talks to the underlying hardware. With each detected beat, the FIFO is filled with the phase offsets of all of the metronomes and flushed via the serial controller.
6.2 Beat Classifier

The beat classifier handles the process of receiving injected audio samples and determining when the audio stream has likely produced a beat. It operates as a server. On the put side, we inject samples. On the get side, we receive beat events.

6.2.1 Operation

The beat classification algorithm essentially compares the local energy of a small sample window to the average energy of a much larger window. If there is significant deviation of the local energy from the average energy (either positive or negative), then the beat classifier reports that it saw a beat.

It runs a round of this every time it receives a sample via its InjectSample method, described below. When a new sample has been presented, it computes this instantaneous energy of the sample, by squaring it and accumulates this to the cur_energy register. When NL of such samples are accumulated, we are ready to compare the local energy with the average energy, which is held in the avg_energy register. If the local energy is different from the average energy by a factor F, we report a beat by setting a register valid as described in Section 6.2.4.

We also keep a list of the last NE energy values so that we can perform an arithmetic mean to calculate the average energy. With each new energy, we “kick out” the oldest value out of the average (by subtracting it) and add in the newest value.

6.2.2 Tunable Parameters

There are a few parameters here that can be fine-tuned.

NL basically asks “how many samples corresponds to local energy?” If it’s too small, we may not get a good enough estimate of the signal energy at any given point, but if it’s too large, then we could be including a beat with non-beat portion of the spectrum. Experiments suggest that NL ≈ 1000 works well.

F determines just how different the local energy has to be from the average energy for a beat to be considered. In practice, if we were to think of the ratio of local energy to average energy, F usually works well at about 1.2 or 1.3. However, this can vary by genre. This is why I would eventually like to be able to compute the variance of local energies to determine a best fit for F.

NE determines how many energy components make up the average energy. We target around 1 second’s worth of samples because biologically, the human ear has been found to compare sound energy to a history of about 1 second.

6.2.3 Put Interface

The module has a very small FIFO through which input samples come in on. The top-level module issues put calls to the classifier with audio sample data. This occurs at a frequency of approximately 48 KHz.
6.2.4 Get Interface

For a given input sample, if the beat classifier has detected a beat, it enqueues a BeatGuess to the output FIFO. The top-level module picks this guess up and delivers a beat event to all of the metronomes.

6.3 Metronome

The metronome keeps time to a given tempo. Essentially, it’s a fancy counter that’s not unlike something that one would use as the phase ramp input to a lookup table for a DDS.

6.3.1 Operation

The metronome uses a fixed point representation where the integer part is only 2 bits and the decimal part is much larger (as large as possible while still fitting within the resource constraints). The integer part represents sixteenth notes. When it rolls over from 3 to 0, a quarter note has occurred.

6.3.2 Injecting a Beat: inject beat

When the beat classifier detects a beat, it indicates this to all of the metronomes. The metronome responds by adjusting its counter’s phase to be closest to the nearest sixteenth note according to the BeatLikelihood value. It also returns the phase offset that it had to apply to achieve this back to the top level module (which goes on to deliver this information to the metronome bank controller).

7 Interface

To gather data from the system, a simple software interface was written. Figure 6 shows its output for a playing stream.

8 Evaluation

Throughout the project, this project was built very close to the hardware. Hardware testing was done just as much, if not more than simulation testing throughout the process. Device timing and area constraints were constantly in mind throughout the entire development process.

After an initial period of testing with only a few metronomes, the design was built with over 60 with little issue in regards to timing or area constraints. The metronomes do not perform any complex mathematics at all, so it is very easy to fit a lot of them onto even a very weak FPGA. Figure 7 shows the device utilization.

Examining the timing analysis report, the critical path is through the beat classifier, with the majority of the time is from the energy calculation path. Figure 8 shows the critical path from the timing analysis.
Figure 6: software interface screenshot showing a 134 BPM song

Device utilization summary:
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Selected Device: 3s700anfgg484-4

Number of Slices: 2420 out of 5888 41%
Number of Slice Flip Flops: 2234 out of 11776 18%
Number of 4 input LUTs: 4069 out of 11776 34%
  Number used as logic: 3893
  Number used as Shift registers: 112
Number of I/Os: 36
Number of bonded I/OBs: 26 out of 372 6%
Number of MULT18X18SIOs: 3 out of 20 15%
Number of GCLKs: 2 out of 24 8%
Number of DCMs: 1 out of 8 12%

Figure 7: device utilization
Paths for end point beat_tracker_inst/bc_bc_outfifo/empty_reg (SLICE_X51Y29.G4), 8012777023 paths

<table>
<thead>
<tr>
<th>Source:-beat_tracker_inst/bc_bc_avg_energy_0 (FF)</th>
<th>Destination:beat_tracker_inst/bc_bc_outfifo/empty_reg (FF)</th>
<th>Requirement:40.000ns</th>
</tr>
</thead>
<tbody>
<tr>
<td>Slack (setup path):0.672ns (requirement - (data path - clock path skew + uncertainty))</td>
<td>Data Path Delay:39.188ns (Levels of Logic = 68)</td>
<td>Clock Path Skew:-0.140ns (0.414 - 0.554)</td>
</tr>
<tr>
<td>Source Clock:clk25 rising at 0.000ns</td>
<td>Destination Clock:clk25 rising at 40.000ns</td>
<td>Clock Uncertainty:0.000ns</td>
</tr>
</tbody>
</table>

Maximum Data Path: beat_tracker_inst/bc_bc_avg_energy_0 to beat_tracker_inst/bc_bc_outfifo/empty_reg

<table>
<thead>
<tr>
<th>Location</th>
<th>Logical Resource</th>
<th>Logical Resource(s)</th>
</tr>
</thead>
<tbody>
<tr>
<td>SLICE_X53Y14.XQ</td>
<td>Tcko</td>
<td>0.591 beat_tracker_inst/bc_bc_avg_energy&lt;0&gt; beat_tracker_inst/bc_bc_avg_energy_0</td>
</tr>
<tr>
<td>SLICE_X52Y13.F2</td>
<td>net (fanout=3)</td>
<td>0.483 beat_tracker_inst/bc_bc_avg_energy&lt;0&gt;</td>
</tr>
<tr>
<td>SLICE_X51Y29.G4</td>
<td>net (fanout=1)</td>
<td>0.652 beat_tracker_inst/Mcompar_NOT_SEXT_bc_bc_energy_buf_63_0_11_CONCAT_0_12_ETC___d154_cy&lt;28&gt; beat_tracker_inst/Mcompar_NOT_SEXT_bc_bc_energy_buf_63_0_11_CONCAT_0_12_ETC___d154_cy&lt;28&gt;</td>
</tr>
<tr>
<td>SLICE_X51Y29.CLK</td>
<td>Tgck</td>
<td>0.727 beat_tracker_inst/bc_bc_outfifo/empty_reg_beat_tracker_inst/bc_bc_outfifo/empty_reg_rstpot beat_tracker_inst/bc_bc_outfifo/empty_reg</td>
</tr>
</tbody>
</table>

Total 39.188ns (26.200ns logic, 12.988ns route) (66.9% logic, 33.1% route)

Figure 8: timing analysis
Calculating amount of brainpower spent on bt...

<table>
<thead>
<tr>
<th>Language</th>
<th>Lines</th>
</tr>
</thead>
<tbody>
<tr>
<td>Bluespec:</td>
<td>836</td>
</tr>
<tr>
<td>VHDL:</td>
<td>1390</td>
</tr>
<tr>
<td>Testbench:</td>
<td>85</td>
</tr>
<tr>
<td>LaTeX:</td>
<td>1455</td>
</tr>
<tr>
<td>Shell:</td>
<td>29</td>
</tr>
<tr>
<td>Python:</td>
<td>1030</td>
</tr>
<tr>
<td><strong>Total:</strong></td>
<td><strong>4825</strong></td>
</tr>
</tbody>
</table>

Figure 9: summary of code written for bt

A fair amount of code was involved in this project, as shown in Figure 9. The design used some existing blocks that I had built for this FPGA, as well as a UART block originally built by Digilent. The majority of the project goals were met, but the convergence time is still not what it needs to be. The predicted tempo still has periods where it fluctuates wildly. Better handling of situations where the beat classifier is not sure what’s going on will improve this problem drastically, but I unfortunately did not have enough time to complete that. I hope to spend more time improving this handling.

9 Design Exploration — Thoughts for the Future

9.1 Estimating Best Tempo

Right now, the software interface determines the best tempo estimate from the phase errors of the metronomes. It might be useful to fold this into the FPGA itself. Furthermore, one could use additional information that the current design essentially throws out to improve tempo estimation. By paying attention to how likely we’re in a part of the stream that has a strong beat, we can ignore spurious data more easily and get a better estimate of what the true tempo is.

9.2 Variance-Sensitive Beat Classifier

If we store about 1 second worth of energies, we can perform the following linear regression to determine a good fit for the ratio of the current instantaneous energy to the last second of average energy in order to detect a beat. Thus, we’re looking for:
where $\mu_E$ is the average energy, $e$ is the current instantaneous energy, and $\sigma_E^2$ is the variance of the last second’s worth of energies. More specifically:

$$\mu_E = \frac{1}{n} \sum_{i=0}^{n-1} e_i$$

(2)

$$\sigma_E^2 = \mu_E^2 - (\mu_E)^2$$

(3)

We can rearrange these equations to be more suitable for implementation in a digital system:

$$e \geq 1.5142857 \mu_E - 0.0025714 \sigma_E^2 \mu_E$$

(4)

$$\geq 1.5142857 \mu_E - 0.0025714 (\mu_E^2 - (\mu_E)^2) \mu_E$$

(5)

$$\geq 1.5142857 \mu_E - 0.0025714 \mu_E \mu_E^2 + 0.0025714 (\mu_E)^3$$

(6)

$$\geq 1.5142857 \frac{1}{n} \sum_{i=0}^{n-1} e_i$$

$$- 0.0025714 \left[ \left( \frac{1}{n} \sum_{i=0}^{n-1} (e_i)^2 \right) + \left( \left( \frac{1}{n} \sum_{i=0}^{n-1} e_i \right) \cdot \left( \frac{1}{n} \sum_{i=0}^{n-1} e_i \right) \right) \right] \cdot \left( \frac{1}{n} \sum_{i=0}^{n-1} e_i \right)$$

(7)

(8)

So, if we keep a shift register of the last $n$ energies, as well as the last $n$ energies squared, as well as a running sum of those two, then we can simply subtract the oldest value and add the newest value with each new input energy. This allows us to quickly compute variance with just one extra cycle. From there, we can use Bluespec’s FixedPoint library to compute the value of $e$ in two more cycles (I’m limiting one multiplication per cycle due to resource constraints on the FPGA. We then can compare $e$ to the current instantaneous energy to see if a beat event occurred or not.

The current design does this in 4 linearly-pipelined stages, though eventually failed to meet the resource constraints of the FPGA. I’m exploring alternate designs.

### 9.3 Frequency-Aware Beat Classifier

A far better beat classifier uses frequency data to determine beat likelihood. This helps offset problems that occur in music where two instruments alternate.
9.4 Final Thoughts

I intend to continue working on this project for as long as I can get access to a Bluespec license, which unfortunately won’t be for long given that I’m graduating this year.