Computer System Architecture
6.823 Quiz #2
November 12th, 2021

Name: ____________________________

This is a closed book, closed notes exam.
80 Minutes
14 Pages (+2 Scratch)

Notes:
• Not all questions are of equal difficulty, so look over the entire exam and budget your time carefully.
• Please carefully state any assumptions you make.
• Show your work to receive full credit.
• Please write your name on every page in the quiz.
• You must not discuss a quiz's contents with other students who have not yet taken the quiz.
• Pages 15 and 16 are scratch pages. Use them if you need more space to answer one of the questions, or for rough work.

Part A _______ 15 Points
Part B _______ 30 Points
Part C _______ 25 Points
Part D _______ 30 Points

TOTAL _______ 100 Points
Part A: Multithreading (15 points)

Ben Bitdiddle is designing an out-of-order superscalar processor that supports simultaneous multithreading up to two threads. He is considering different design options for the processor’s committed store buffer. The committed store buffer holds data for stores that have committed until they are written to the L1 cache in program order. An entry is allocated in the store buffer when a store instruction commits, and it is freed when the corresponding value is written to the L1 cache.

Ben’s processor executes two threads, A and B, with the following characteristics:
- Thread A contains 1 store every 4 instructions. Each store takes on average 8 cycles between commit and writing to the L1 cache.
- Thread B contains 1 store every 5 instructions. Each store takes on average 20 cycles between commit and writing to the L1 cache.

Question 1 (8 points)

Ben first considers a shared store buffer design with 6 entries, where the two threads are both allowed to allocate entries on a single store buffer. The processor uses a round-robin fetch policy, which results in each thread committing 1 instruction per cycle. How many store buffer entries are used on average?

Question 2 (7 points)

Ben now considers a split store buffer design where each thread uses a separate 3-entry store buffer. By how much does the overall throughput decrease compared to the shared store buffer in Question 1?
**Part B: Cache Coherence (30 points)**

Ben Bitdiddle is designing a 2-core processor where each core has a private, local cache with shared main memory. The private caches have 4-byte lines and are kept coherent by a directory-based MSI Protocol. The diagrams below show the block diagram of the system (left) and the coherence protocol’s processor-side state-transition diagram (right).

Ben wishes to add a **next-line prefetcher** to each core to reduce the overall number of cache misses in his programs. The prefetcher works by monitoring the cache misses out of the processor. When the processor misses on cache line X and the prefetcher predicts that the next cache line (at address X+4, since lines are 4 bytes long) will soon be accessed by the core, the prefetcher signals the processor to send a ShReq for the next cache line in addition to the original coherence request for cache line X.

**Question 1 (5 points)**

Consider the following sequence of accesses happening in chronological order. Assume that the coherence transaction initiated by a core's read/write finishes before the next core action, including prefetches.

- Core 1: read A
- Core 1: read A+4
- Core 2: write A+4

Assume that all private caches are initially invalid, and Core 1's prefetcher signals the core to send a ShReq for line A+4 upon a cache miss to line A.
(a) Fill in the table below indicating how coherence states for the two cache lines A and A+4 change after each access.

<table>
<thead>
<tr>
<th>Standard MSI Protocol</th>
<th>Core 1's Cache</th>
<th>Core 2's Cache</th>
</tr>
</thead>
<tbody>
<tr>
<td>Initial State</td>
<td>A: I</td>
<td>A: I</td>
</tr>
<tr>
<td></td>
<td>A+4: I</td>
<td>A+4: I</td>
</tr>
<tr>
<td>After Core 1 reads A</td>
<td>A:</td>
<td>A:</td>
</tr>
<tr>
<td></td>
<td>A+4:</td>
<td>A+4:</td>
</tr>
<tr>
<td>After Core 1 reads A+4</td>
<td>A:</td>
<td>A:</td>
</tr>
<tr>
<td></td>
<td>A+4:</td>
<td>A+4:</td>
</tr>
<tr>
<td>After Core 2 writes A+4</td>
<td>A:</td>
<td>A:</td>
</tr>
<tr>
<td></td>
<td>A+4:</td>
<td>A+4:</td>
</tr>
</tbody>
</table>

(b) How many coherence requests (ShReq, ExReq, DownReq, InvReq) were processed throughout the sequence of accesses?

**Question 2 (5 points)**

Now consider the following sequence:

Core 1: read A
Core 2: write A+4
Core 1: read A+4

Again, assume that all private caches are initially invalid, and Core 1's prefetcher signals the core to send a ShReq for line A+4 upon a cache miss to line A. How many coherence requests (ShReq, ExReq, DownReq, InvReq) were processed throughout this new sequence of accesses?
Ben wants to systematically characterize the effects of prefetches. He first classifies prefetches according to their *usefulness* to the requesting core:

- **Useful**: The prefetched line is referenced by the requesting core before it is evicted (either due to a conflict, or due to a write to the line from another core).
- **Useless**: The prefetched line is *not* referenced by the requesting core before it is evicted.

Ben further classifies useless prefetches into two sub-categories according to their *harmfulness* to the remote core:

- **Harmless**: A useless prefetch is initially classified as harmless unless it satisfies the harmfulness criteria specified below.
- **Harmful**: The prefetch downgraded a remote core's copy of the cache line, and that core subsequently wrote to the line before it was evicted.

Note that this means a prefetch can be categorized into one of three classes: Useful, Harmless (implying Useless), and Harmful (also implying Useless).

**Question 3 (5 points)**

Consider the sequences from Questions 1 and 2. How would you classify the two prefetches according to Ben's categorization: Useful, Harmless, or Harmful?

**Question 4 (5 points)**

Describe a sequence of accesses (like those in Question 1 and 2) that cause a *Harmful* prefetch in Ben’s system. All cache lines should start invalid at the beginning of your sequence, and the prefetched line should be in an invalid state at the end of the sequence.

How many extra coherence requests does the prefetch incur for your sequence compared to a 2-core system that does not implement prefetching?
Ben modifies his coherence protocol to reduce the number of Harmful prefetches. Now, all ShReqs also contain a *prefetch bit* that is set if the ShReq was sent due to a prefetch from a core. Since ShReqs with the prefetch bit set are speculative, the directory decides how to process this request as follows: If no other core holds a copy of the line in the modified (M) state, the directory replies with a ShResp since the prefetch can never become Harmful. Otherwise, the directory NACKs the ShReq.

**Question 5 (5 points)**

Does Ben's modification remove all Harmful prefetches? Explain briefly.

**Question 6 (5 points)**

Describe a sequence of accesses for Ben's 2-core system where Ben's modification to the coherence protocol prevents a Useful prefetch from happening.
Part C: Memory Consistency (25 points)

Consider a system with two processors. Assume the following:
- Each processor has a private cache, and *private caches are kept coherent*.
- Memory location A initially contains a value of 0.
- The contents of registers R1 and R2 for both processors alias to the same memory location A, i.e., \(\text{Reg}[R1] = \text{Reg}[R2] = A\). In other words, all memory operations are to the same address, A, for both processors, but this is not necessarily known at issue time.

Consider the following memory accesses performed by each processor:

<table>
<thead>
<tr>
<th>P1</th>
<th>P2</th>
</tr>
</thead>
<tbody>
<tr>
<td>P1.1: ST 0(R1) ← 1</td>
<td>P2.1: LD Ra ← 0(R1)</td>
</tr>
<tr>
<td>P1.2: ST 0(R2) ← 2</td>
<td>P2.2: LD Rb ← 0(R2)</td>
</tr>
</tbody>
</table>

**Question 1 (17 points)**

For the following questions, answer whether the final set of values \((Ra, Rb) = (2, 1)\) are possible under the corresponding memory consistency model. *Note:* Because caches are kept coherent, all memory consistency models must enforce coherence invariants (write propagation and write serialization).

a) **Sequential Consistency**: stores and loads of individual processors happen in the order specified by the program. (4 points)

b) **Total Store Order (TSO)**: stores can be reordered after later loads. (4 points)

c) **Partial Store Order (PSO)**: stores can be reordered after later loads and stores. (4 points)

d) **Relaxed Memory Order (RMO)**: loads and stores can be reordered after later loads and stores. (5 points)
Question 2 (8 points)

The RMO machine has the following fine-grained barrier instructions:

- **MEMBAR\_RR** guarantees that all reads that precede **MEMBAR\_RR** in program order will be performed before any read that follows the barrier.
- **MEMBAR\_RW** guarantees that all reads that precede **MEMBAR\_RW** in program order will be performed before any write that follows the barrier.
- **MEMBAR\_WR** guarantees that all writes that precede **MEMBAR\_WR** in program order will be performed before any read that follows the barrier.
- **MEMBAR\_WW** guarantees that all writes that precede **MEMBAR\_WW** in program order will be performed before any write that follows the barrier.

Using the **minimum number of memory barrier instructions**, rewrite **P1** and **P2** from Question 1 such that the **RMO machine produces the same outputs as the SC machine for the given code**.

<table>
<thead>
<tr>
<th>P1</th>
<th>P2</th>
</tr>
</thead>
<tbody>
<tr>
<td>P1.1: ST (A) ← 1</td>
<td>P2.1: LD Ra ← (A)</td>
</tr>
<tr>
<td>P1.2: ST (A) ← 2</td>
<td>P2.2: LD Rb ← (A)</td>
</tr>
</tbody>
</table>
Part D: Networks (30 points)

Question 1 (8 points)

Consider the following two topologies: A ring and a 2-dimensional mesh.

Assuming that there are N nodes, calculate the following for each topology. Assume uniform random traffic for average distance calculation. For the average distance of the mesh, you can answer in terms of its asymptotic growth with respect to N (e.g., O(N^3)).

<table>
<thead>
<tr>
<th></th>
<th>Ring</th>
<th>2-D Mesh</th>
</tr>
</thead>
<tbody>
<tr>
<td>Number of links</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bisection Bandwidth</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Diameter</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Average Distance</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
Now consider a 9-node network for the two topologies. Each node is assigned a unique ID as shown in the figure below:

![Ring Topology and 2-Dimensional Mesh Topology](image)

**Question 2 (4 points)**

Consider a *neighbor* traffic pattern instead of the usual uniform random traffic. In this traffic pattern, processor $i$ sends all of its traffic to processor $(i + 1) \mod 9$.

What are the average distances of the two topologies under the neighbor traffic pattern?
Question 3 (4 points)

Can a relabeling of nodes lead to a lower average distance for the mesh topology with the neighbor traffic pattern? If possible, show the relabeling in the figure below. If not, briefly explain your reasoning.

2-Dimensional Mesh Topology
Now consider a 25-processor mesh network, as shown below:

In this system, each processor produces a single value, and all values must be summed up:

\[ \text{sum} \equiv v_0 + v_1 + v_2 + \ldots + v_{24} \]

where \( v_i \) is the value produced by processor \( i \).

To accomplish this, each core sends a packet containing its value \( v_i \) to a single processor, called the reduction node. The reduction node computes the final sum by adding values as they arrive. Ben chooses processor 12 as the reduction node.

Assume the following:

- Each processor \( i \) sends a packet containing its value \( v_i \) at cycle 0.
- Each packet takes 1 cycle to traverse a router. Assume unlimited buffering at each router.
- Each router-to-router and router-to-processor link represents two channels in opposite directions. Channel traversal is instantaneous i.e., no additional cycles are spent in traversing a channel.
- Only one packet can traverse a router-to-router link at a given cycle, whereas an unlimited number of packets can traverse a router-to-processor link at a given cycle. The processor is able to reduce all packets it receives in the same cycle.
- The mesh network routes packets via XY-routing (all horizontal links are traversed before vertical links).
**Question 4 (4 points)**

We define that a router is *congested* when multiple packets in its input ports are wish to be routed to the same output channel in a given cycle. Which router is congested for the most number of cycles during the reduction?

**Question 5 (5 points)**

At what cycle does the last packet arrive at the reduction node?
Ben tries to reduce router congestion by having each router sum up the packets as they arrive. Each router is now augmented with an adder. If multiple packets wish to be routed to the same output channel in the same cycle, the router creates a new packet at the output channel in the next cycle that contains the summed values of those packets.

**Question 6 (5 points)**

Assume each processor $i$ sends a packet containing its value $v_i$ at cycle 0. At what cycle does the last packet arrive at the reduction node with the modified routers?
Scratch Space

Use these extra pages if you run out of space or for your own personal notes. We will not grade these unless you tell us explicitly in the earlier pages.