

# *Cache Organization*

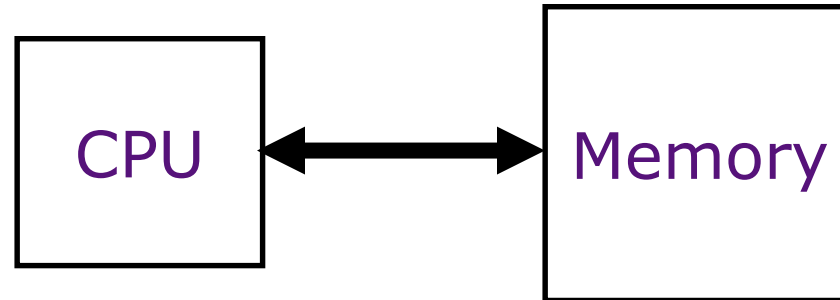
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M.I.T.

<http://www.csg.csail.mit.edu/6.823>

# CPU-Memory Bottleneck

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Performance of high-speed computers is usually limited by memory *bandwidth* & *latency*

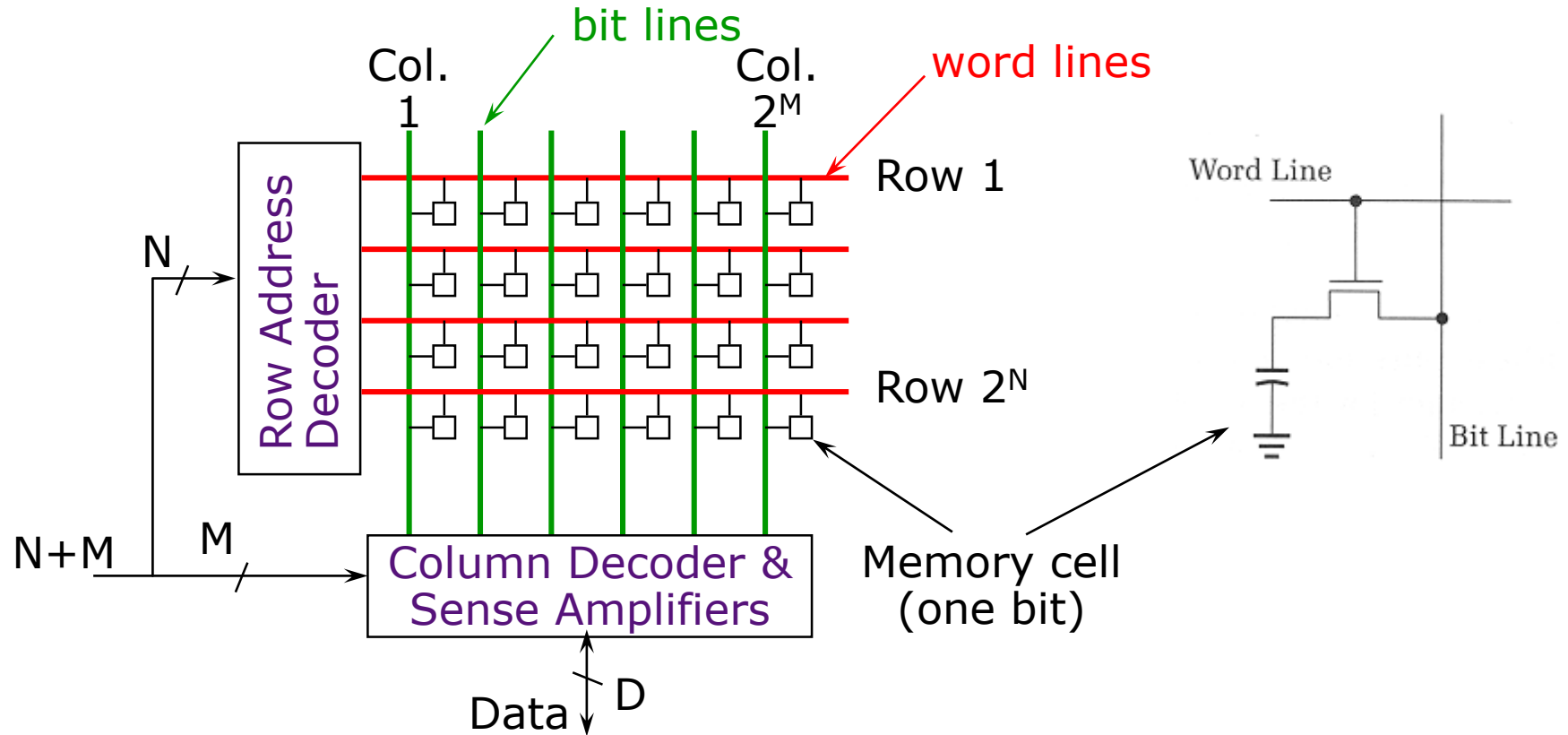
- Latency (time for a single access)  
Memory access time  $\gg$  Processor cycle time
- Bandwidth (number of accesses per unit time)  
if fraction  $m$  of instructions access memory,  
 $\Rightarrow 1+m$  memory references / instruction  
 $\Rightarrow \text{CPI} = 1$  requires  $1+m$  memory refs / cycle

# Memory Technology

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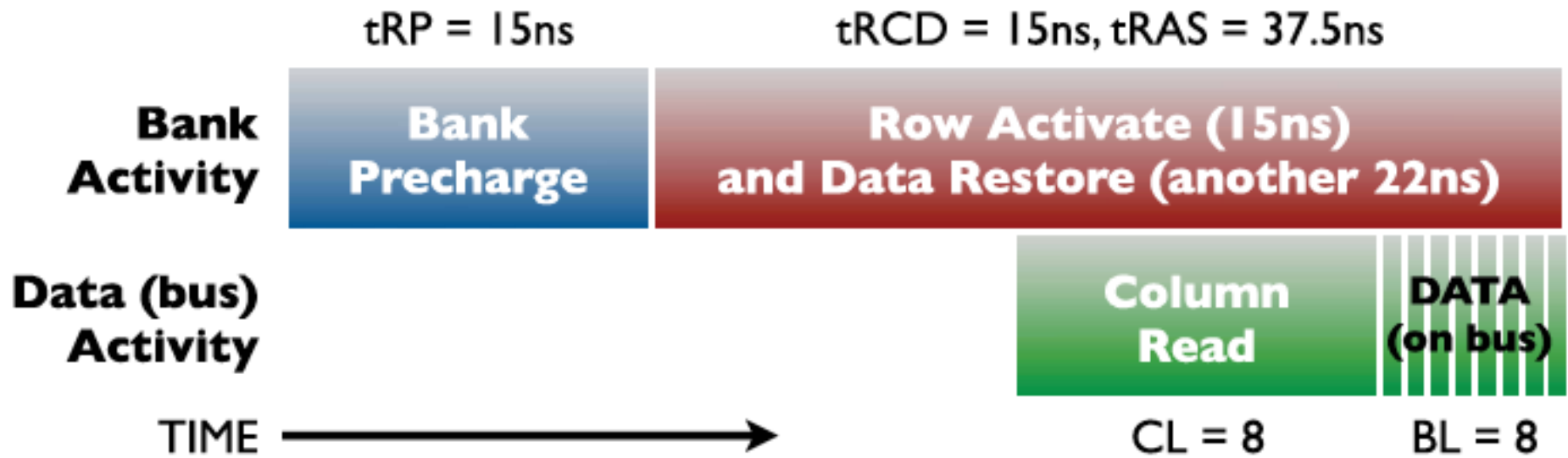
- Early machines used a variety of memory technologies
  - Manchester Mark I used CRT Memory Storage
  - EDVAC used a mercury delay line
- Core memory was first large scale reliable main memory
  - invented by Forrester in late 40s at MIT for Whirlwind project
  - Bits stored as magnetization polarity on small ferrite cores threaded onto 2 dimensional grid of wires
- First commercial DRAM was Intel 1103
  - 1Kbit of storage on single chip
  - charge on a capacitor used to hold value
- Semiconductor memory quickly replaced core in 1970s
  - Intel formed to exploit market for semiconductor memory
- Flash memory
  - Slower, but denser than DRAM. Also non-volatile, but with wearout issues
- Phase change memory (PCM) looking promising for the future
  - Slightly slower, but much denser than DRAM and non-volatile

# DRAM Architecture



- Bits stored in 2-dimensional arrays on chip
- Modern chips have around 4 logical banks on each chip
  - each logical bank physically implemented as many smaller arrays

# DRAM timing

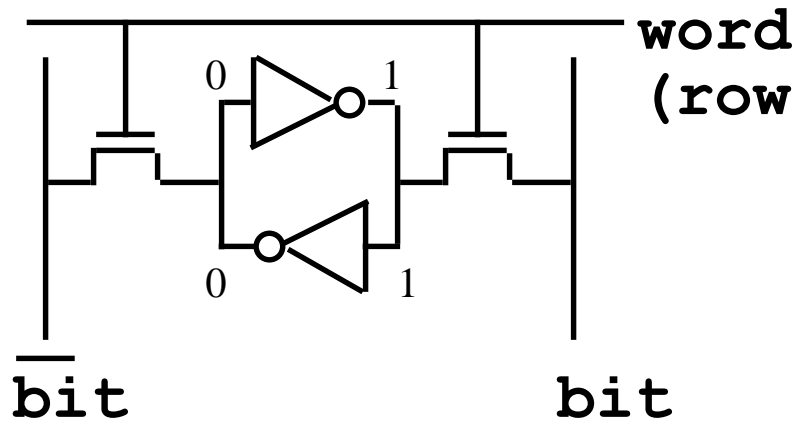


DRAM Spec:

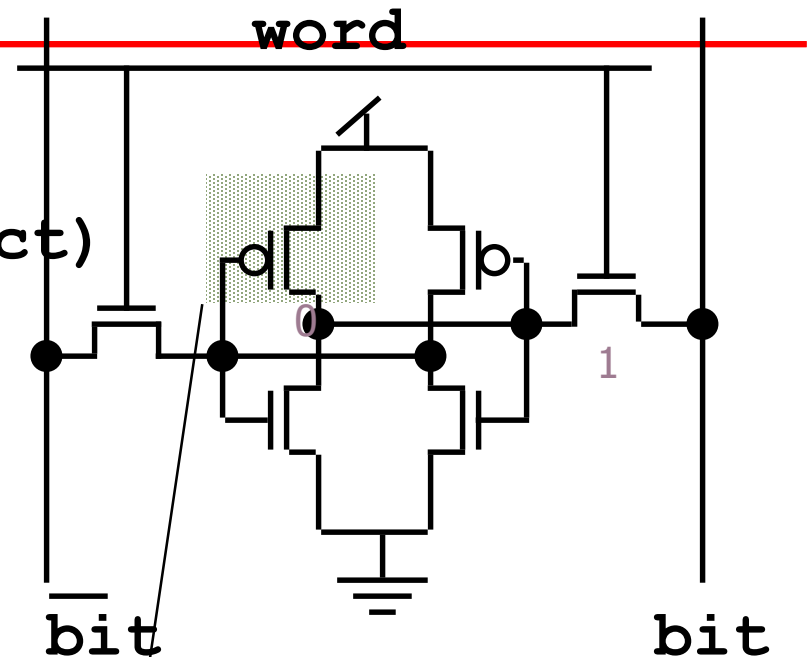
CL, tRCD, tRP, tRAS, e.g., 9-9-9-24

# Basic Static RAM Cell

## 6-Transistor SRAM Cell

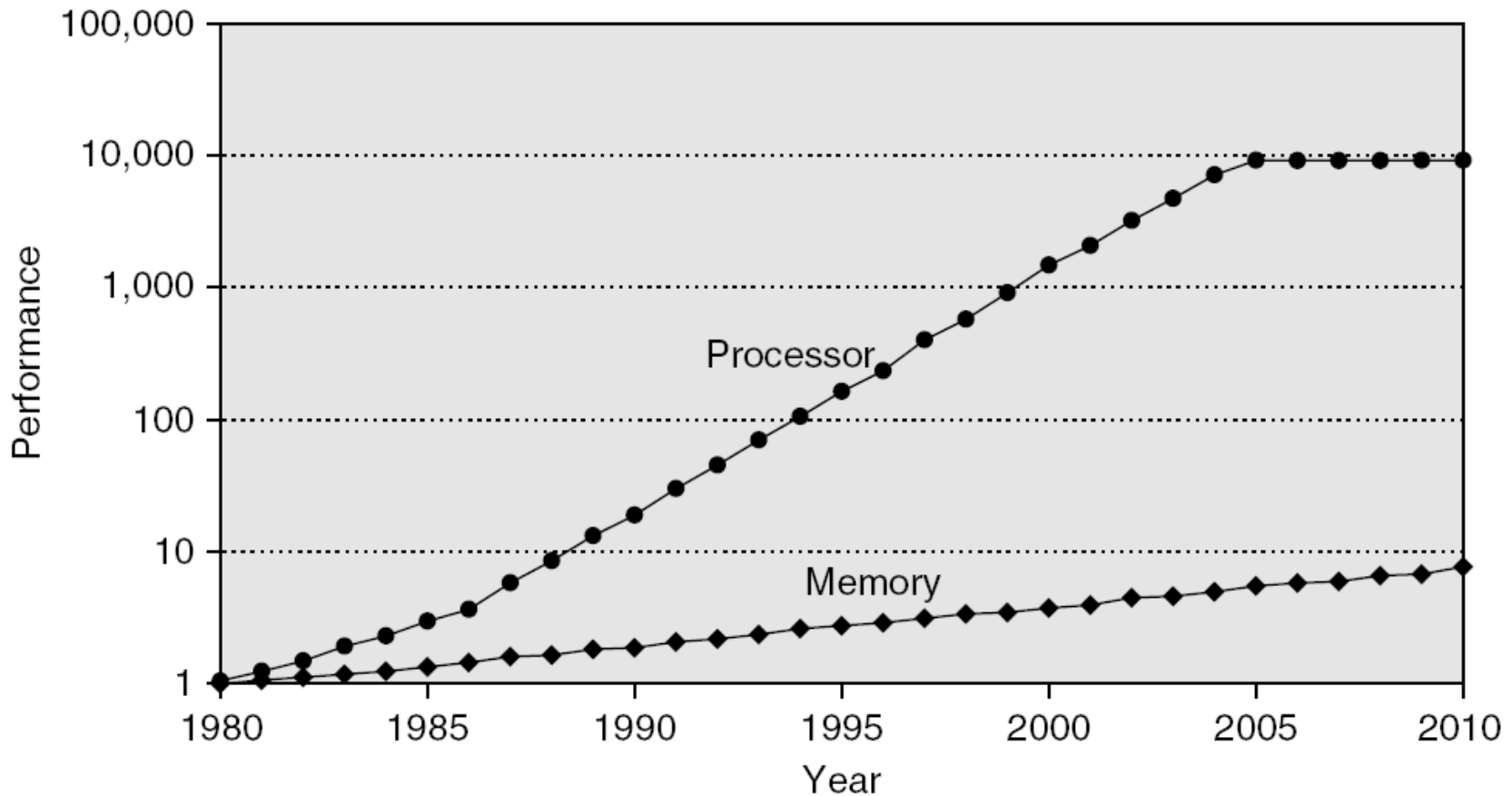


- Write:
  1. Drive bit lines (bit=1, bitbar=0)
  2. Select row
- Read:
  1. Precharge bit and bitbar to Vdd
  2. Select row
  3. Cell pulls one line low
  4. Column sense amp detects difference between bit & bitbar



Often replaced with pullup to save area

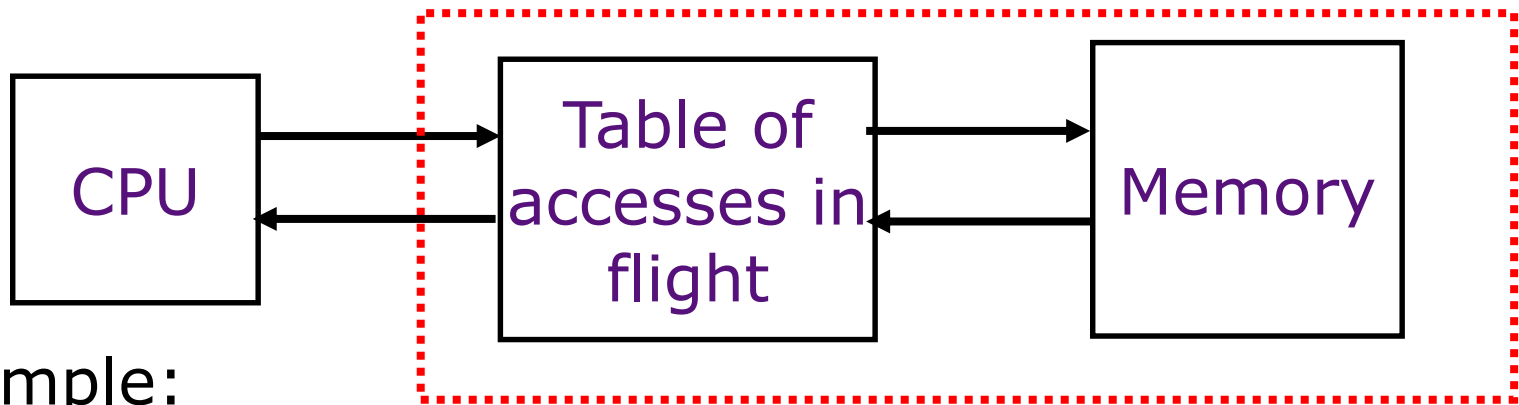
# Processor-DRAM Gap (latency)



Four-issue 2GHz superscalar accessing 100ns DRAM could execute 800 instructions during time for one memory access!

# Little's Law

$$\text{Throughput } (T) = \text{Number in Flight } (N) / \text{Latency } (L)$$



Example:

- Assume infinite bandwidth memory
- 100 cycles / memory reference
- 1 + 0.2 memory references / instruction

⇒ Table size = 1.2 \* 100 = 120 entries

120 independent memory operations in flight!



# Multilevel Memory

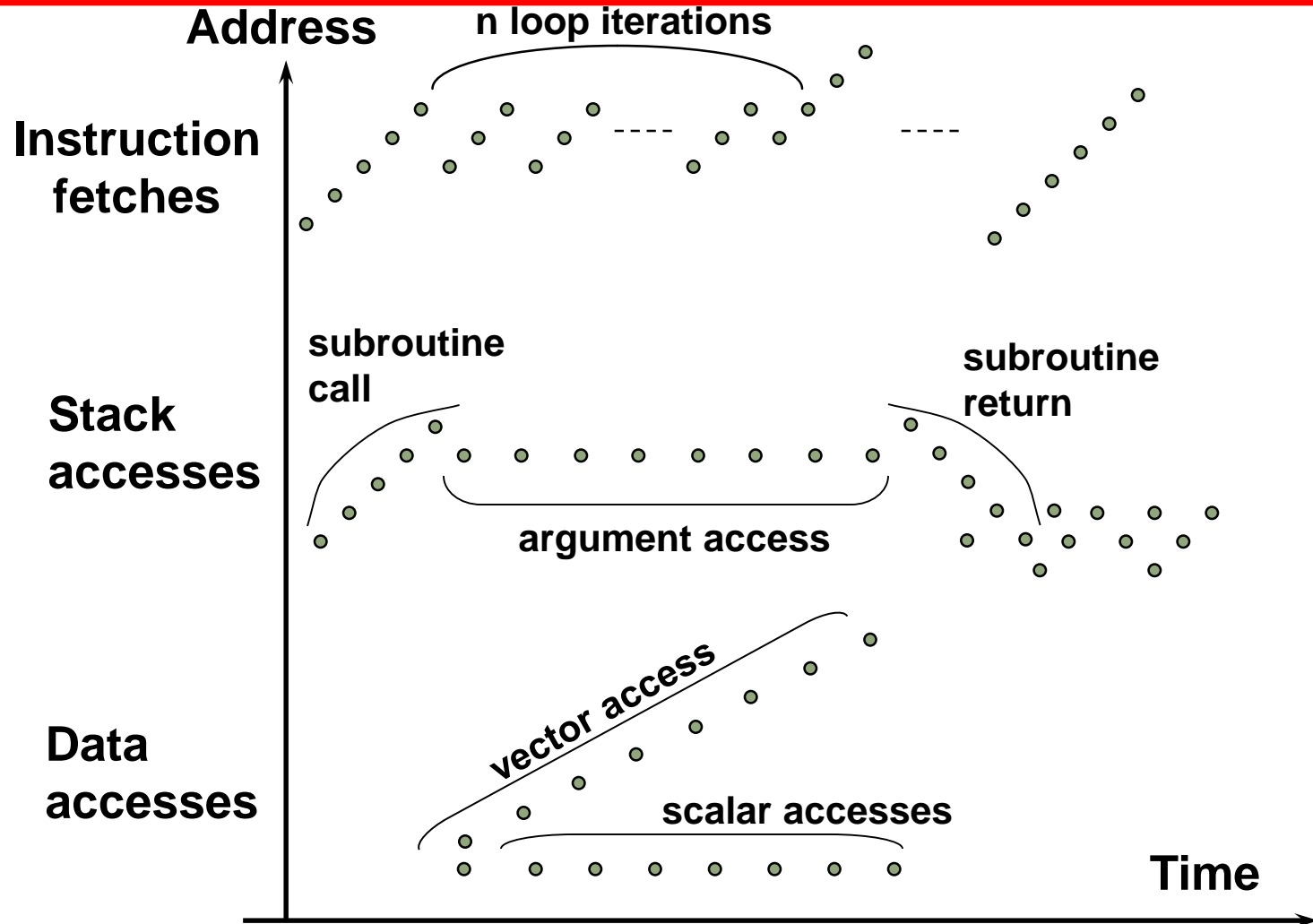
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Strategy: Reduce average latency using small, fast memories called caches.

Caches are a mechanism to reduce memory latency based on the empirical observation that the patterns of memory references made by a processor are often highly predictable:

	<u>PC</u>
...	96
<i>loop: ADD r2, r1, r1</i>	100
<i>SUBI r3, r3, #1</i>	104
<i>BNEZ r3, loop</i>	108
...	112

# Typical Memory Reference Patterns



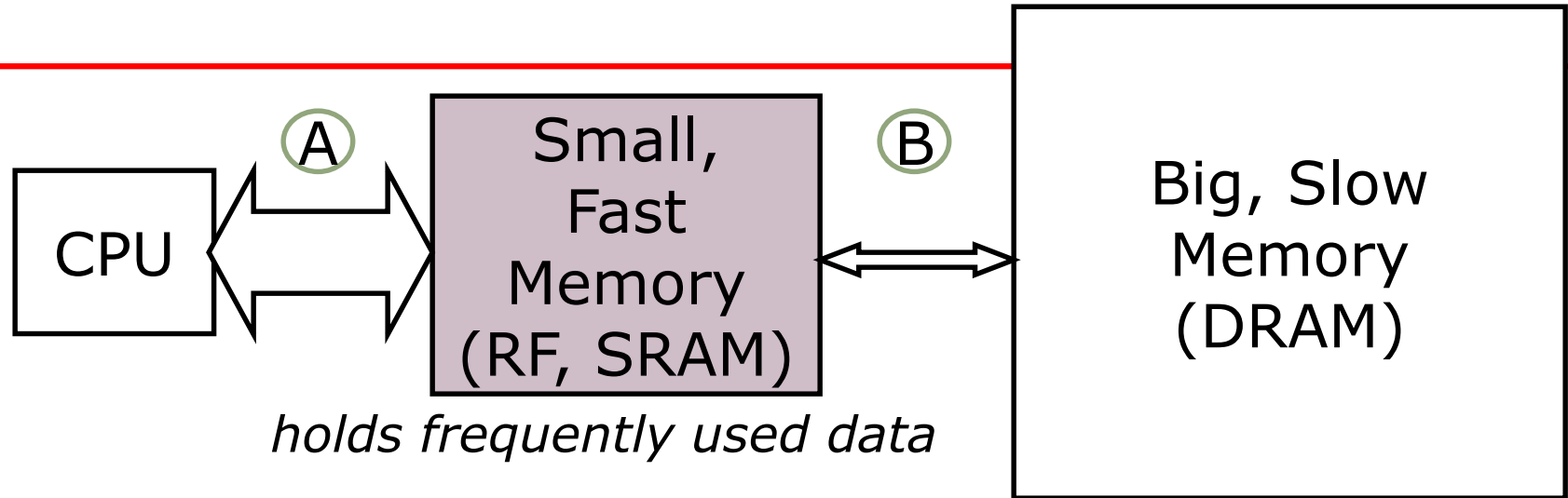
# Common Predictable Patterns

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Two predictable properties of memory references:

- *Temporal Locality*: If a location is referenced it is likely to be referenced again in the near future.
- *Spatial Locality*: If a location is referenced it is likely that locations near it will be referenced in the near future.

# Memory Hierarchy



- *size*: Register  $\ll$  SRAM  $\ll$  DRAM *why?*
- *latency*: Register  $\ll$  SRAM  $\ll$  DRAM *why?*
- *bandwidth*: on-chip  $\gg$  off-chip *why?*

On a data access:

*hit* (data  $\in$  fast memory)  $\Rightarrow$  low latency access

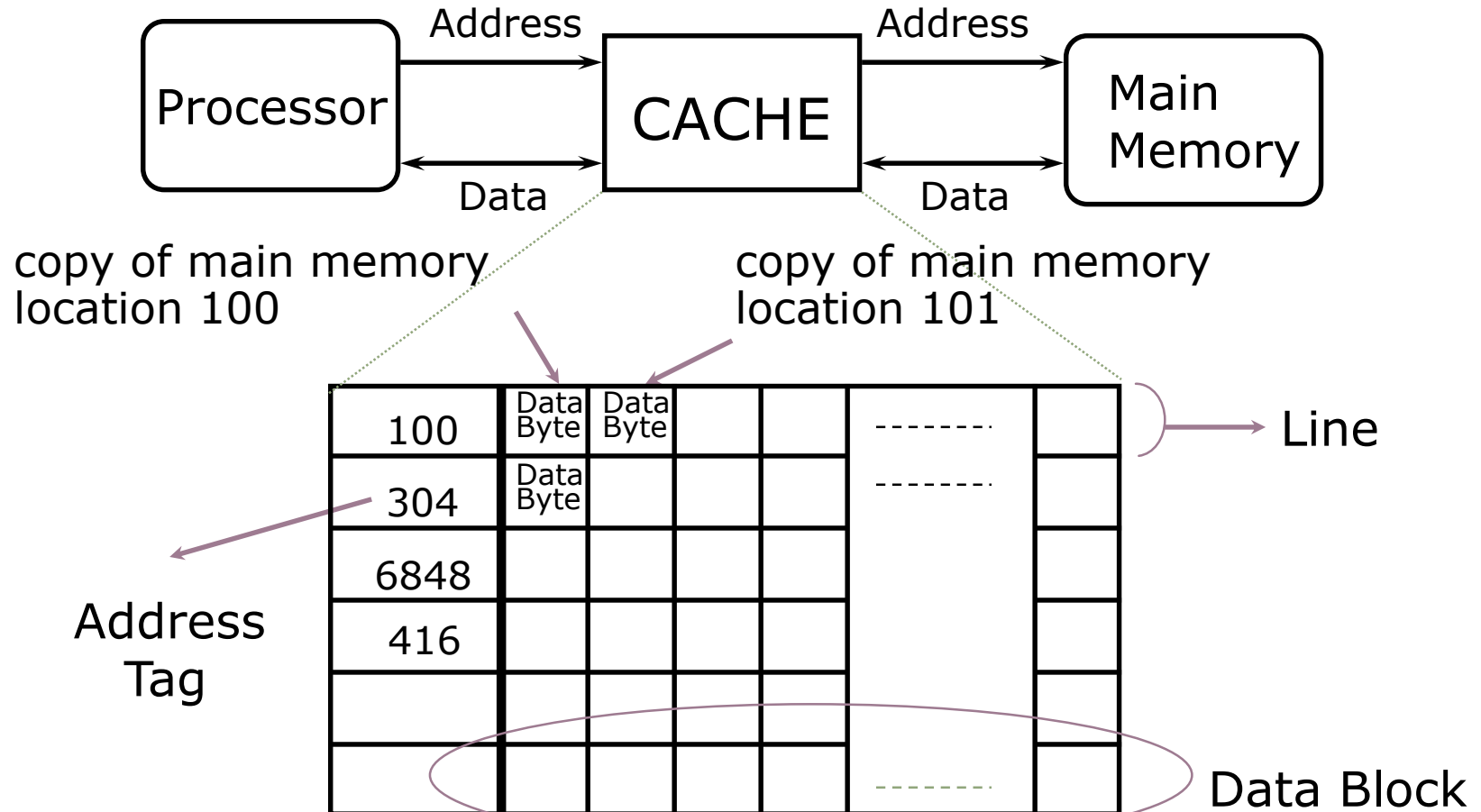
*miss* (data  $\notin$  fast memory)  $\Rightarrow$  long latency access (*DRAM*)

# Management of Memory Hierarchy

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- Small/fast storage, e.g., registers
  - Address usually specified in instruction
  - Generally implemented directly as a register file
    - but hardware might do things behind software's back, e.g., stack management, register renaming
- Large/slower storage, e.g., memory
  - Address usually computed from values in register
  - Generally implemented as a cache hierarchy
    - hardware decides what is kept in fast memory
    - but software may provide "hints", e.g., don't cache or prefetch

# Inside a Cache



How many bits are needed in tag?

Enough to uniquely identify block

# Cache Algorithm (Read)

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Look at Processor Address, search cache tags to find match. Then either

Found in cache  
a.k.a. HIT

Not in cache  
a.k.a. MISS

Return copy  
of data from  
cache

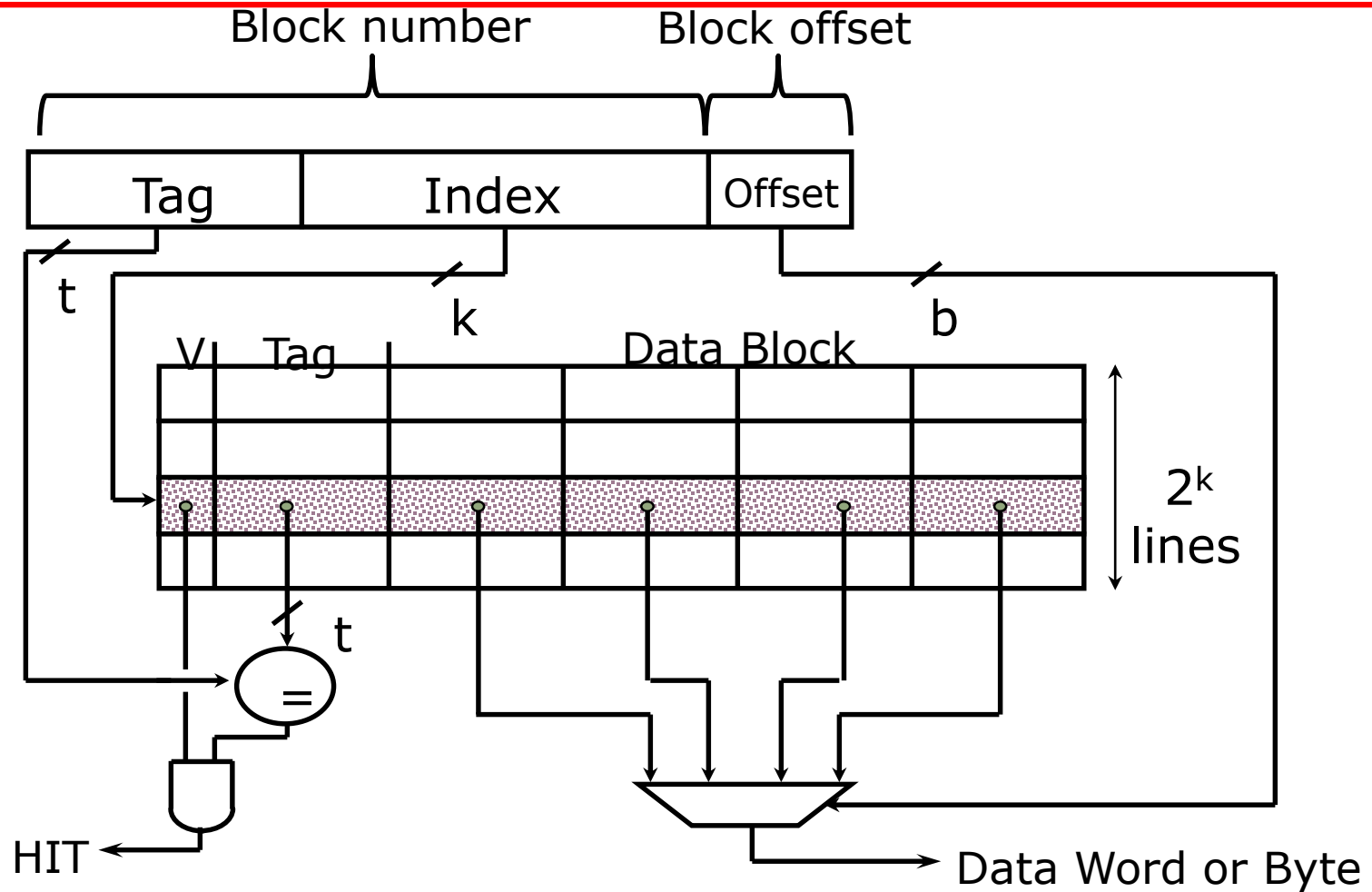
Read block of data from  
Main Memory

Wait ...

Return data to processor  
and update cache

Q: Which line do we replace?

# Direct-Mapped Cache



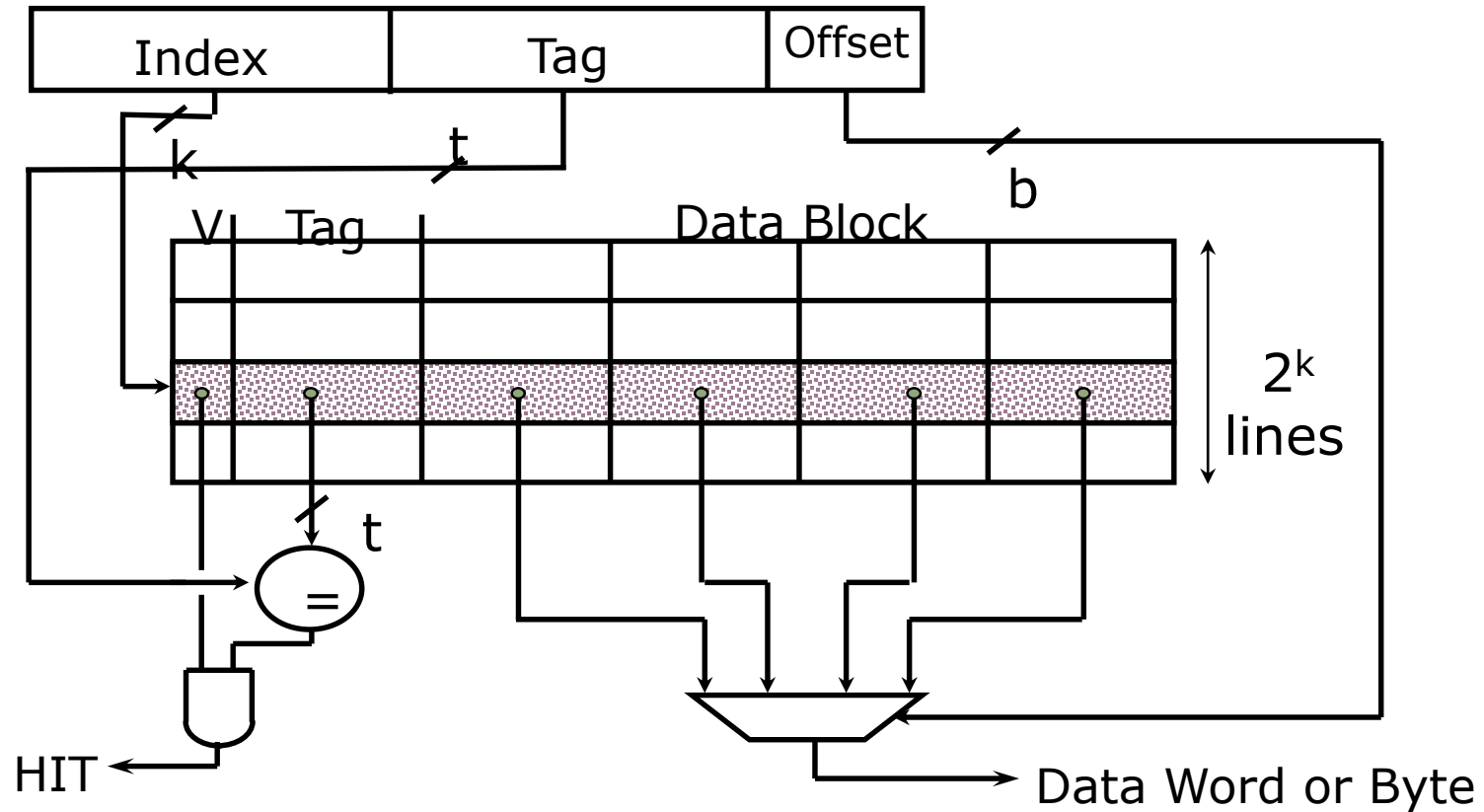
What is a bad reference pattern?

**Strided at size of cache**



# Direct Map Address Selection

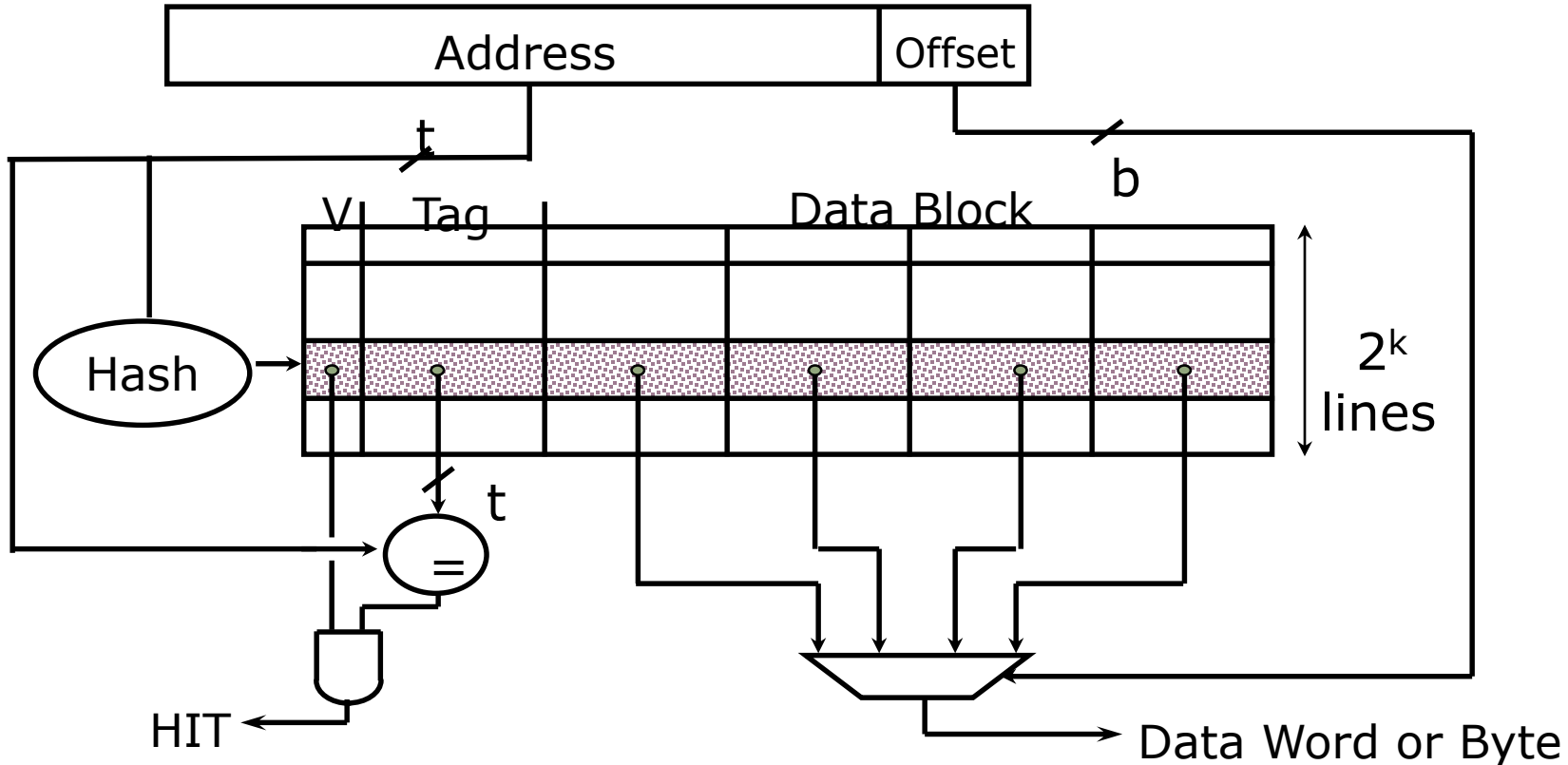
*higher-order vs. lower-order address bits*



Why might this be undesirable?

**Spatially local blocks conflict**

# Hashed Address Selection



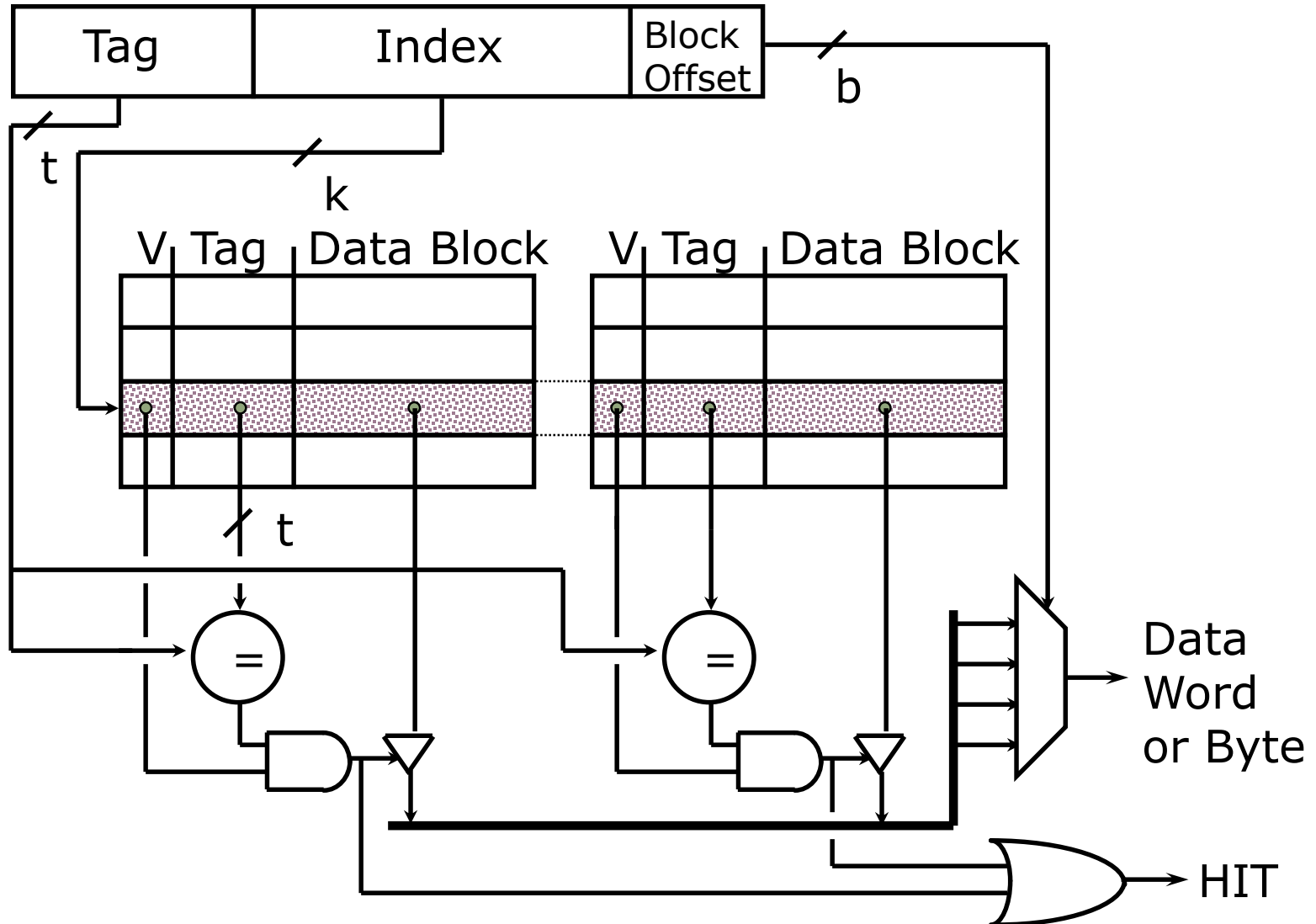
What are the tradeoffs of hashing?

Good: Regular strides don't conflict

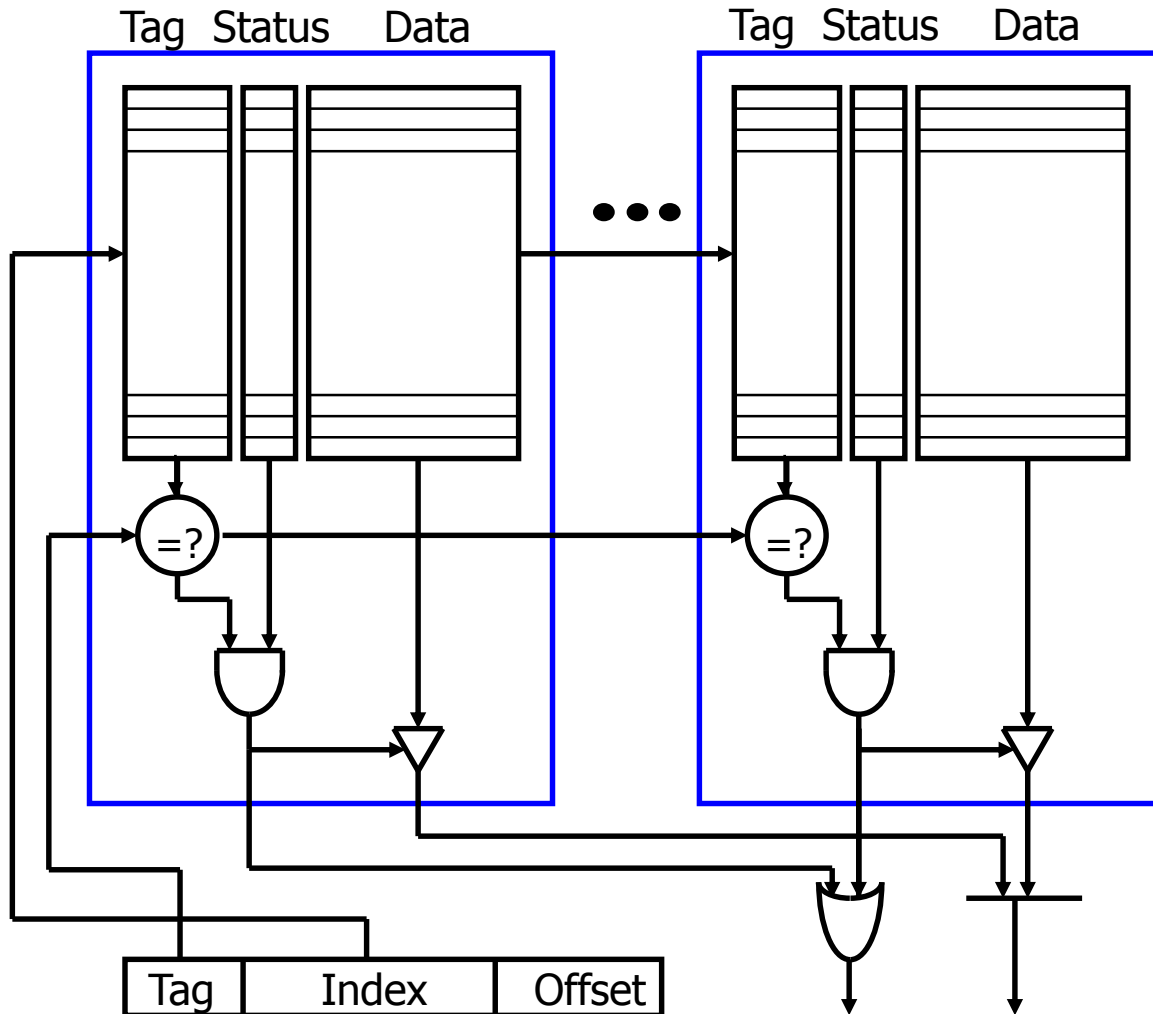
Bad: Hash adds latency

Tag is larger

# 2-Way Set-Associative Cache



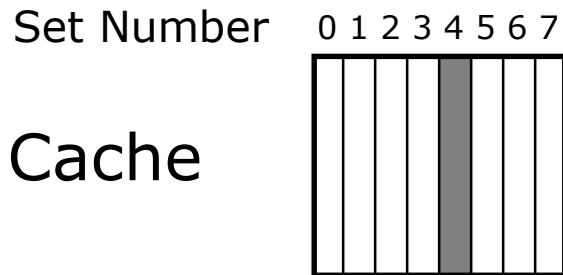
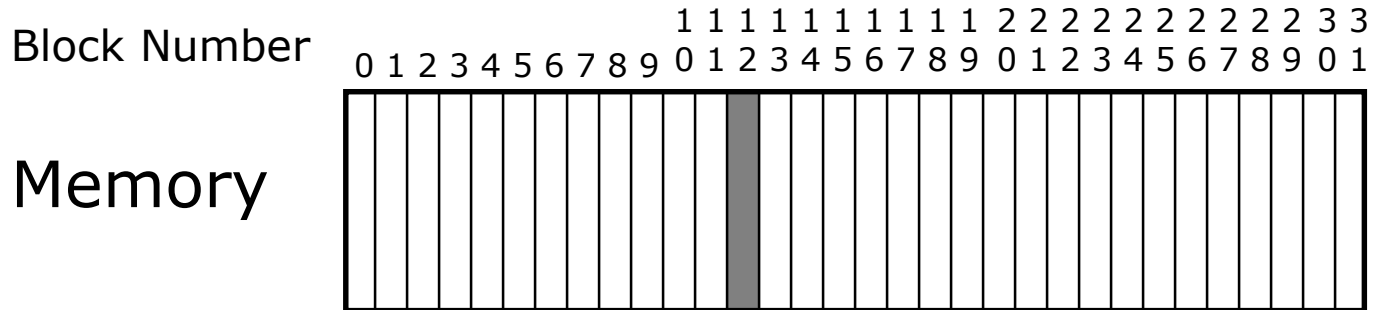
# Set-Associative RAM-Tag Cache



Not energy-efficient  
 – A tag and data word is read from every way

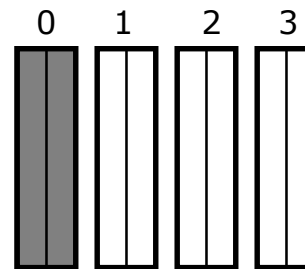
Two-phase approach  
 – First read tags, then just read data from selected way  
 – More energy-efficient  
 – Doubles latency in L1  
 – OK, for L2 and above, why?

# Placement Policy



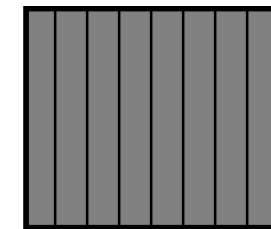
Direct  
Mapped  
only into  
block 4

$(12 \bmod 8)$



(2-way) Set  
Associative  
anywhere in  
set 0

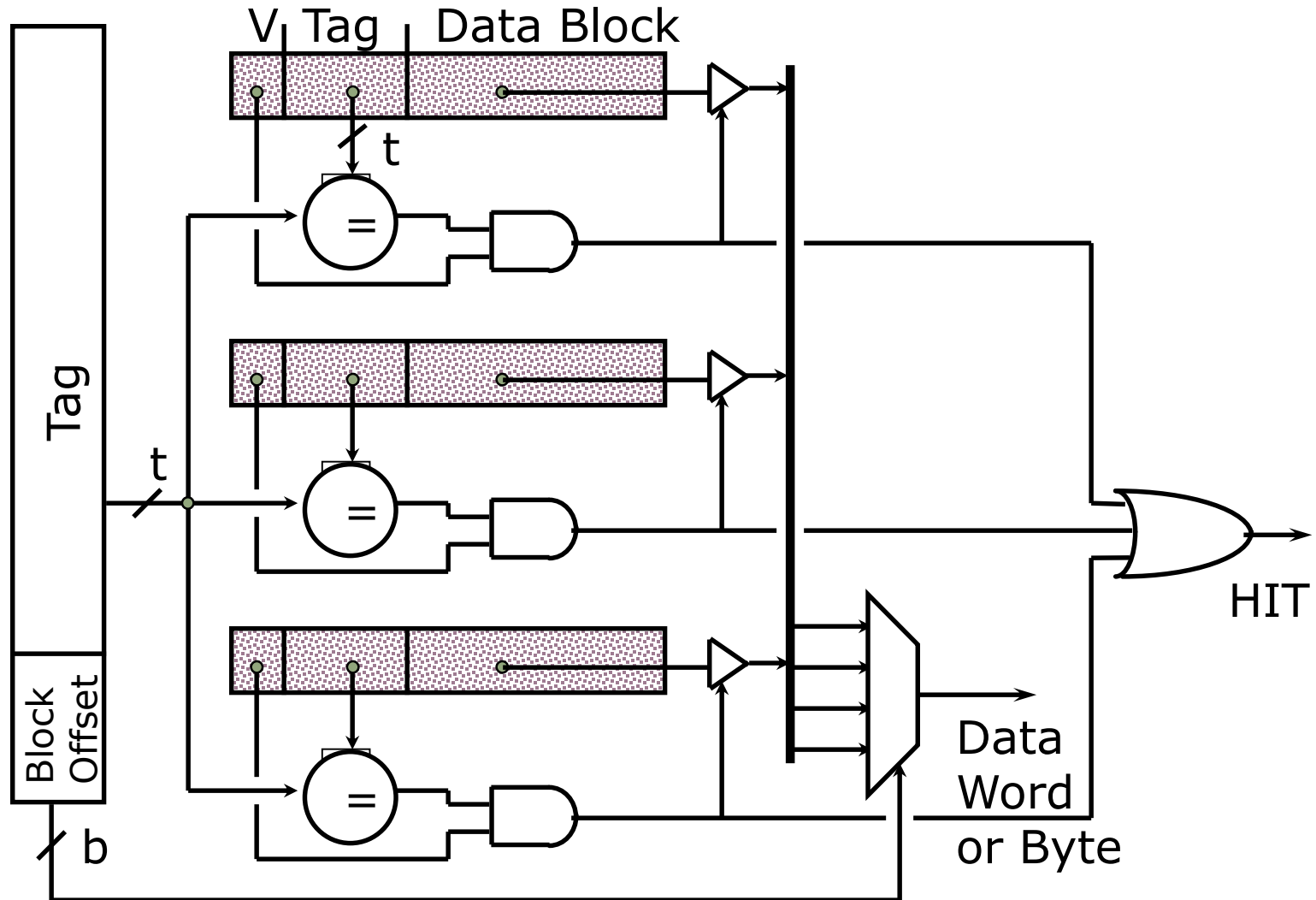
$(12 \bmod 4)$



Fully  
Associative  
Anywhere

block 12  
can be placed

# Fully Associative Cache



# Improving Cache Performance

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Average memory access time =  
Hit time + Miss rate x Miss penalty

To improve performance:

- reduce the hit time
- reduce the miss rate (e.g., larger, better policy)
- reduce the miss penalty (e.g., L2 cache)

*What is the simplest design strategy?*

*Biggest cache that doesn't increase hit time past 1-2 cycles  
(approx 8-32KB in modern technology)*

*[design issues more complex with out-of-order superscalar processors]*

# Causes for Cache Misses

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- *Compulsory:*  
first-reference to a block *a.k.a.* cold start misses
  - misses that would occur even with infinite cache
- *Capacity:*  
cache is too small to hold all data the program needs
  - misses that would occur even under perfect placement & replacement policy
- *Conflict:*  
misses from collisions due to block-placement strategy
  - misses that would not occur with full associativity



# Effect of Cache Parameters on Performance

	Larger capacity cache	Higher associativity cache	Larger block size cache *
Compulsory misses	=	=	↓
Capacity misses	↓	=	↓
Conflict misses	↓	↓	?
Hit latency	↑	↑	=
Miss latency	=	=	↑ ↓

\* Assume substantial spatial locality

# Block-level Optimizations

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- Tags are too large, i.e., too much overhead
  - Simple solution: Larger blocks, but miss penalty could be large.
- Sub-block placement (aka sector cache)
  - A valid bit added to units smaller than the full block, called sub-blocks
  - Only read a sub-block on a miss
  - *If a tag matches, is the word in the cache?*

<b>100</b>
<b>300</b>
<b>204</b>

<b>1</b>		<b>1</b>		<b>1</b>		<b>1</b>	
<b>1</b>		<b>1</b>		<b>0</b>		<b>0</b>	
<b>0</b>		<b>1</b>		<b>0</b>		<b>1</b>	

# Replacement Policy

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Which block from a set should be evicted?

- Random
- Least Recently Used (LRU)
  - LRU cache state must be updated on every access
  - true implementation only feasible for small sets (2-way)
  - pseudo-LRU binary tree was often used for 4-8 way
- First In, First Out (FIFO) a.k.a. Round-Robin
  - used in highly associative caches
- Not Least Recently Used (NLRU)
  - FIFO with exception for most recently used block or blocks
- One-bit LRU
  - Each way represented by a bit. Set on use, replace first unused.

# Re-reference interval prediction



Time



References:

H	F	E	F	B	C	A	F
	0	1	2	3	4	5	6

tag	C	A	F	B
-----	---	---	---	---

RRI	4	5	0	3
-----	---	---	---	---

Best candidate?

A

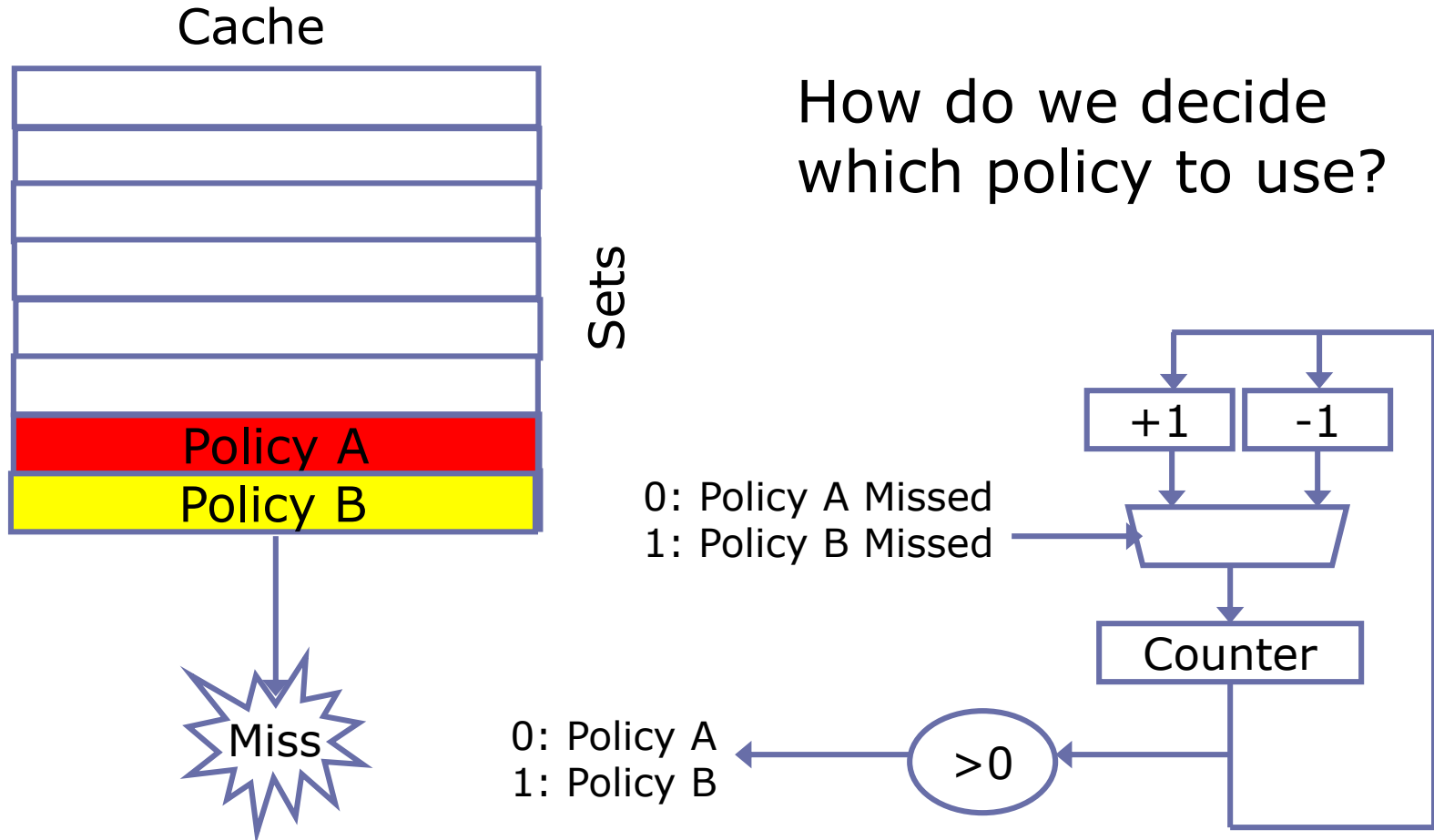
tag	C	A	F	B
-----	---	---	---	---

RRIP	2	3	0	1
------	---	---	---	---

RRIP-bit LRU

# Multiple replacement policies

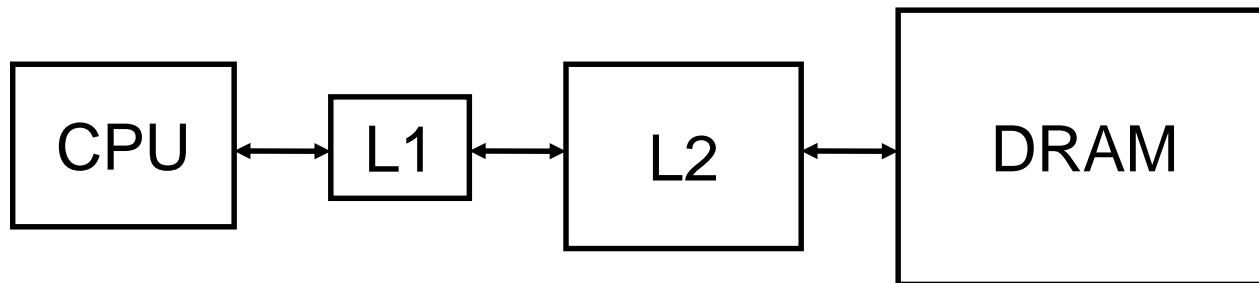
Use the best replacement policy for a program



# Multilevel Caches

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- A memory cannot be large and fast
- Add level of cache to reduce miss penalty
  - Each level can have longer latency than level above
  - So, increase sizes of cache at each level



Metrics:

Local miss rate = misses in cache / accesses to cache

Global miss rate = misses in cache / CPU memory accesses

Misses per instruction = misses in cache / number of instructions

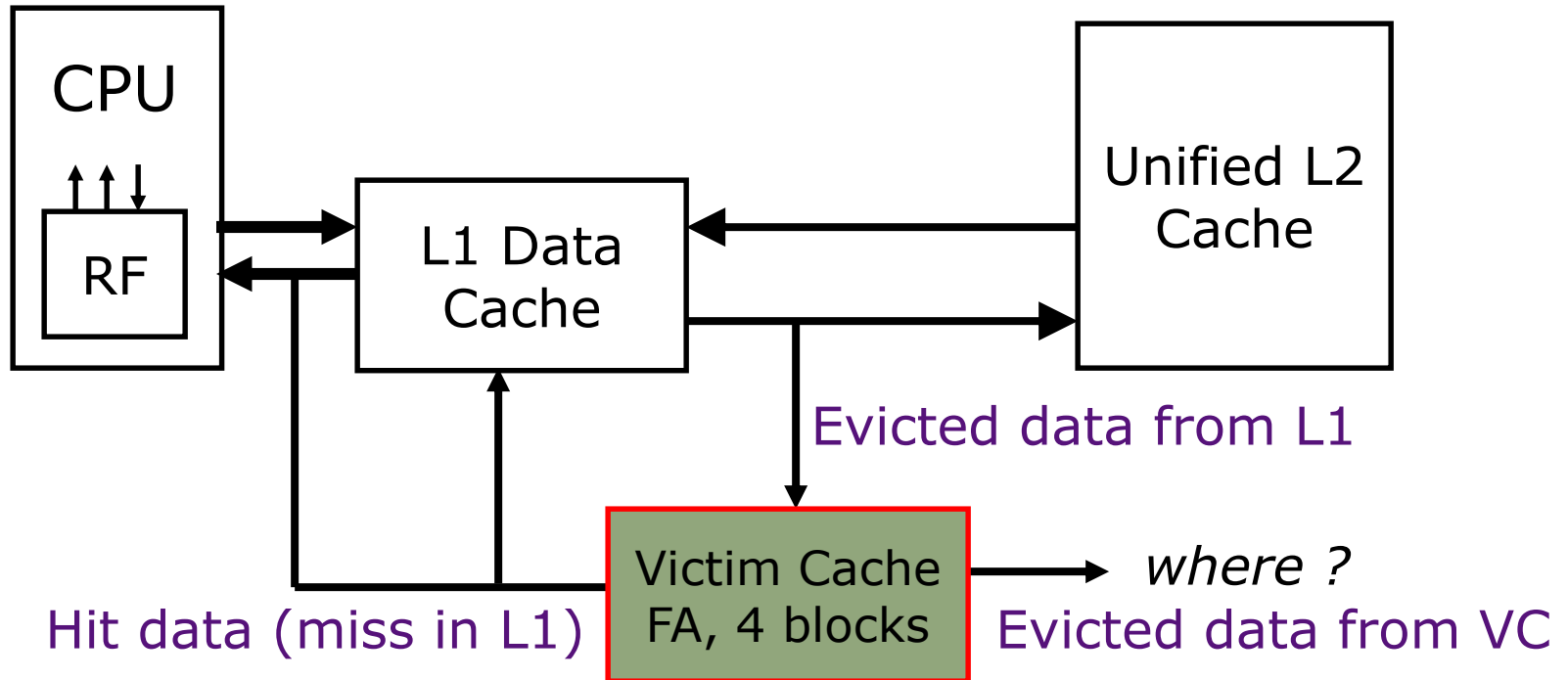
# Inclusion Policy

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- Inclusive multilevel cache:
  - Inner cache holds copies of data in outer cache
  - External access need only check outer cache
  - Most common case
- *Exclusive* multilevel caches:
  - Inner cache may hold data not in outer cache
  - Swap lines between inner/outer caches on miss
  - Used in AMD Athlon with 64KB primary and 256KB secondary cache

Why choose one type or the other?

# Victim Caches (HP 7200)



Victim cache is a small associative back up cache, added to a direct mapped cache, which holds recently evicted lines

- First look up in direct mapped cache
- If miss, look in victim cache
- If hit in victim cache, swap hit line with line now evicted from L1
- If miss in victim cache, L1 victim -> VC, VC victim->?

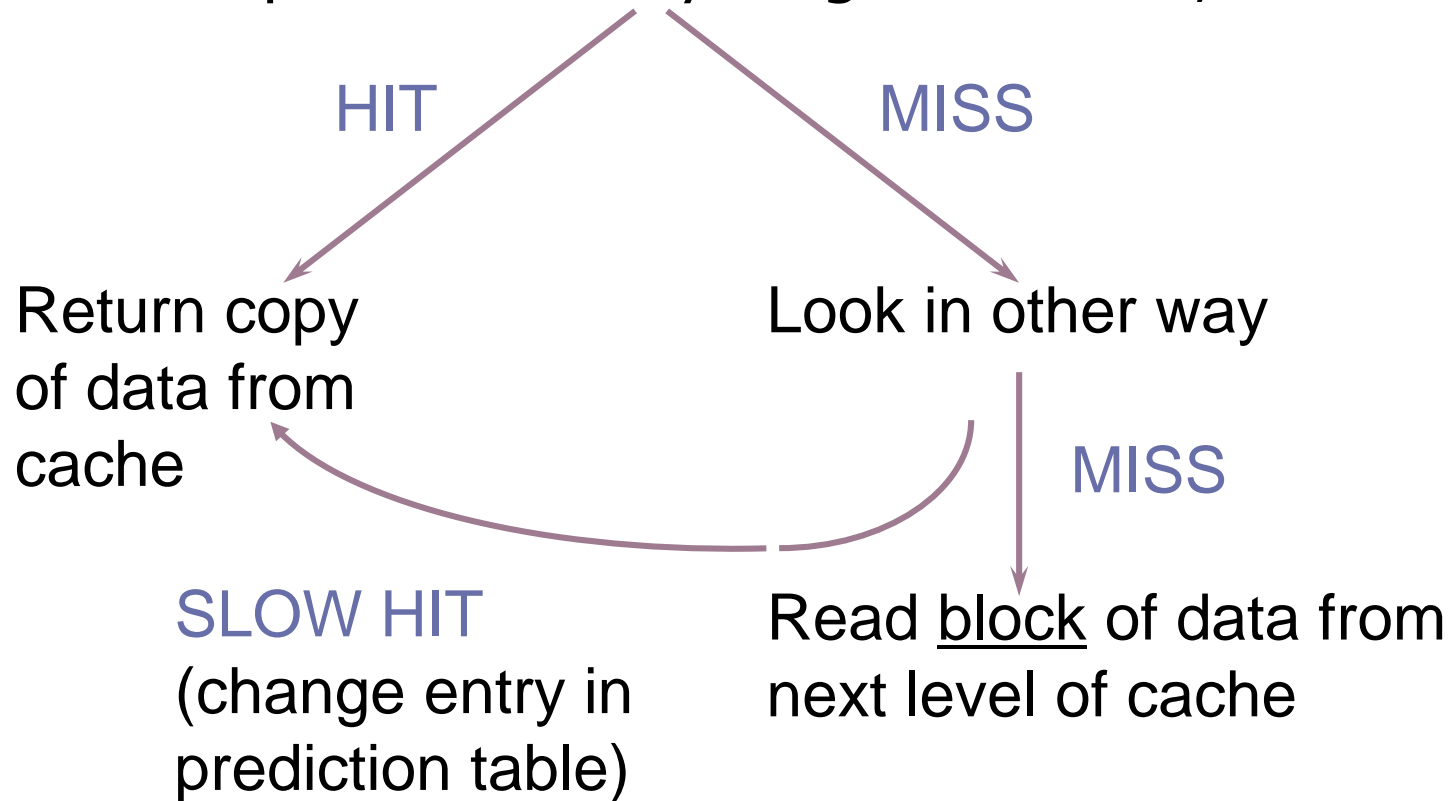
Fast hit time of direct mapped but with reduced conflict misses



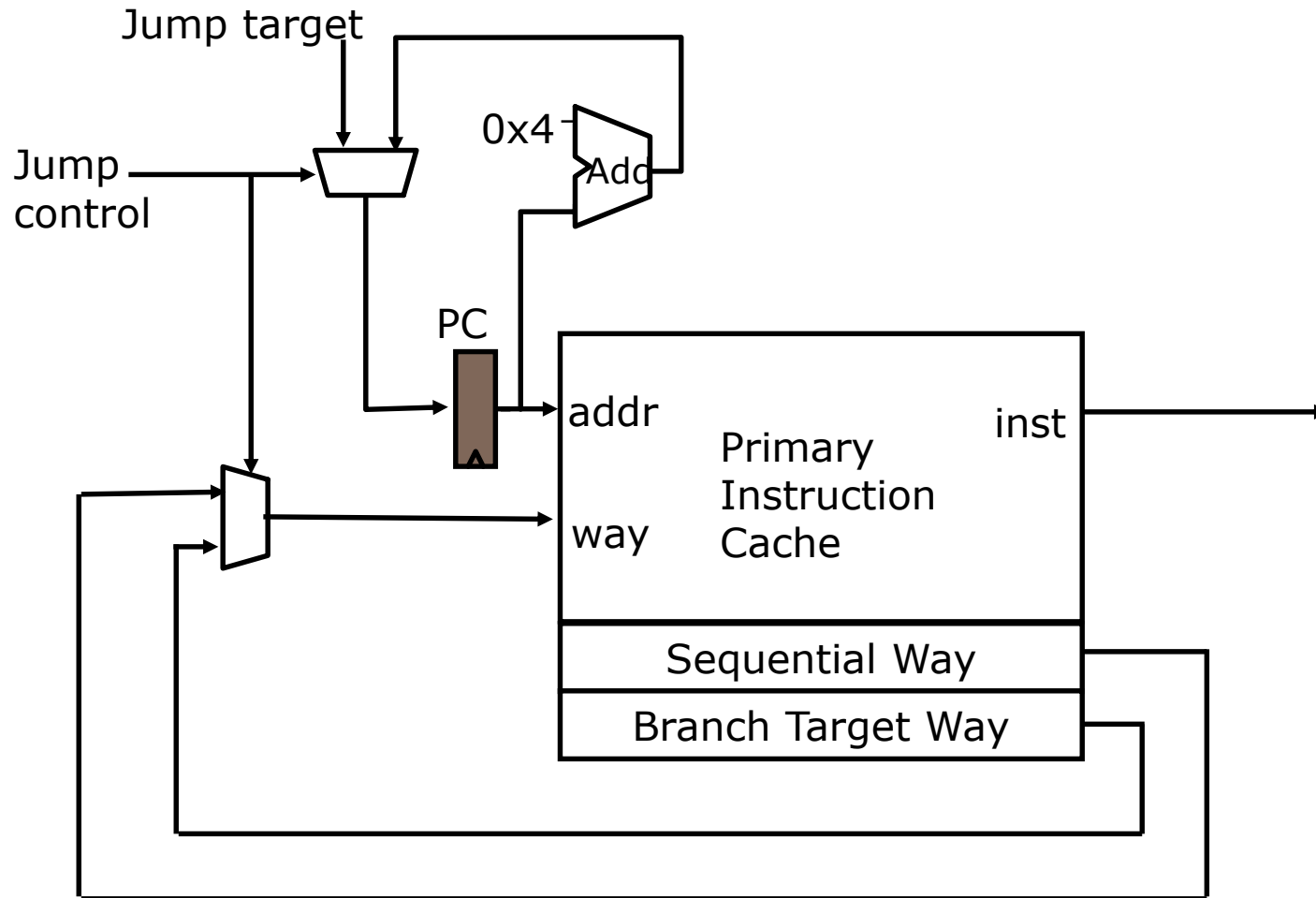
# Way Predicting Caches (MIPS R10000 L2 cache)

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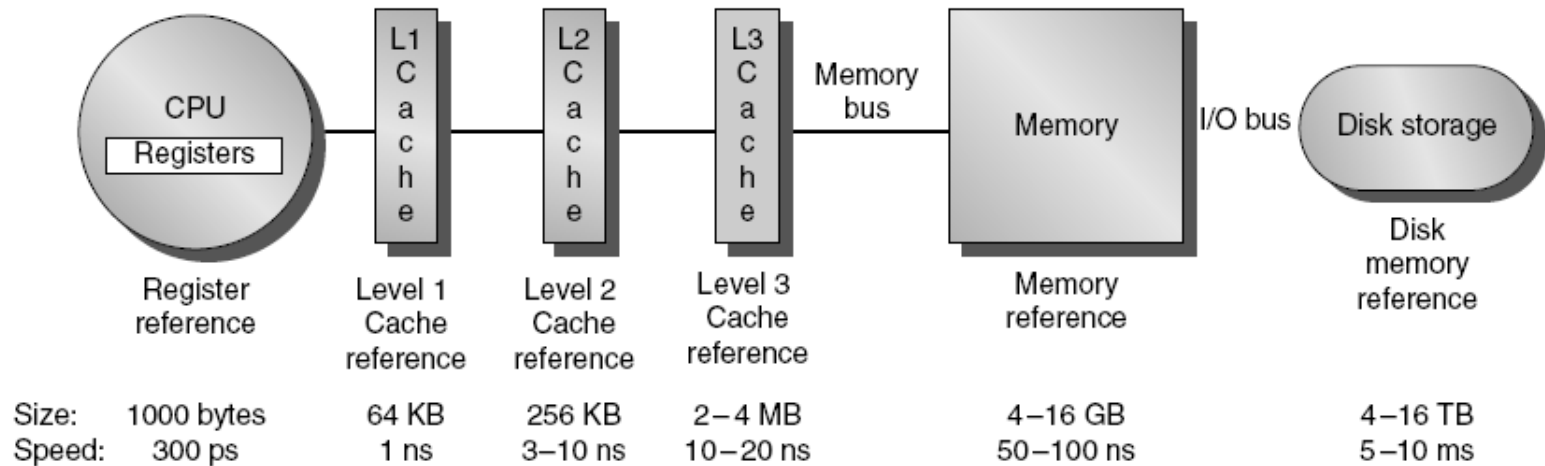
- Use processor address to index into way prediction table
- Look in predicted way at given index, then:



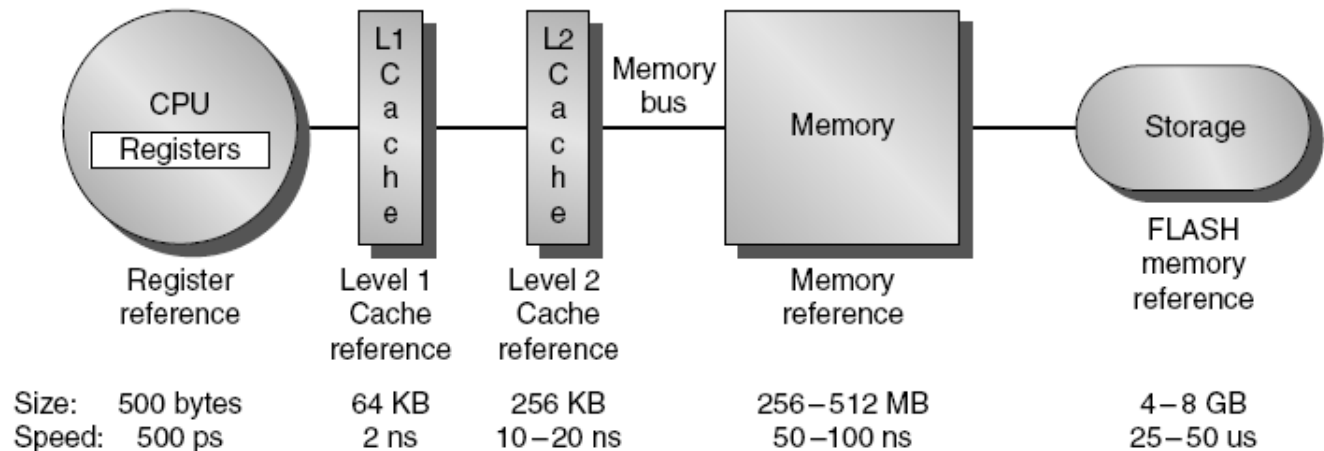
# Way Predicting Instruction Cache (Alpha 21264-like)



# Typical memory hierarchies



(a) Memory hierarchy for server



(b) Memory hierarchy for a personal mobile device

*Thank you !*

*Next lecture – virtual memory*