

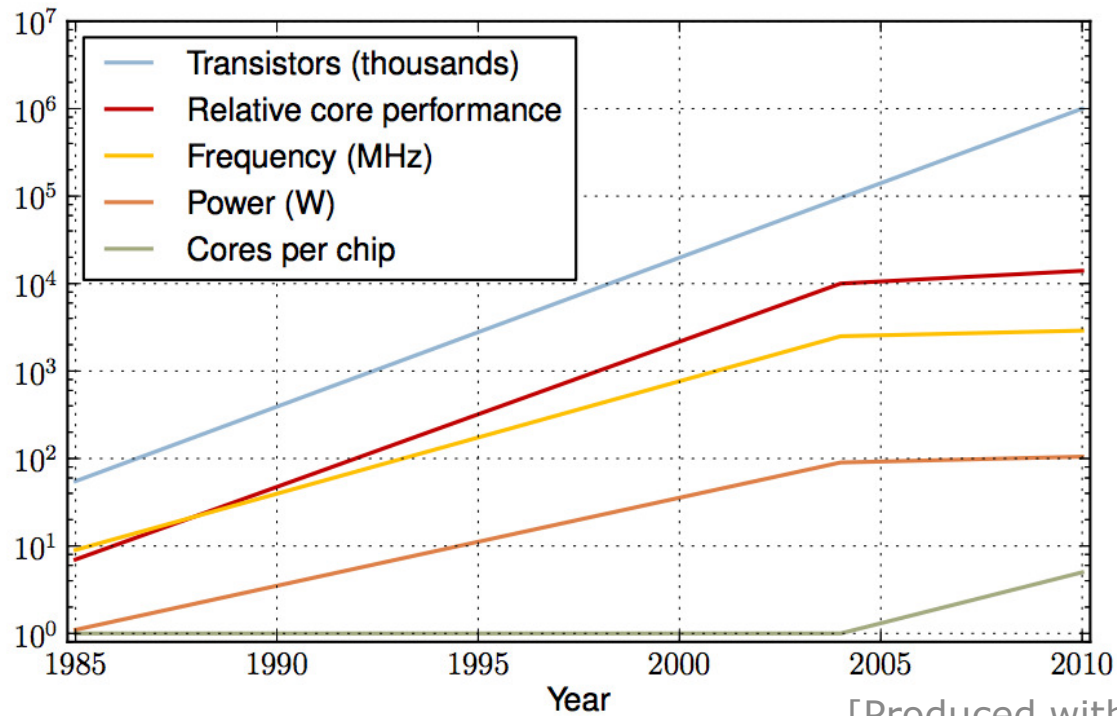
Cache Coherence

Daniel Sanchez

Computer Science and Artificial Intelligence Laboratory
M.I.T.

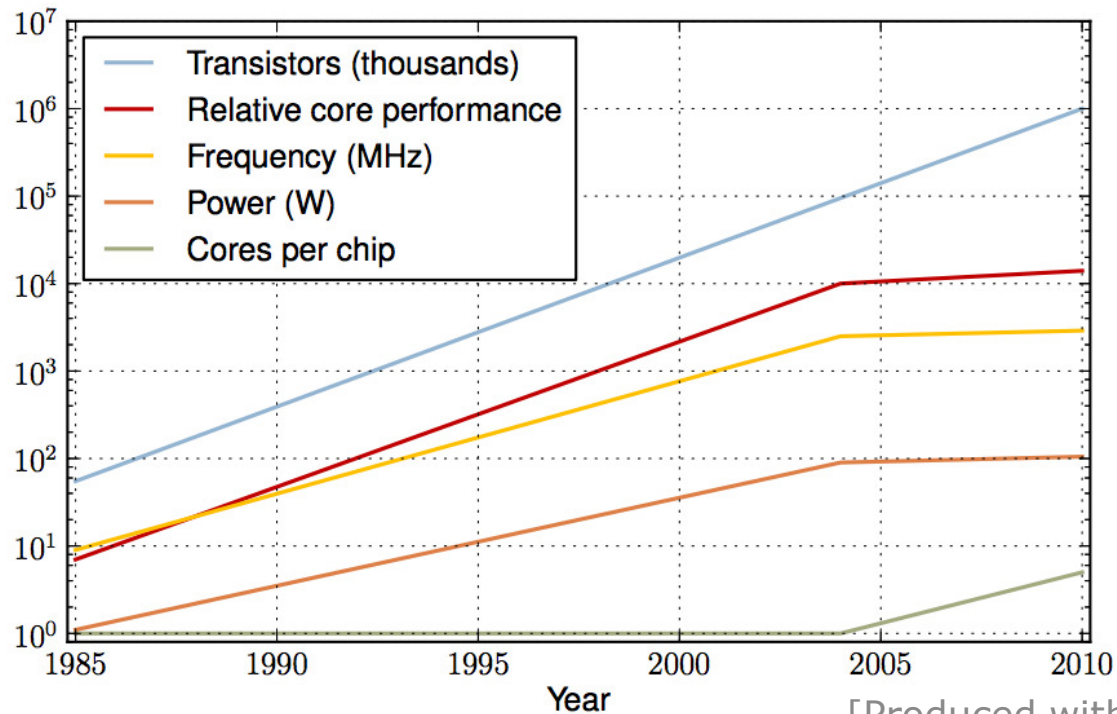
<http://www.csg.csail.mit.edu/6.823>

The Shift to Multicore



[Produced with CPADB,
cpadb.stanford.edu]

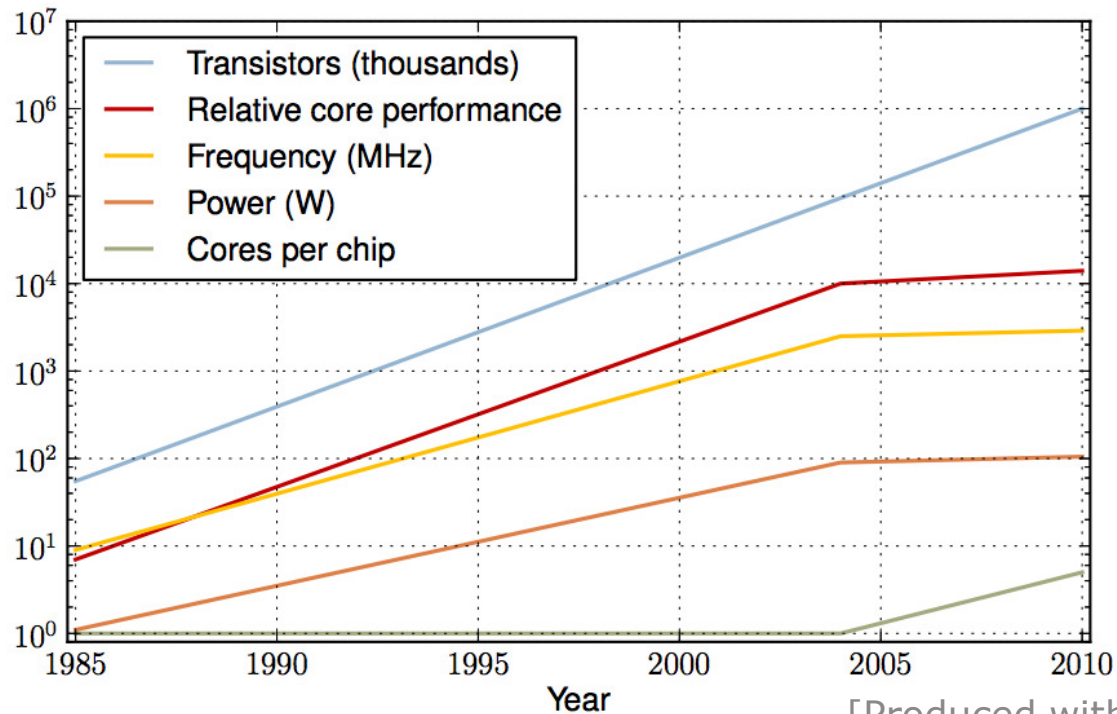
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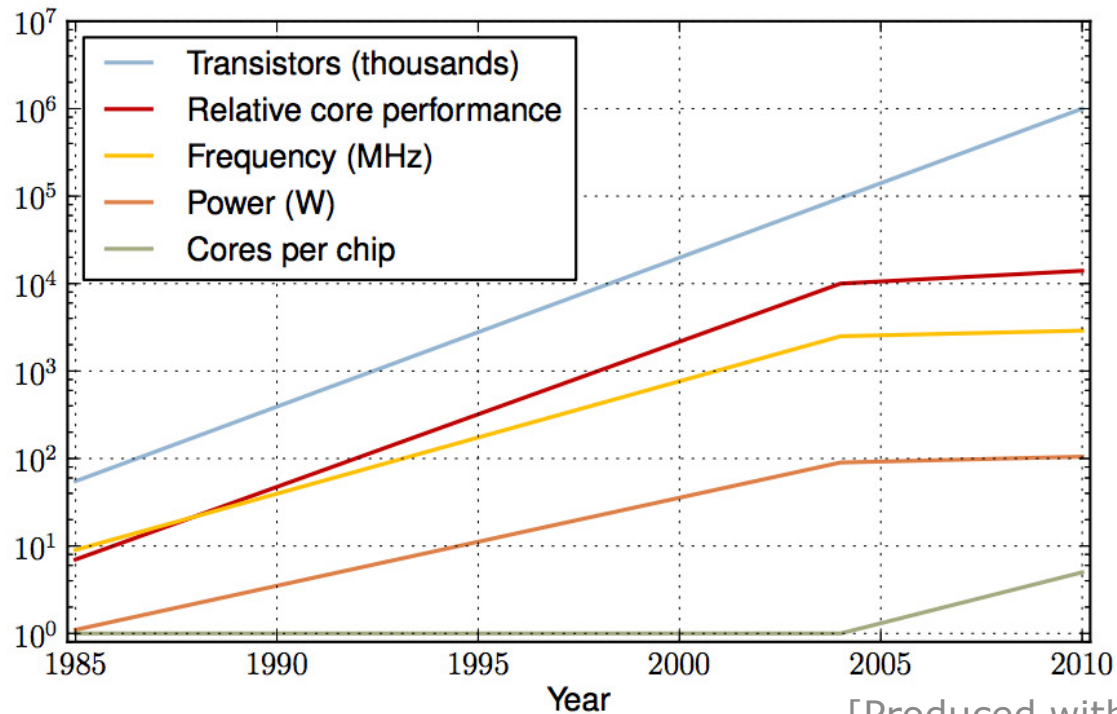
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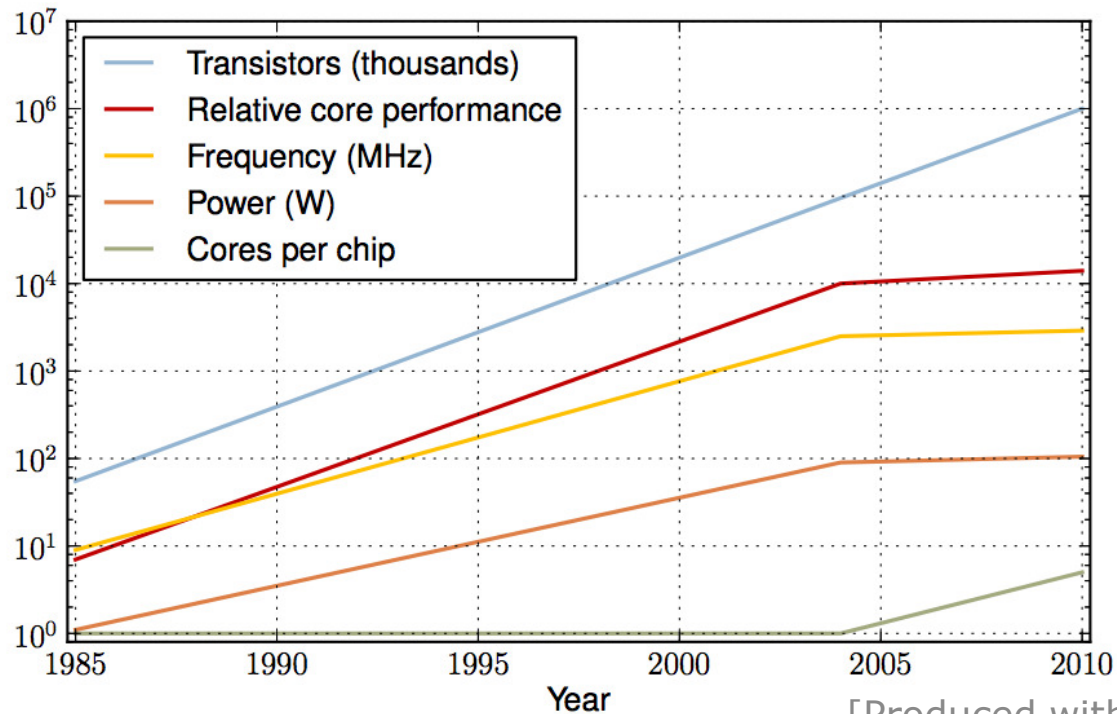
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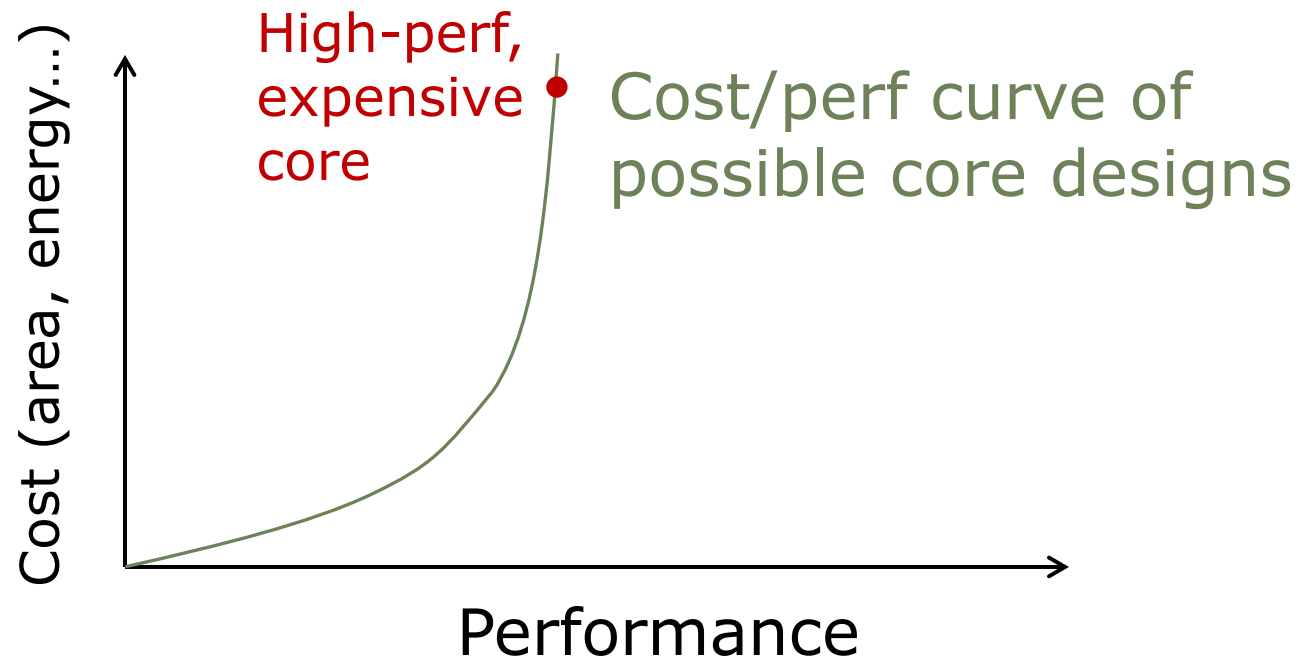
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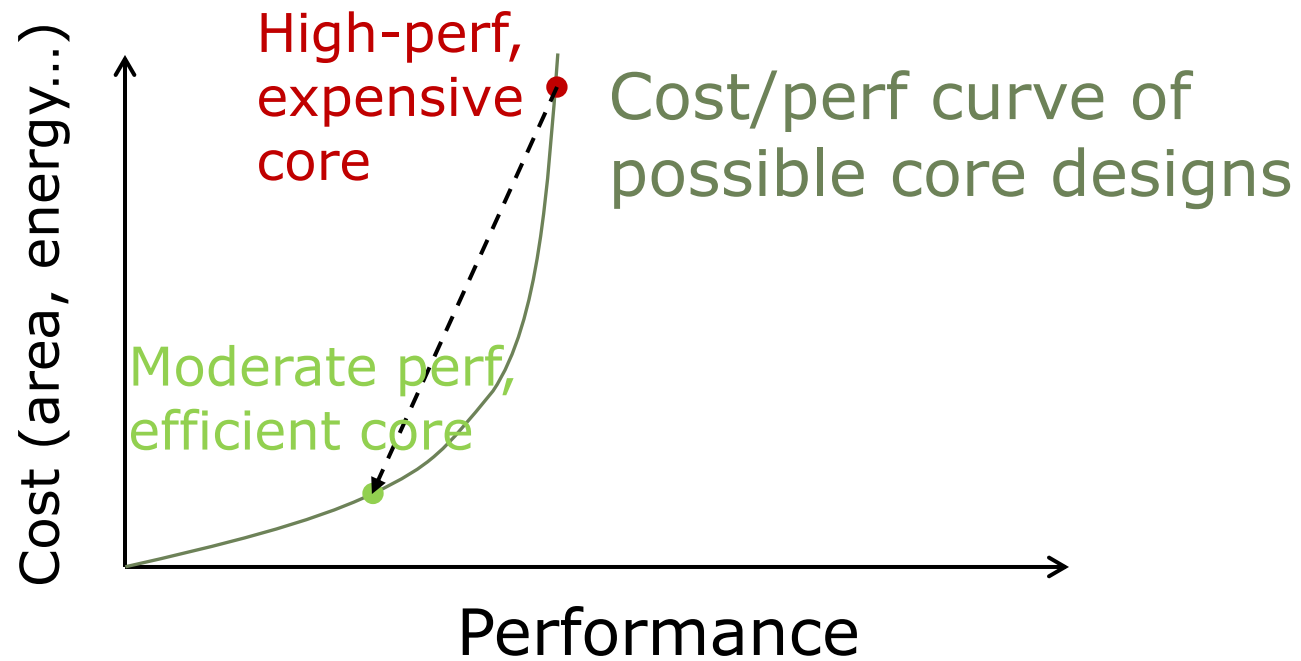
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Technology scaling

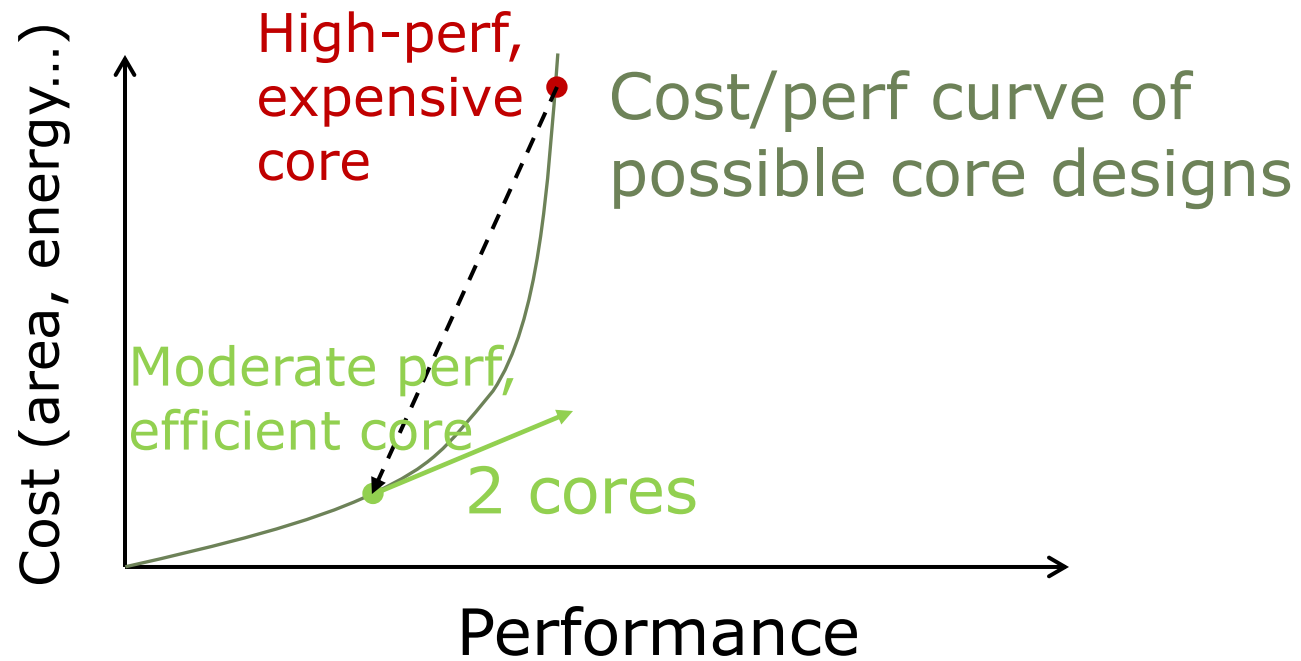
Multicore Performance



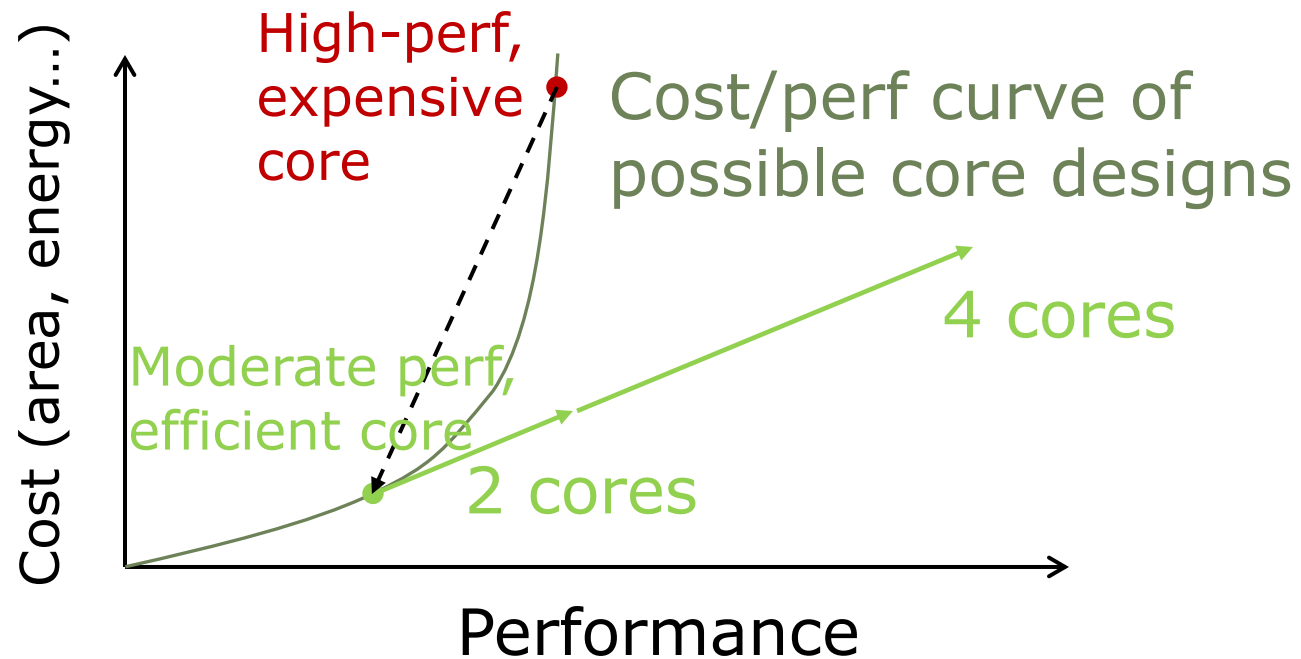
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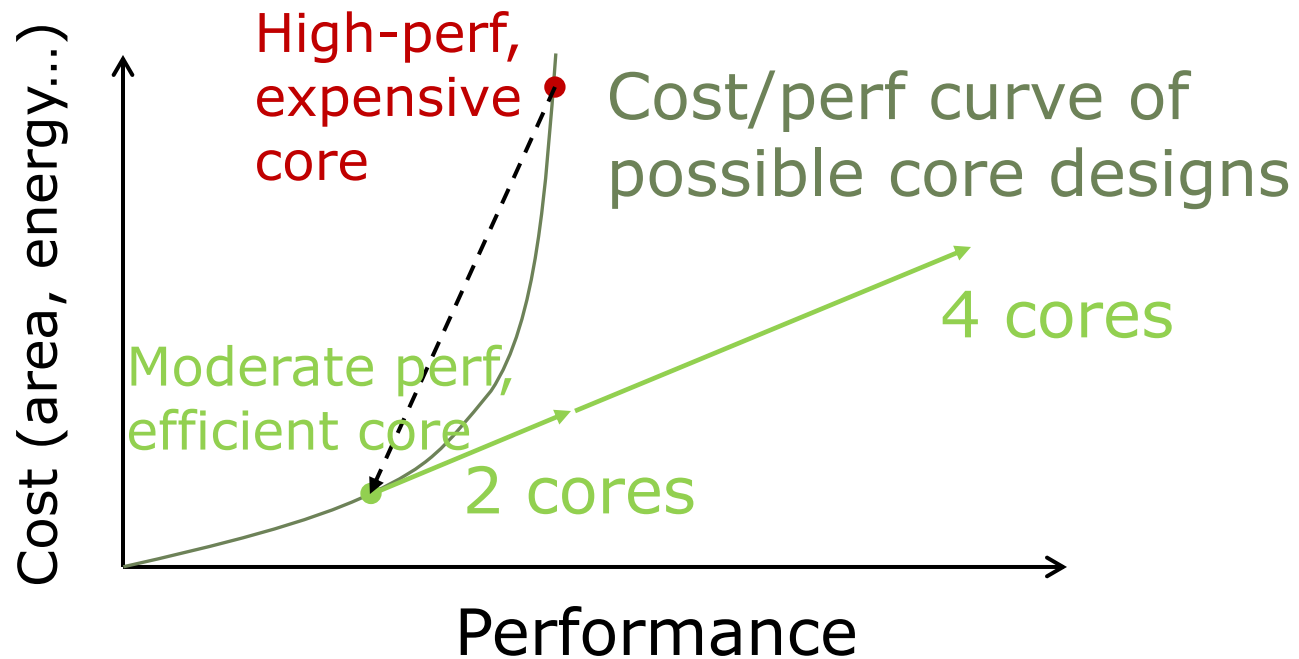
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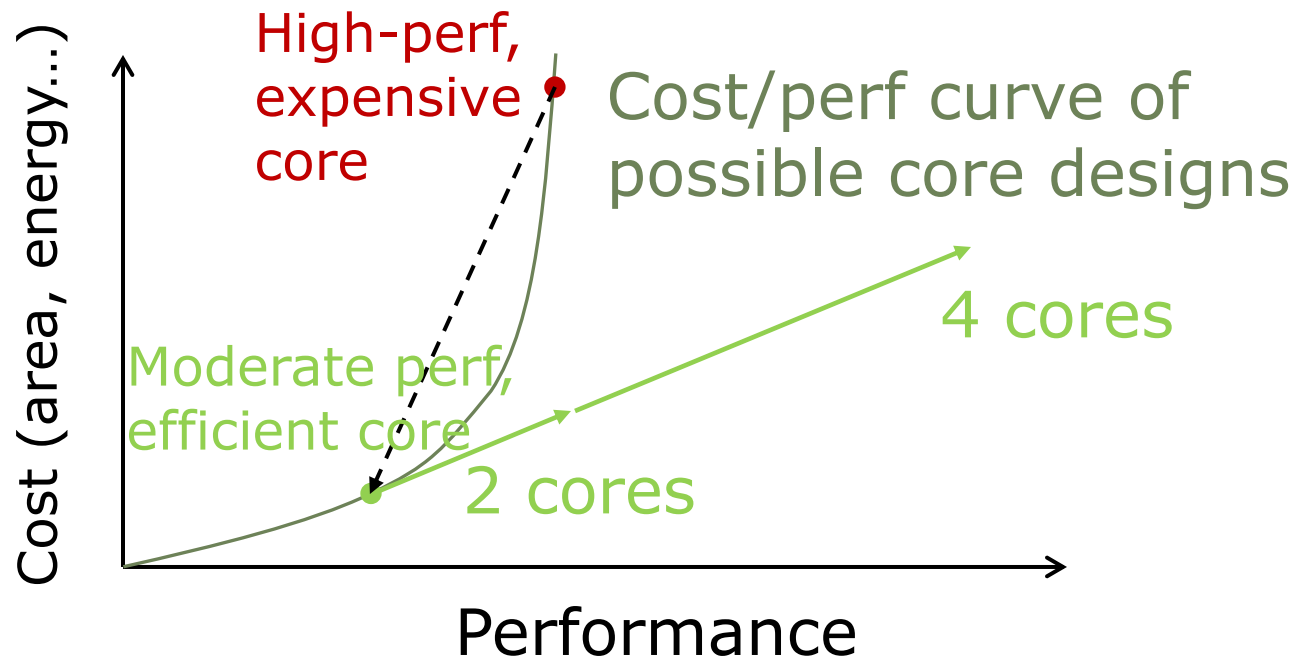


Multicore Performance



What factors may limit multicore performance?

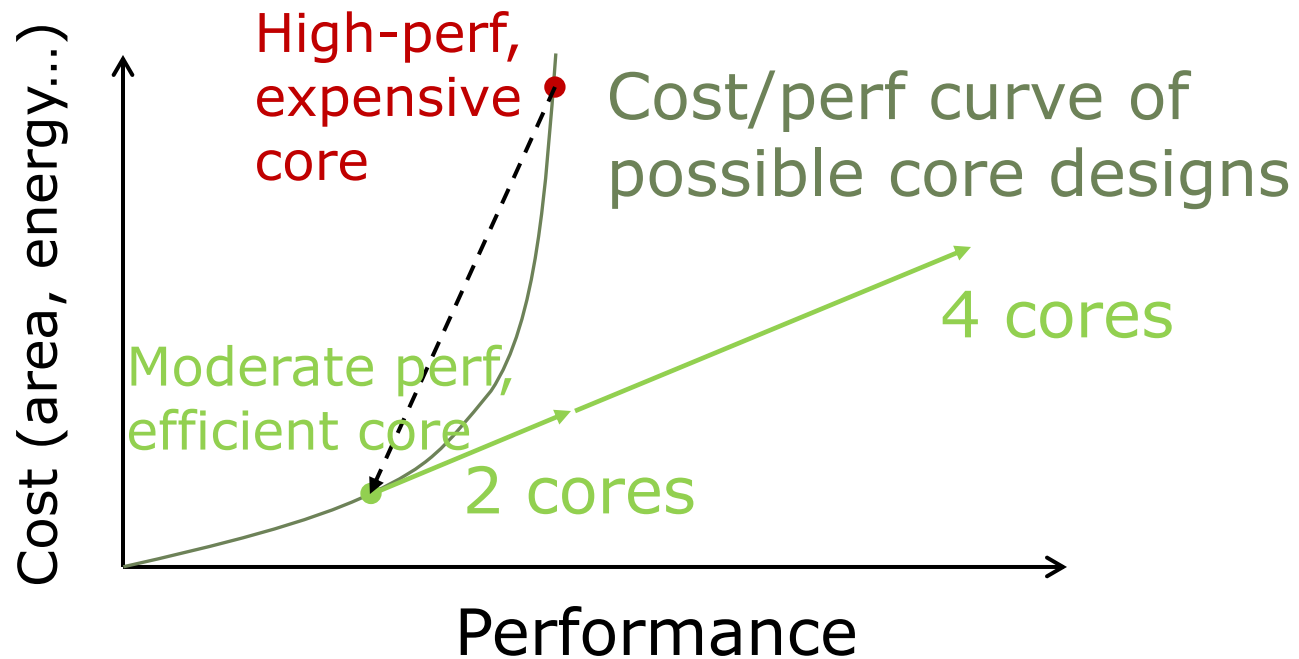
Multicore Performance



What factors may limit multicore performance?

Limited application parallelism

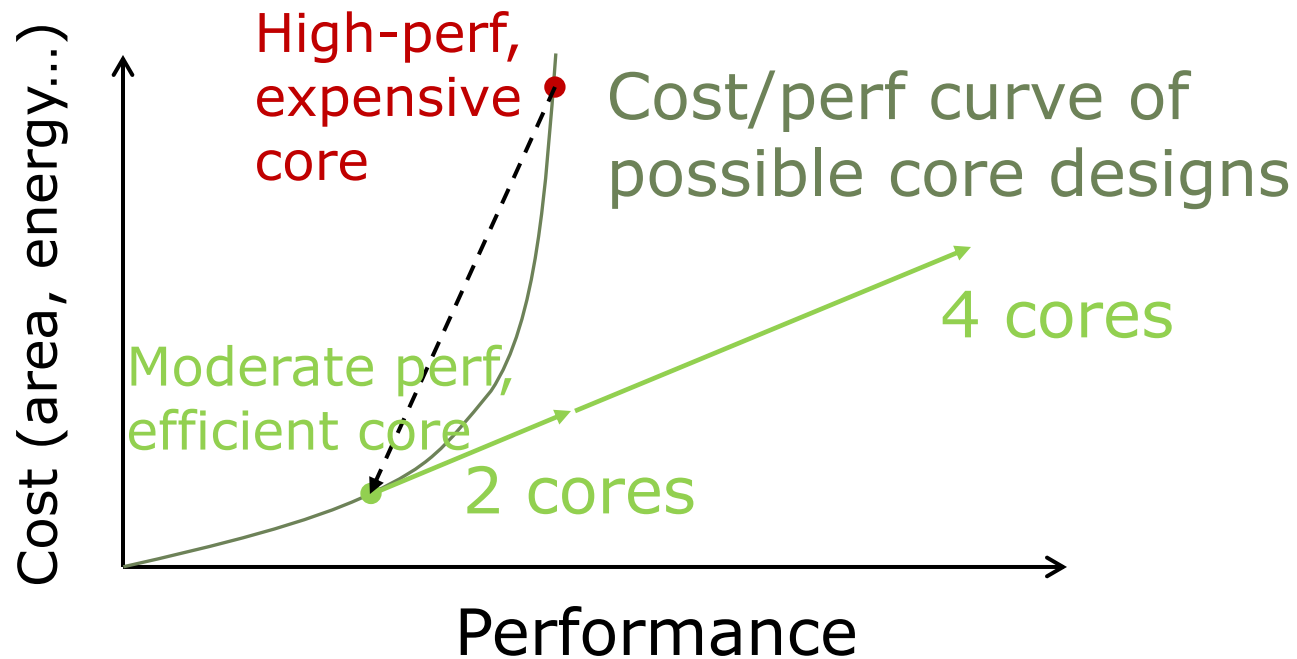
Multicore Performance



What factors may limit multicore performance?

Limited application parallelism
Memory accesses and inter-core communication

Multicore Performance



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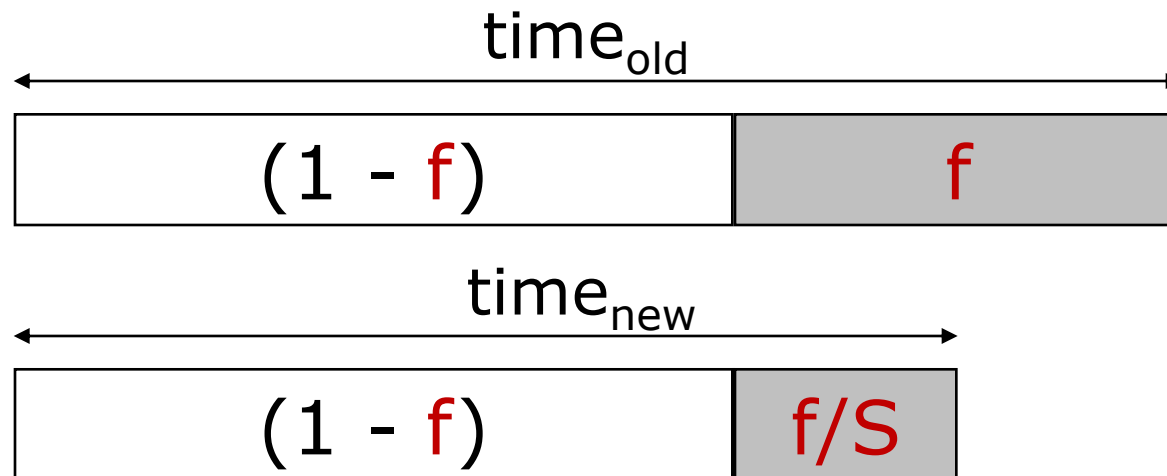
Limited application parallelism
Memory accesses and inter-core communication
Programming complexity

Amdahl's Law

- Speedup = $\text{time}_{\text{without enhancement}} / \text{time}_{\text{with enhancement}}$
- Suppose an enhancement speeds up a fraction f of a task by a factor of S

$$\text{time}_{\text{new}} = \text{time}_{\text{old}} \cdot ((1-f) + f/S)$$

$$S_{\text{overall}} = 1 / ((1-f) + f/S)$$

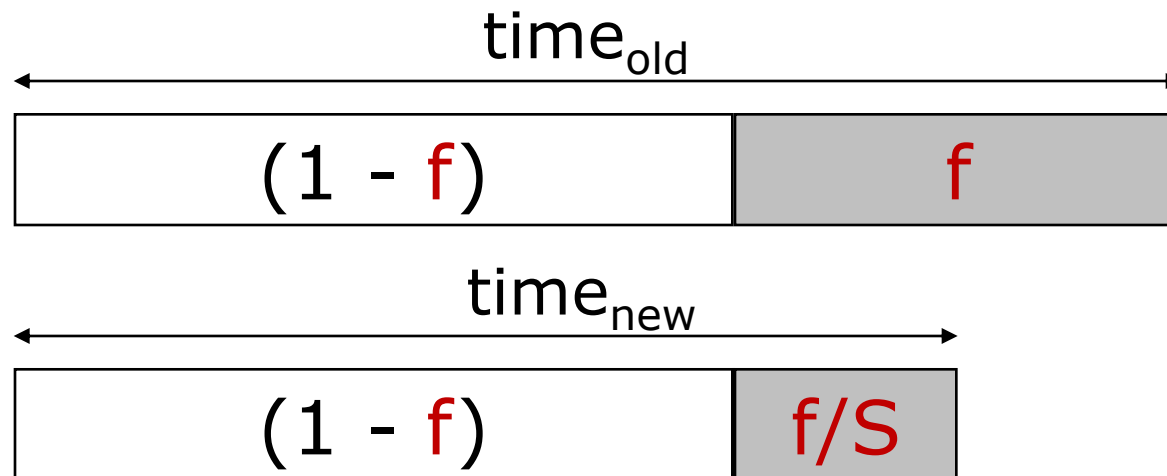


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Corollary: Make the common case fast

Amdahl's Law and Parallelism

- Say you write a program that can do 90% of the work in parallel, but the other 10% is sequential
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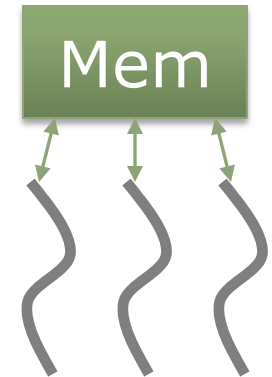
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What f do you need to use a 1000-core machine well?

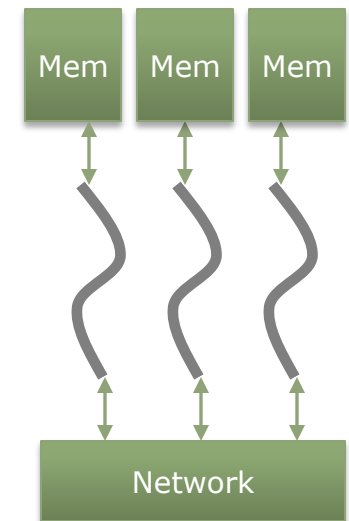
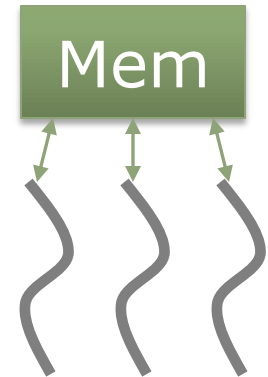
Communication Models

- Shared memory:
 - Single address space
 - Implicit communication by reading/writing memory
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 - Control (semaphores, locks, barriers, ...)
 - Low-level programming model: threads



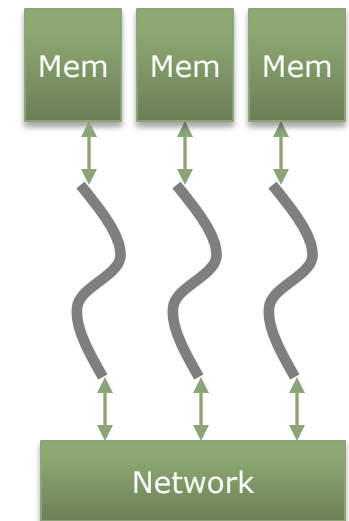
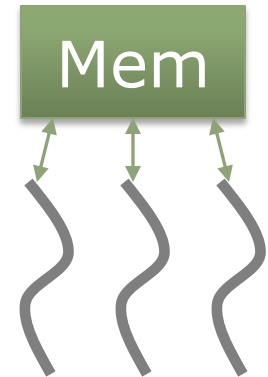
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- Pros/cons of each model?



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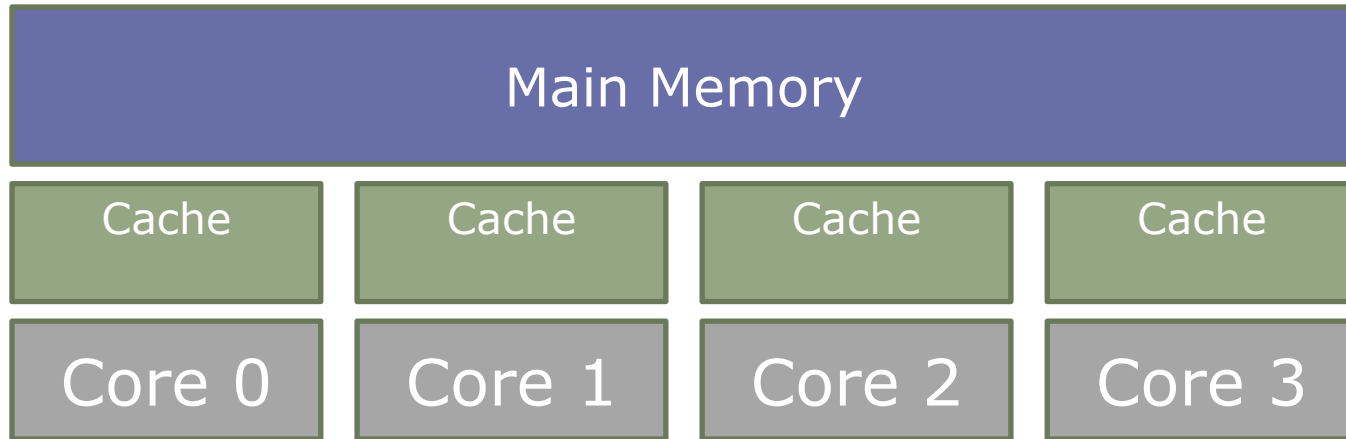
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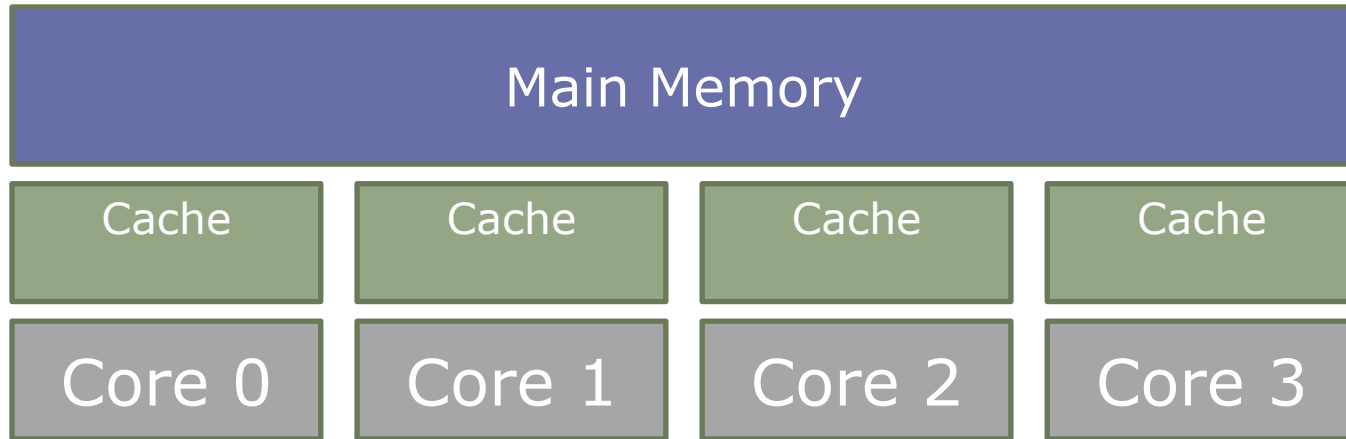
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Cache Coherence Avoids Stale Data

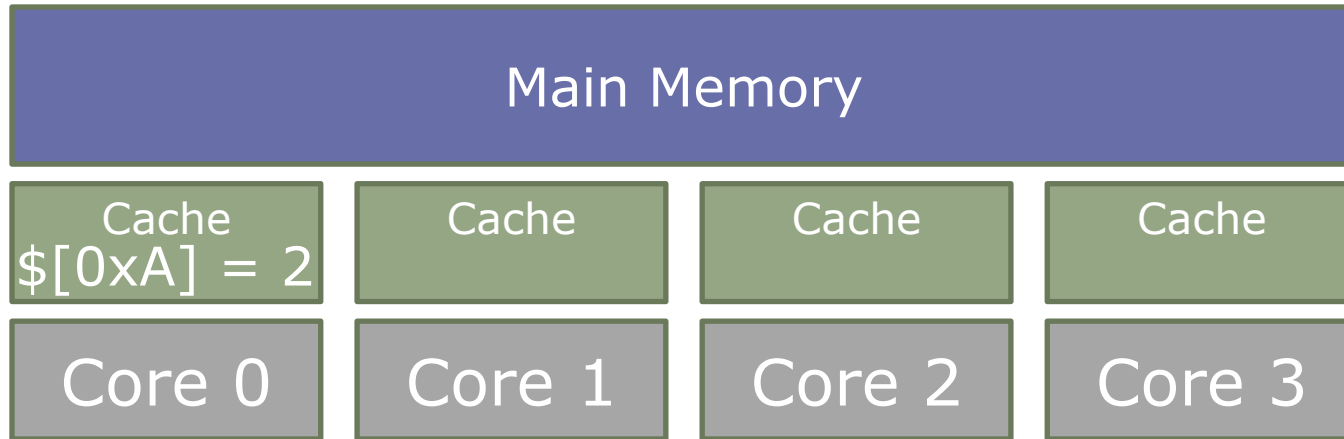


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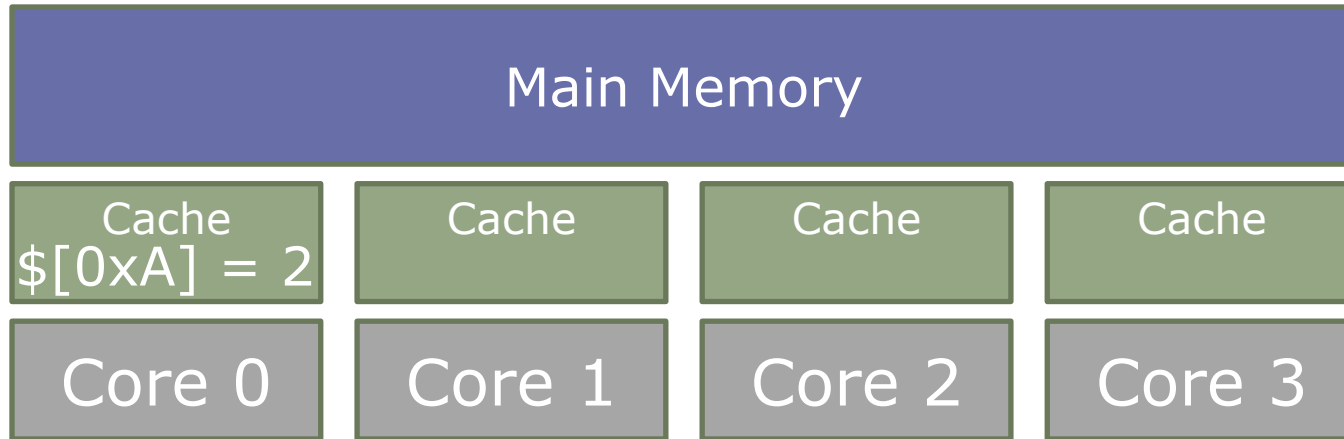
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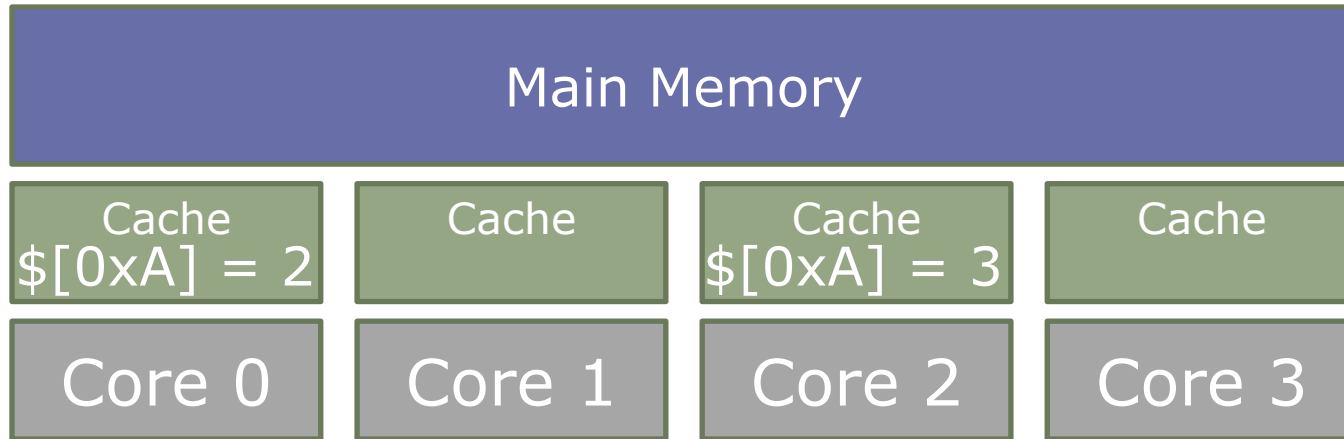
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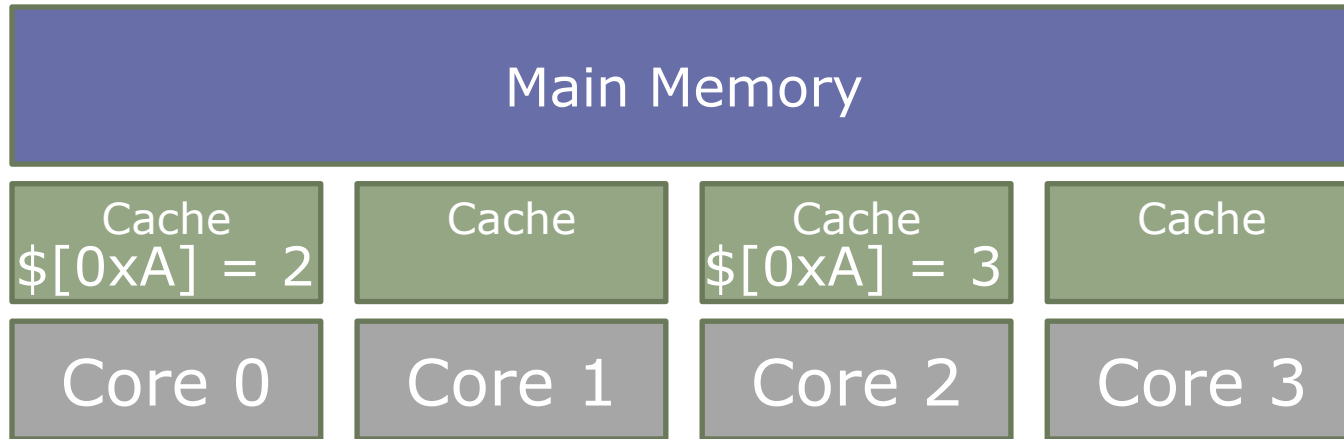
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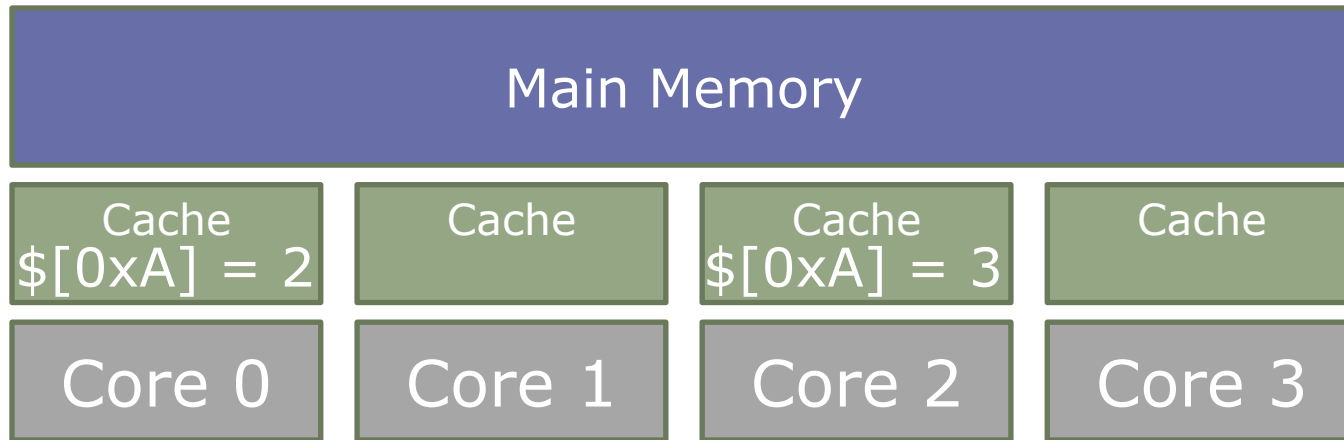


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Cache Coherence Avoids Stale Data



① LD 0xA → 2

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③ LD 0xA → 2 (stale!)

- A **cache coherence protocol** controls cache contents to avoid stale cache lines

Implementing Cache Coherence

- Coherence protocols must enforce two rules:
 - Write propagation: Writes eventually become visible to all processors
 - Write serialization: Writes to the same location are serialized (all processors see them in the same order)

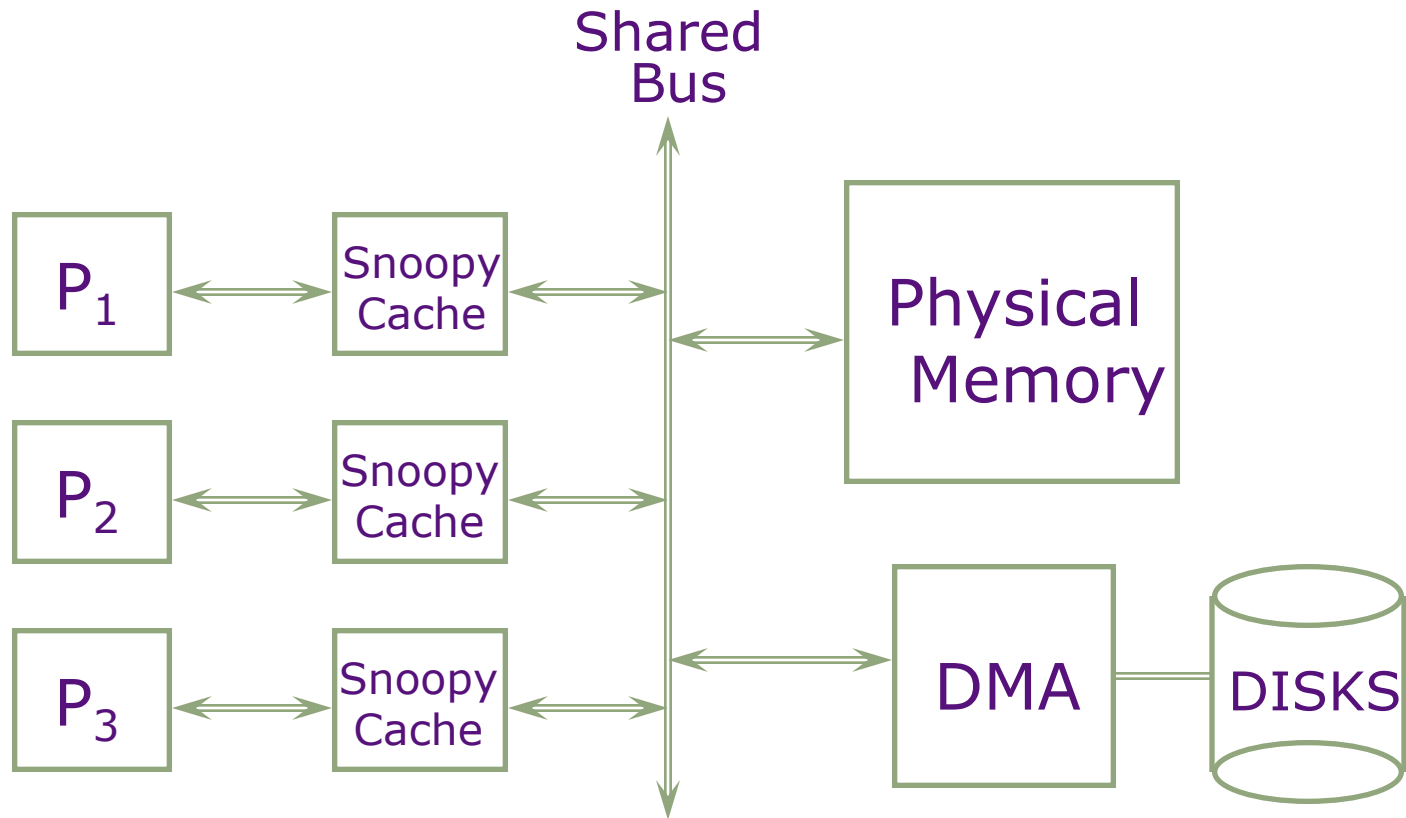
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- How to track sharing state of cached data and serialize requests to the same address?
 - Snooping-based protocols: All caches observe each other's actions through a shared bus
 - Directory-based protocols: A coherence directory tracks contents of private caches and serializes requests

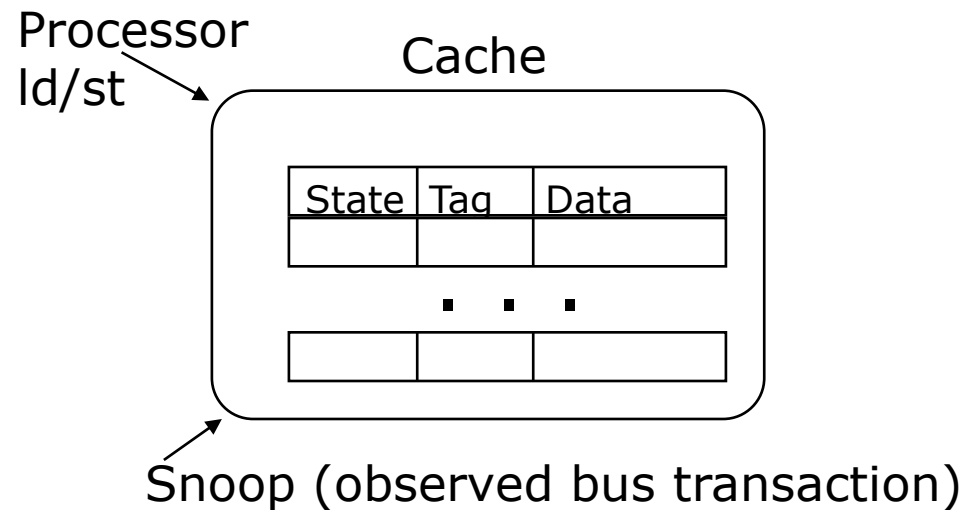
Snooping-Based Coherence [Goodman 1983]



Caches watch (snoop on) bus to keep all processors' view of memory coherent

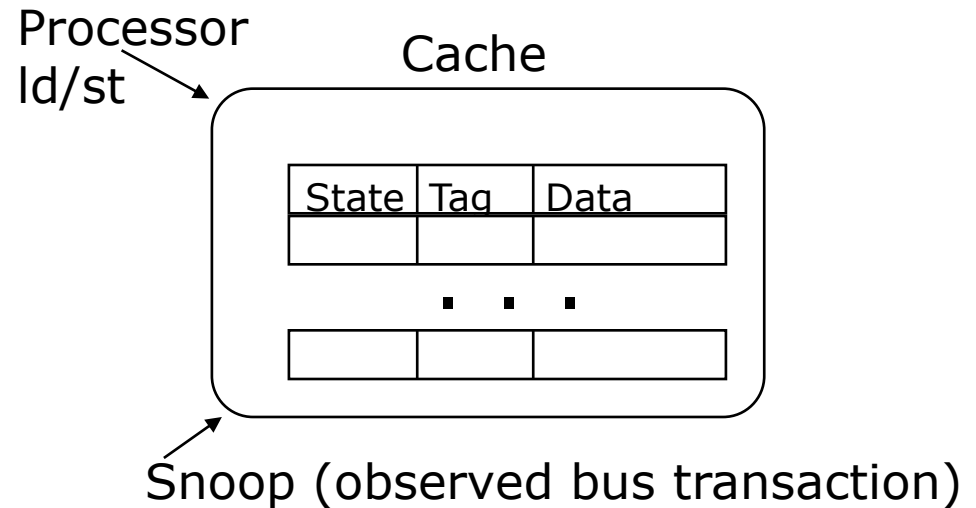
Snooping-Based Coherence

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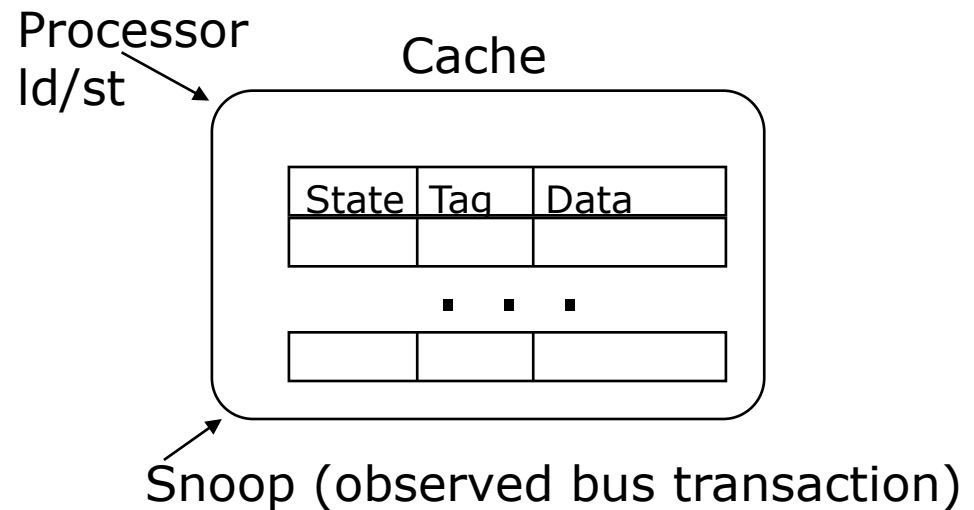
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 - State-transition diagram
 - Actions

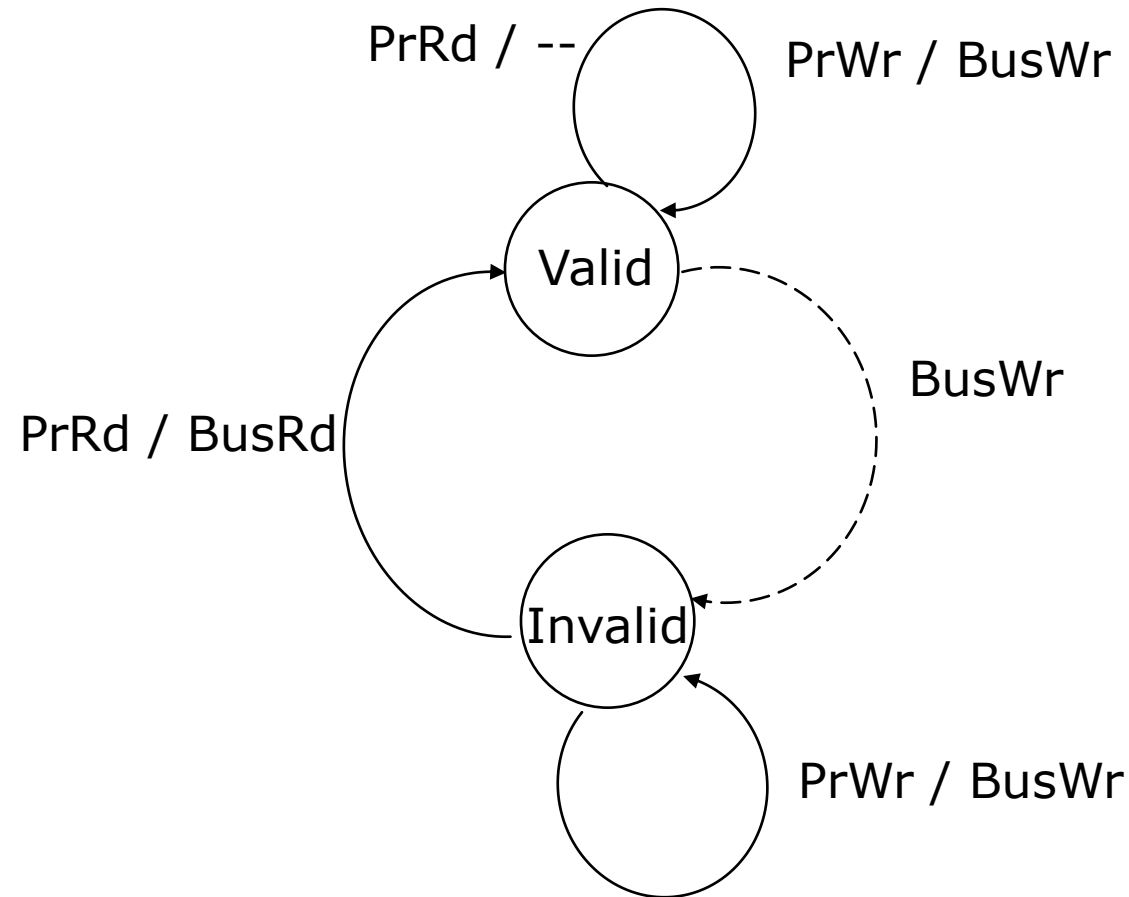


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- Handling writes:
 - Write-invalidate
 - Write-update



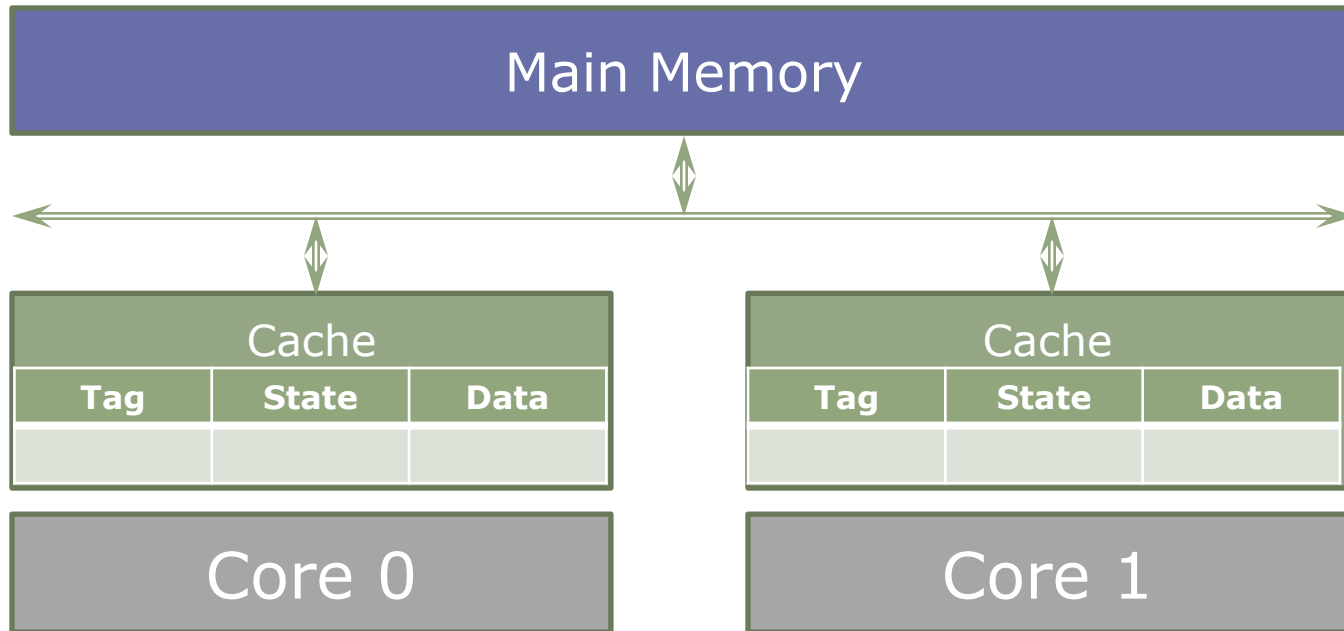
A Simple Protocol: Valid/Invalid (VI)



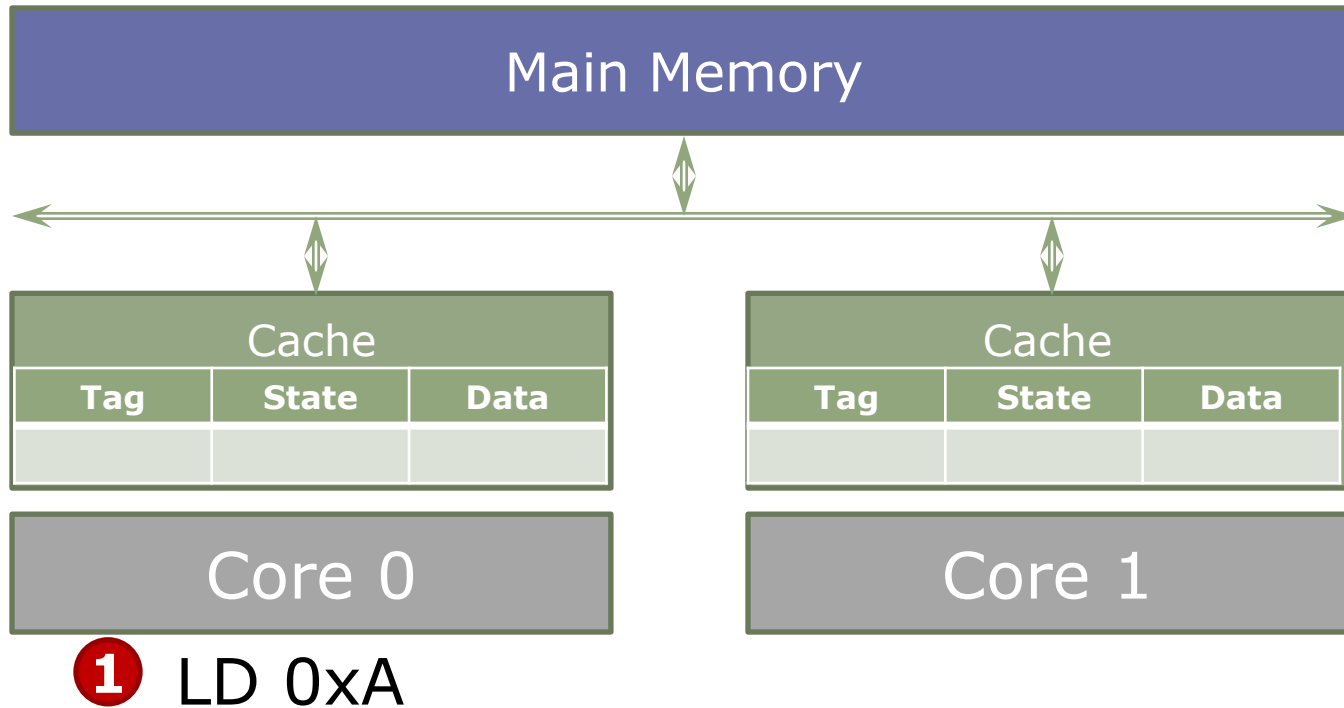
- Assume write-through caches

Actions
Processor Read (PrRd)
Processor Write (PrWr)
Bus Read (BusRd)
Bus Write (BusWr)

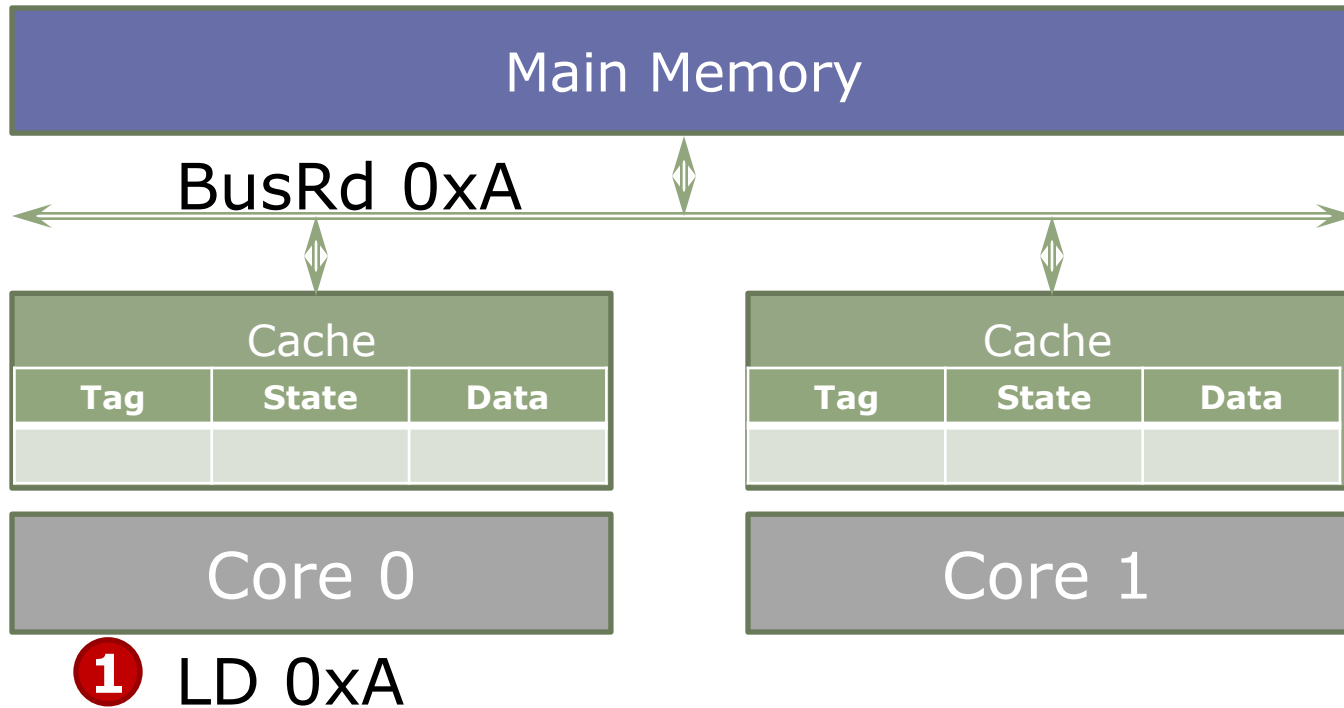
Valid/Invalid Example



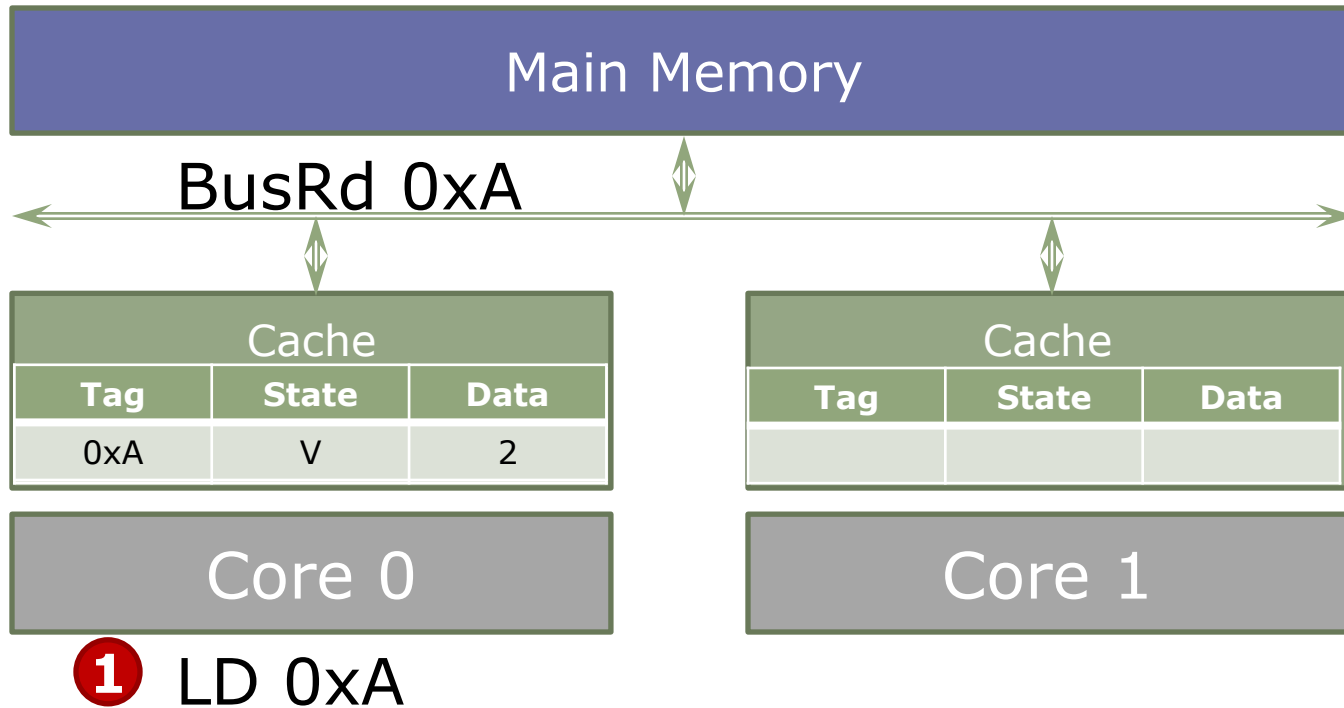
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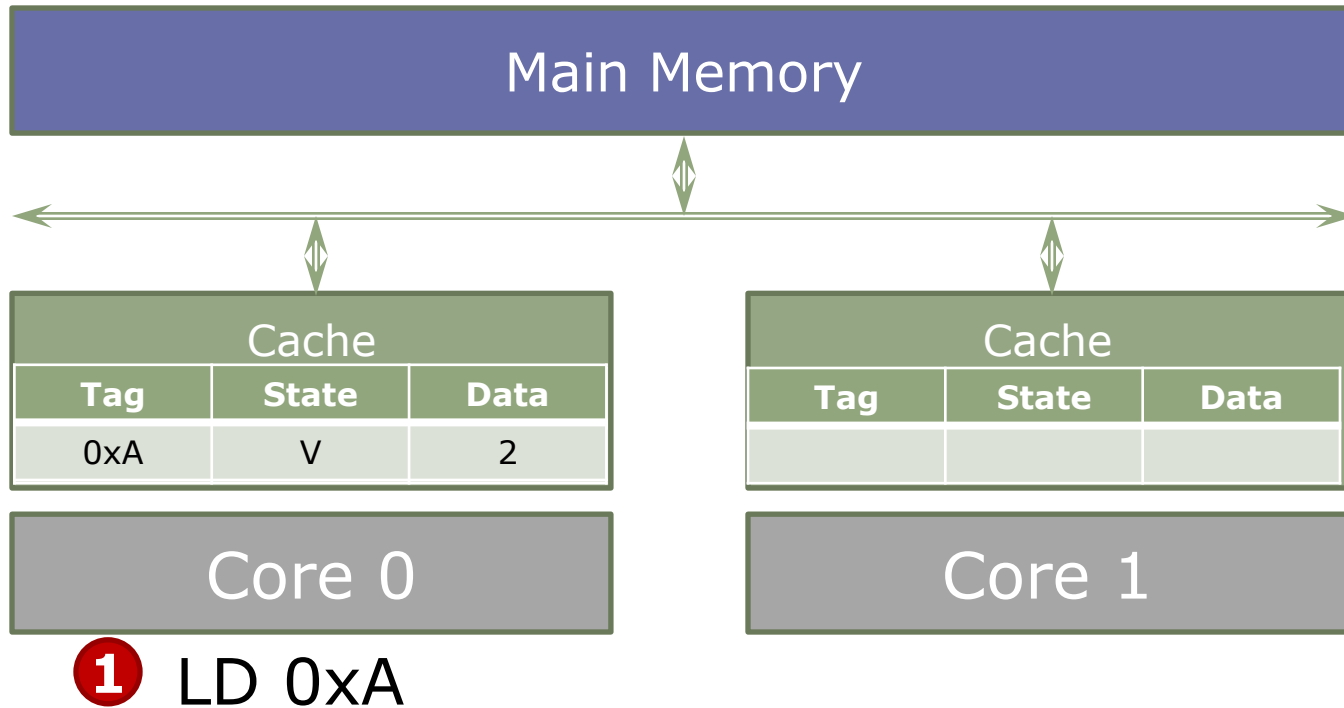
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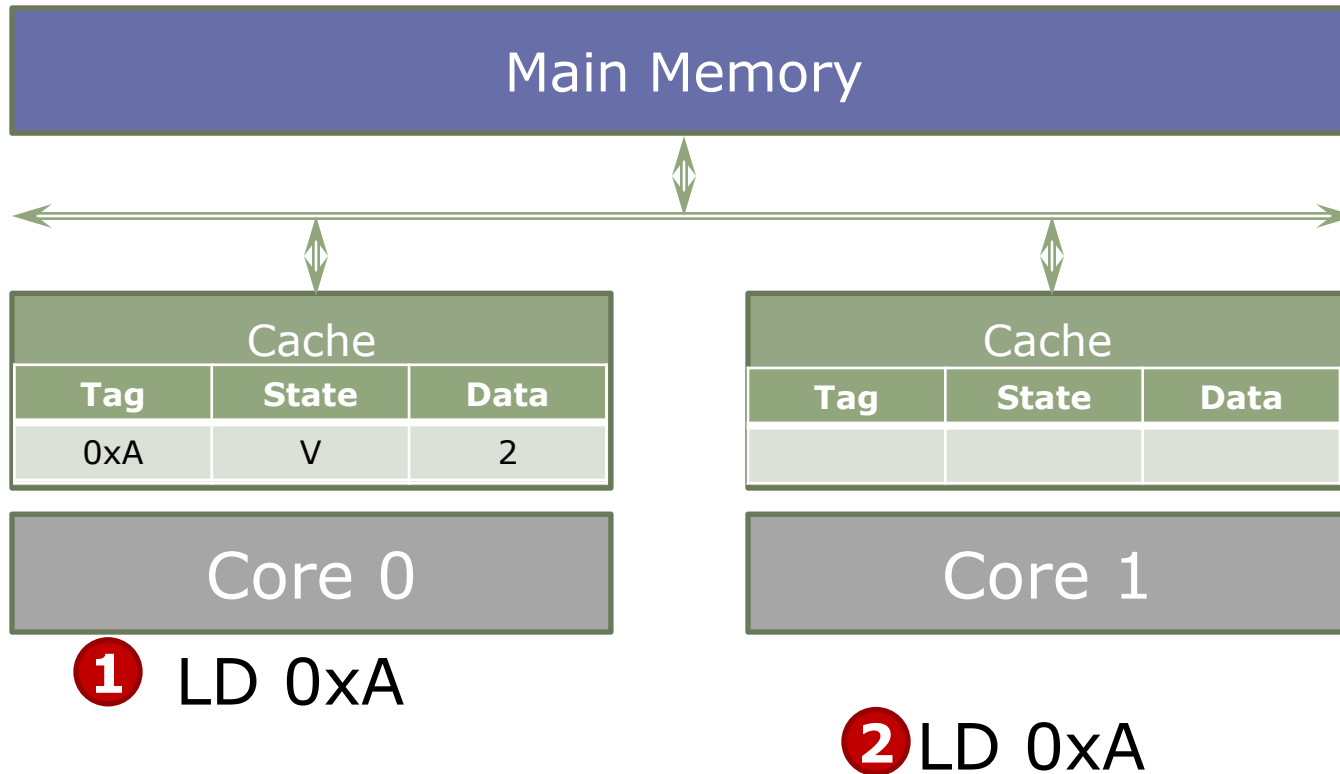
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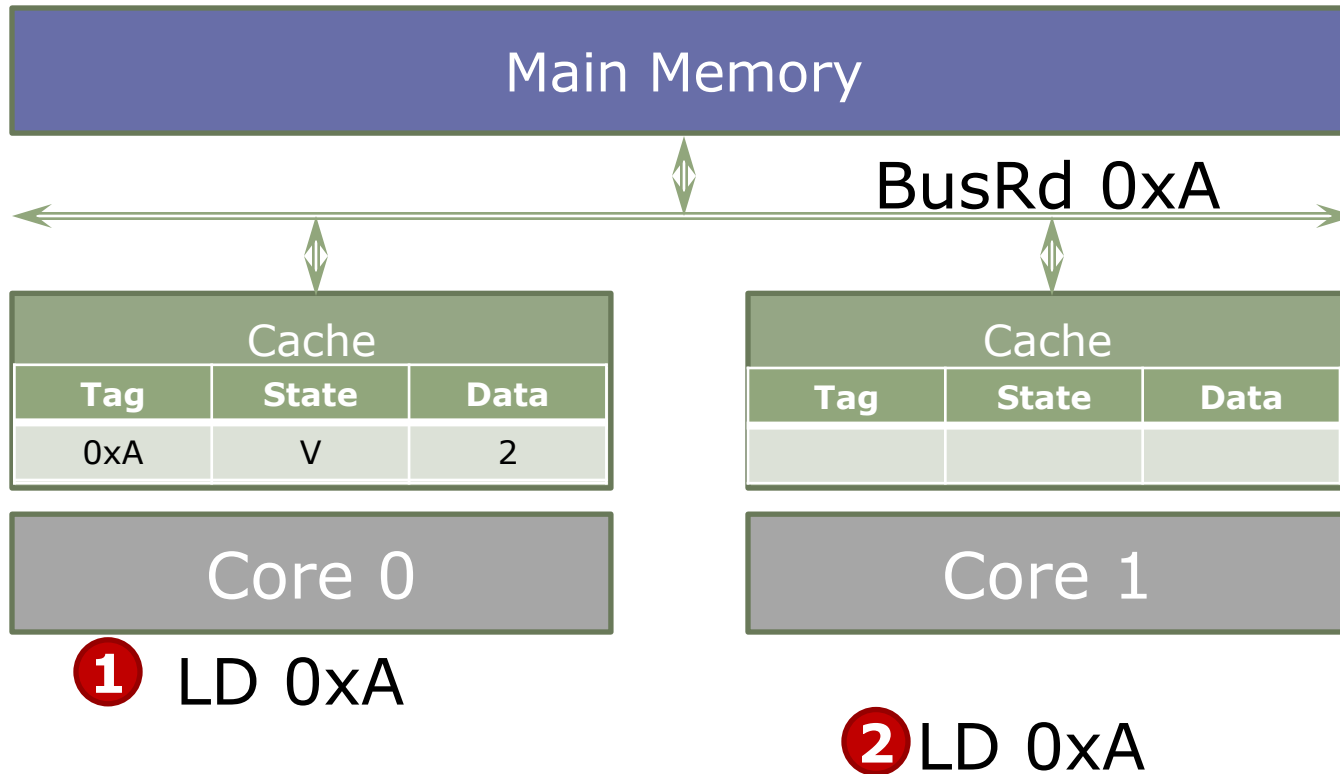
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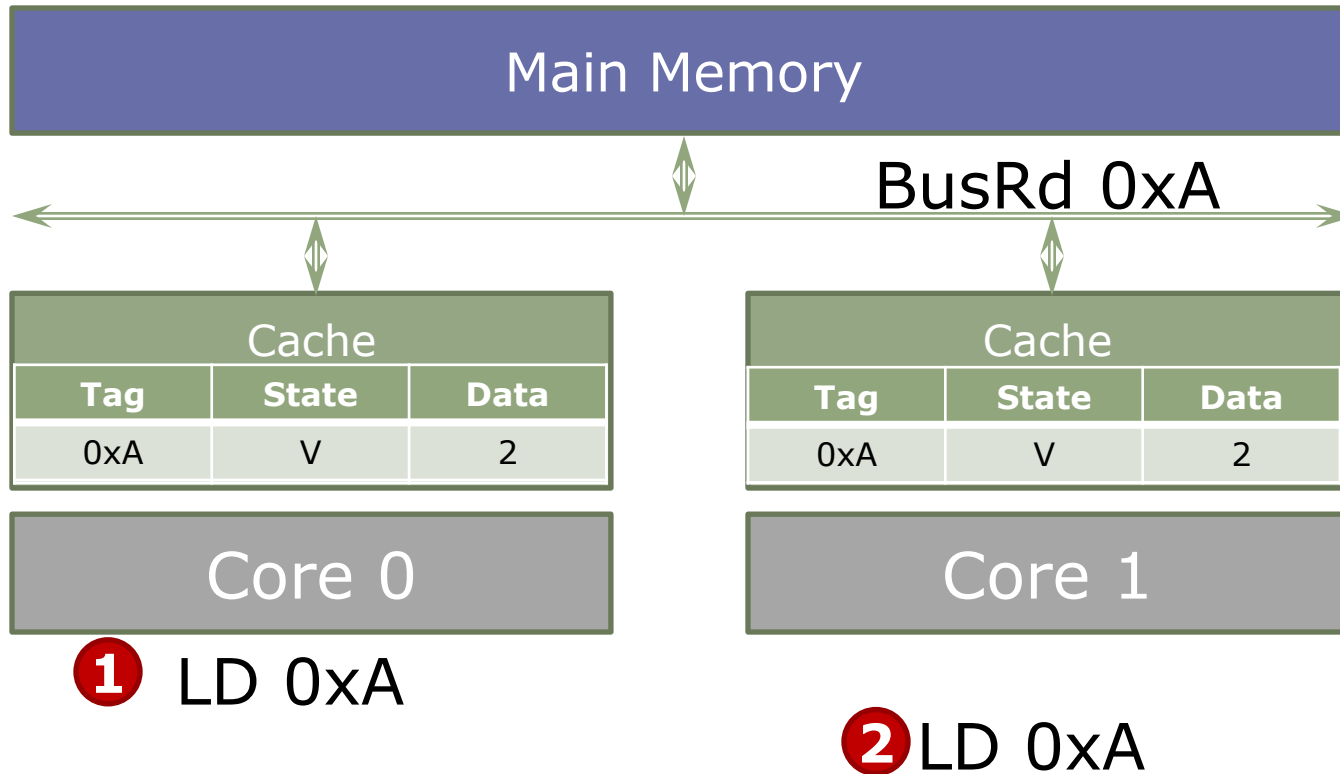
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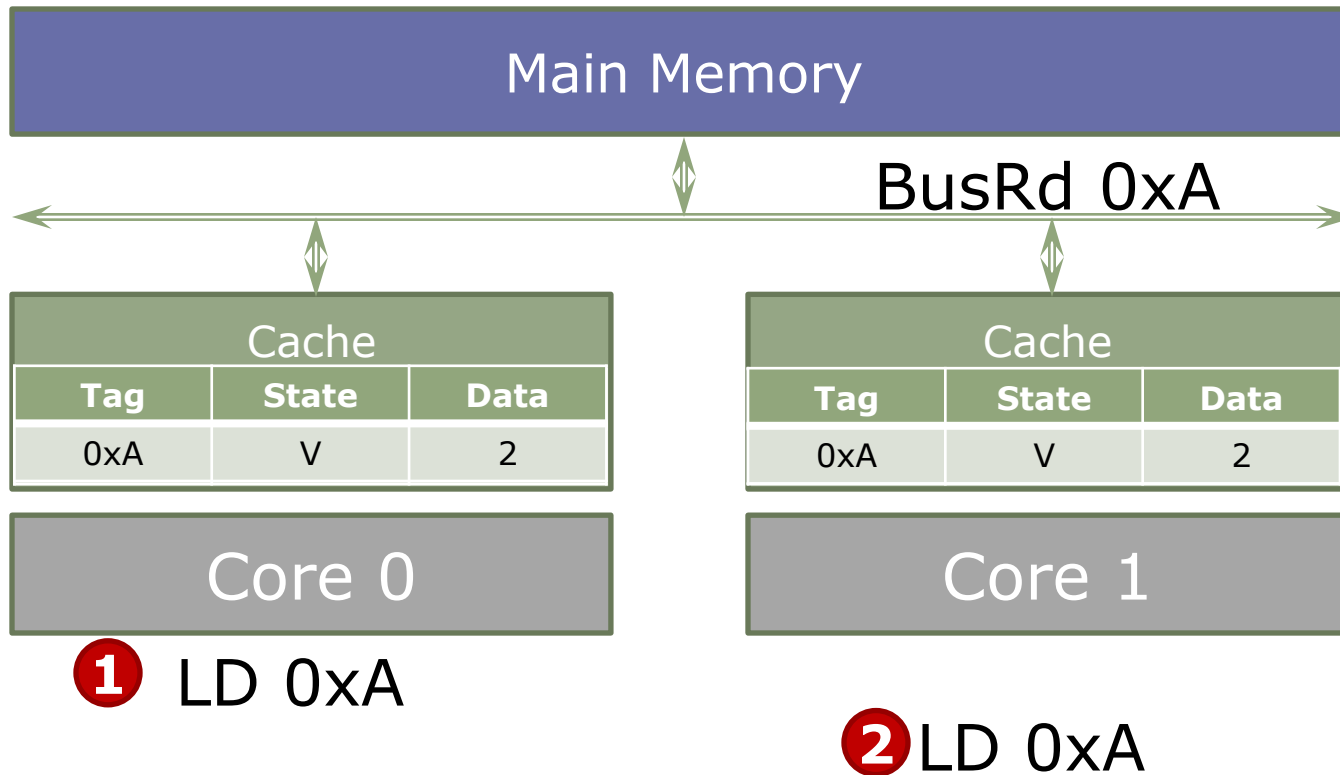
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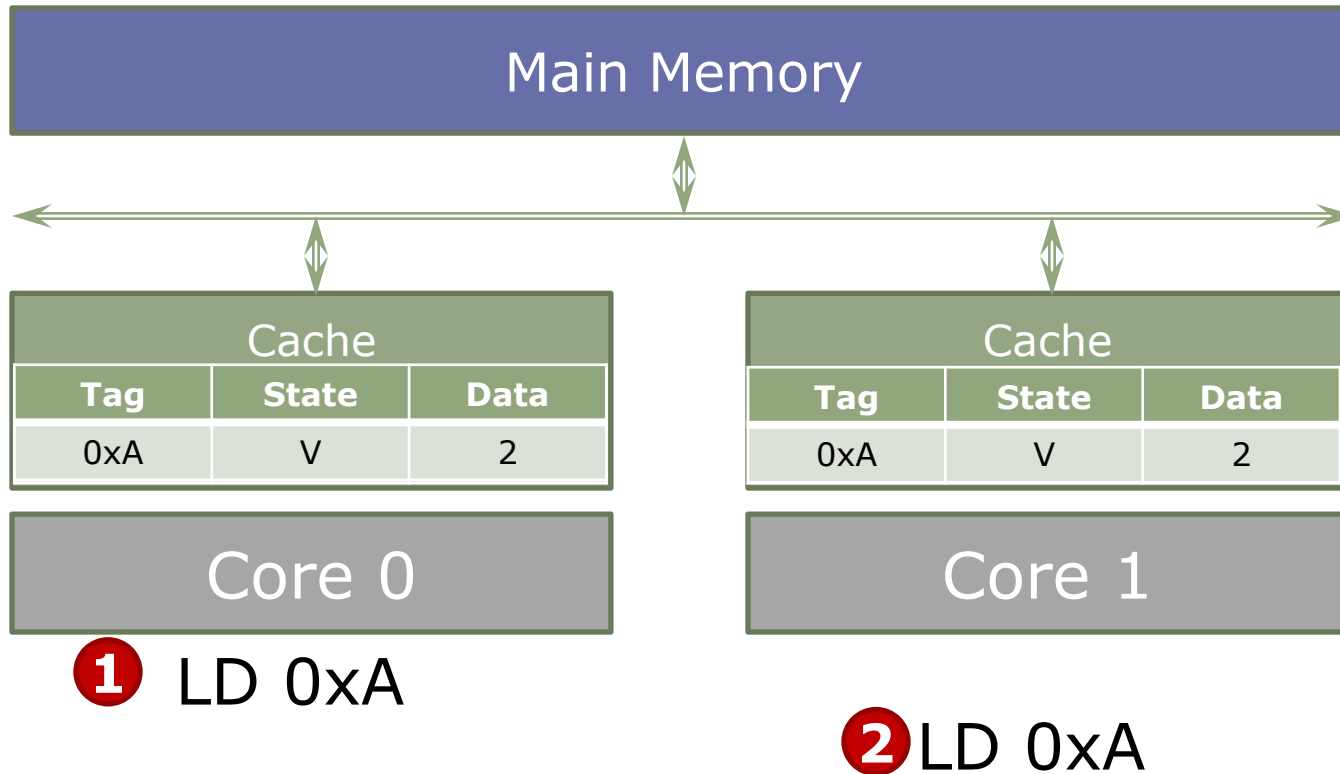


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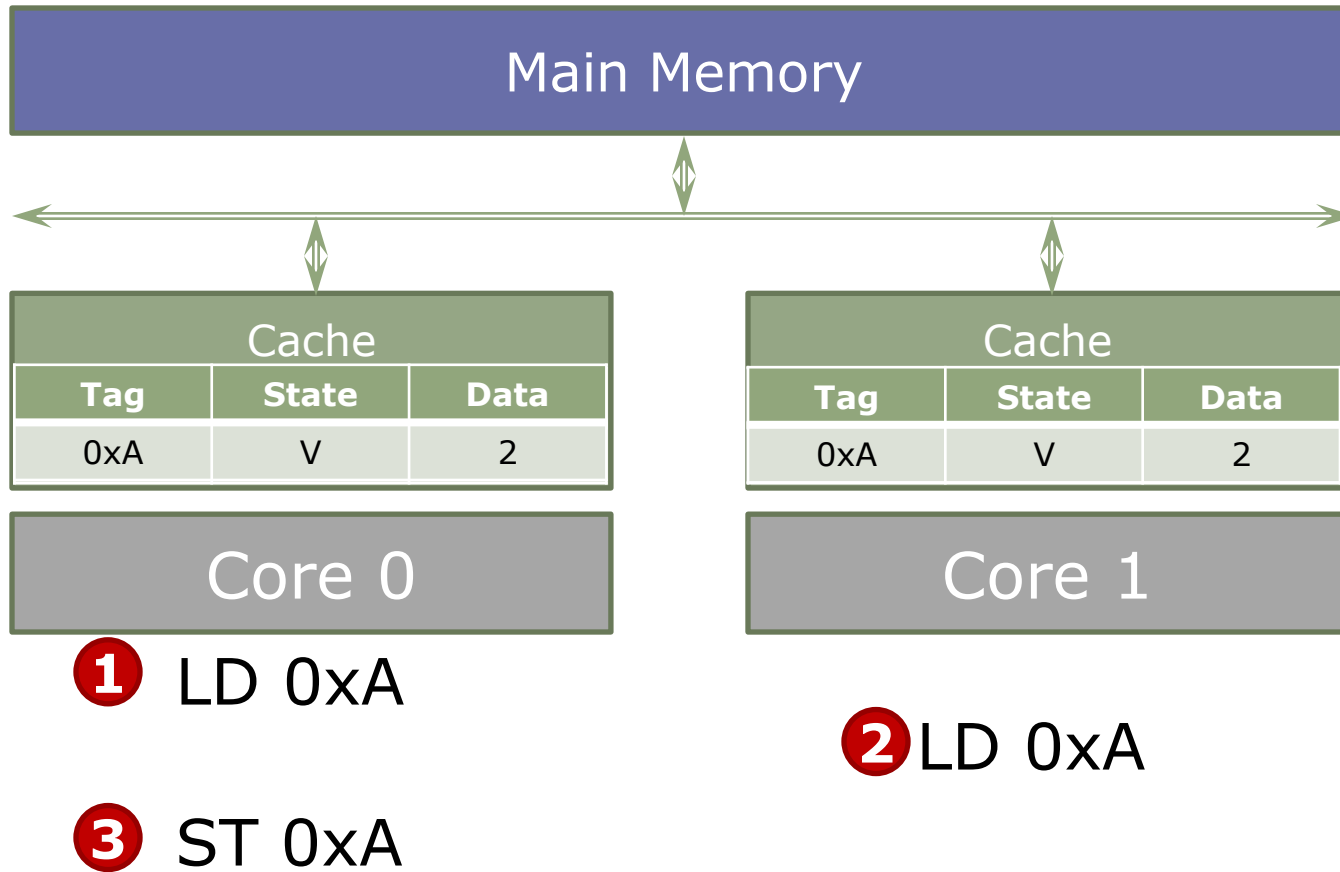


Additional loads satisfied locally, without BusRd

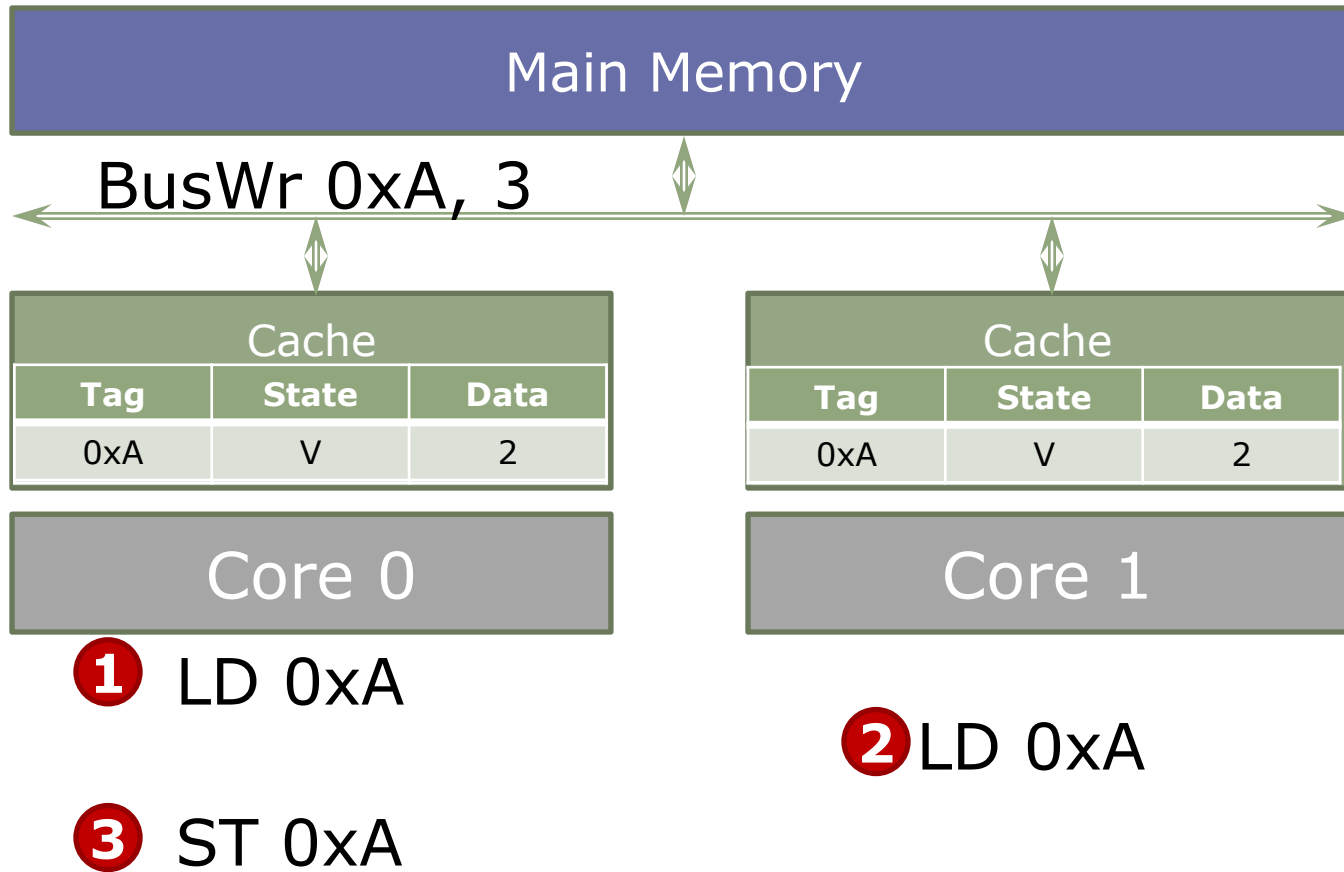
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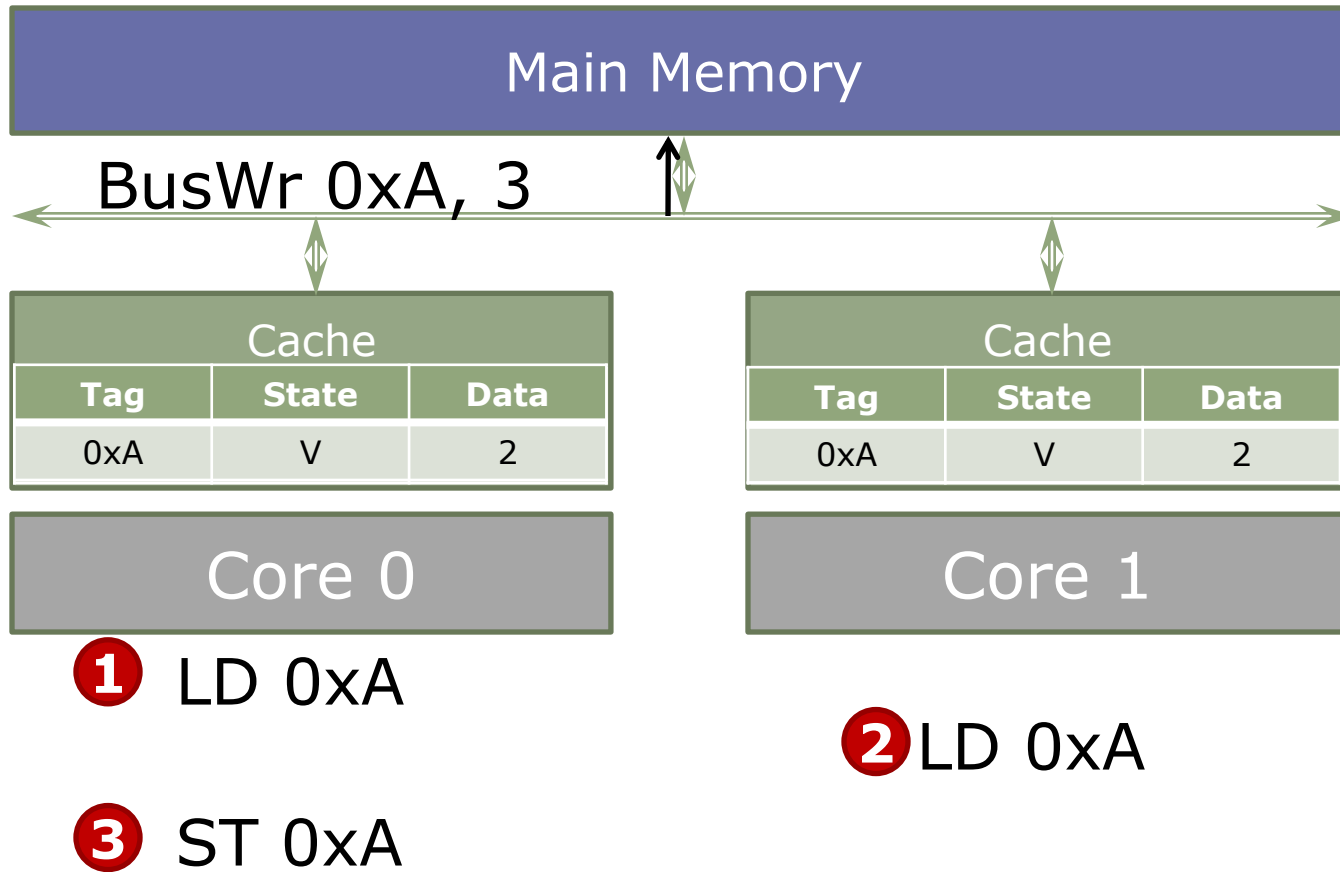
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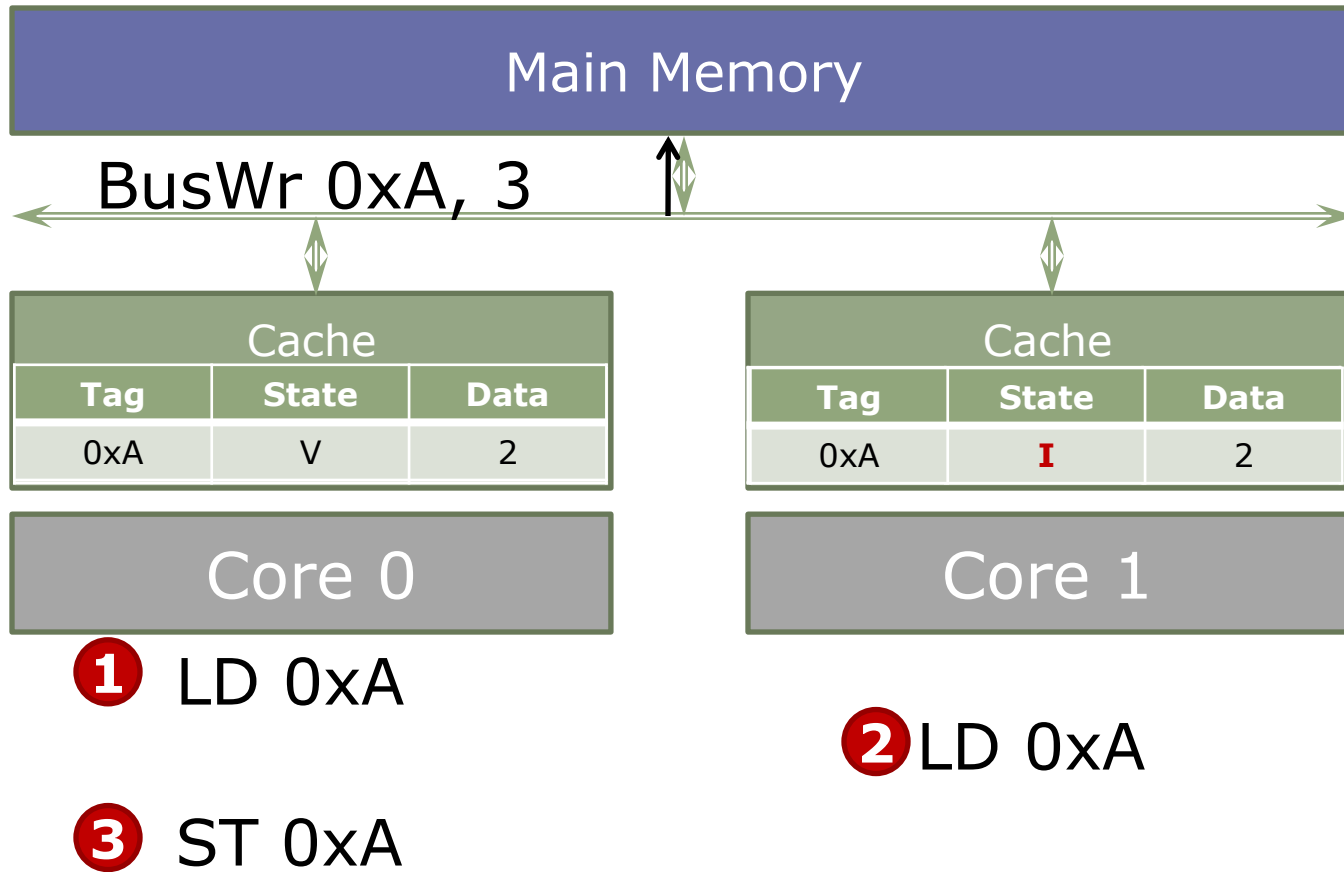
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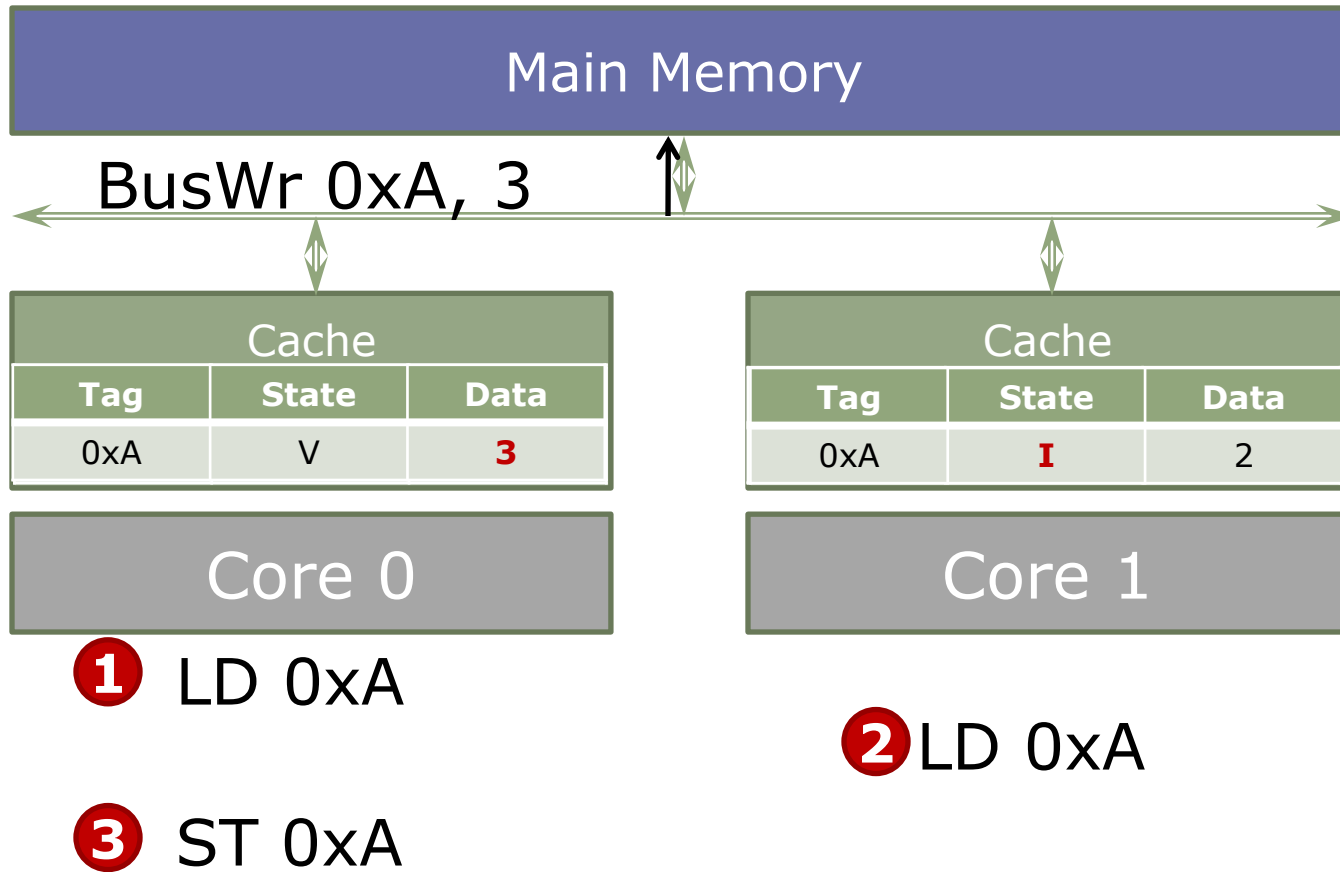
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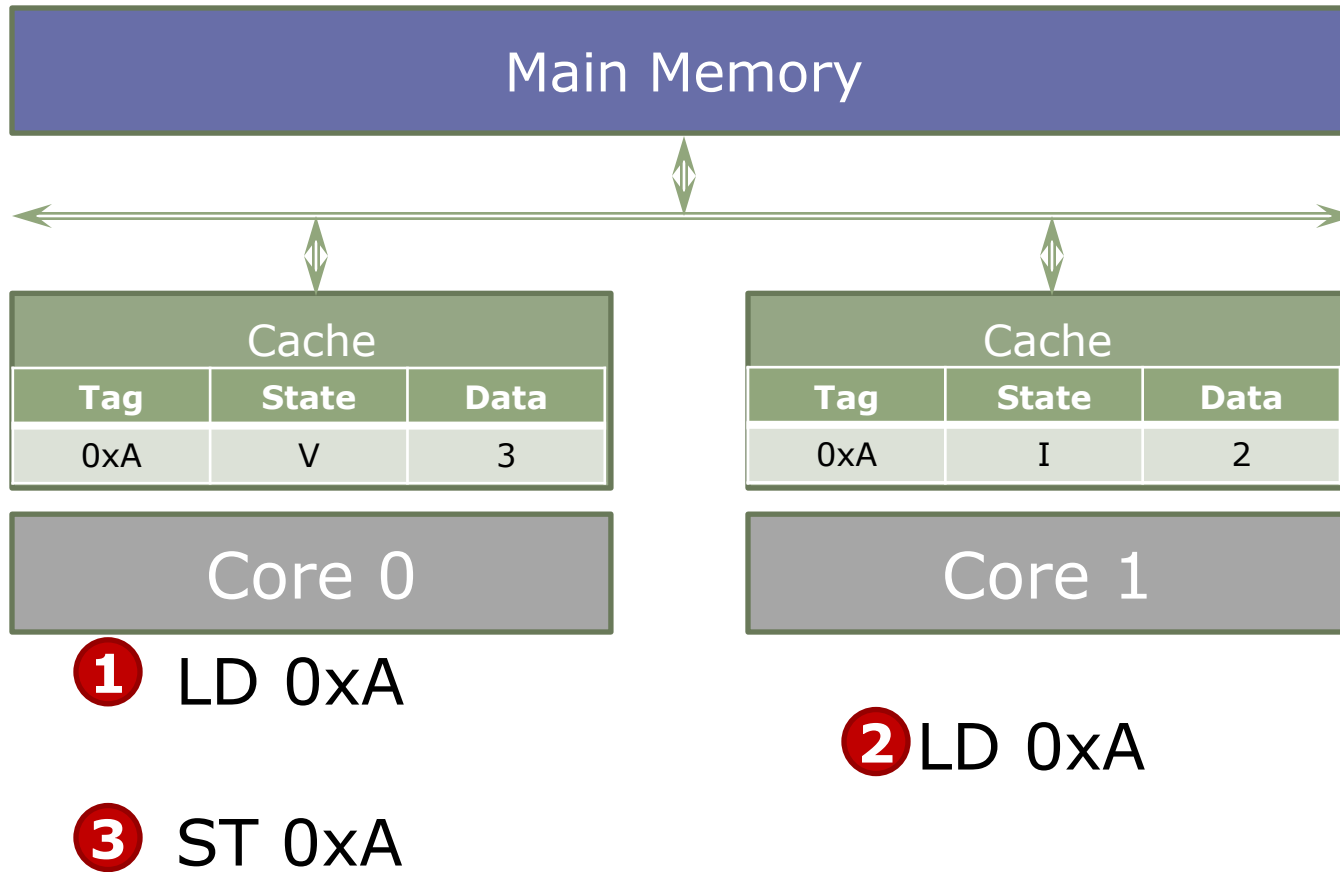
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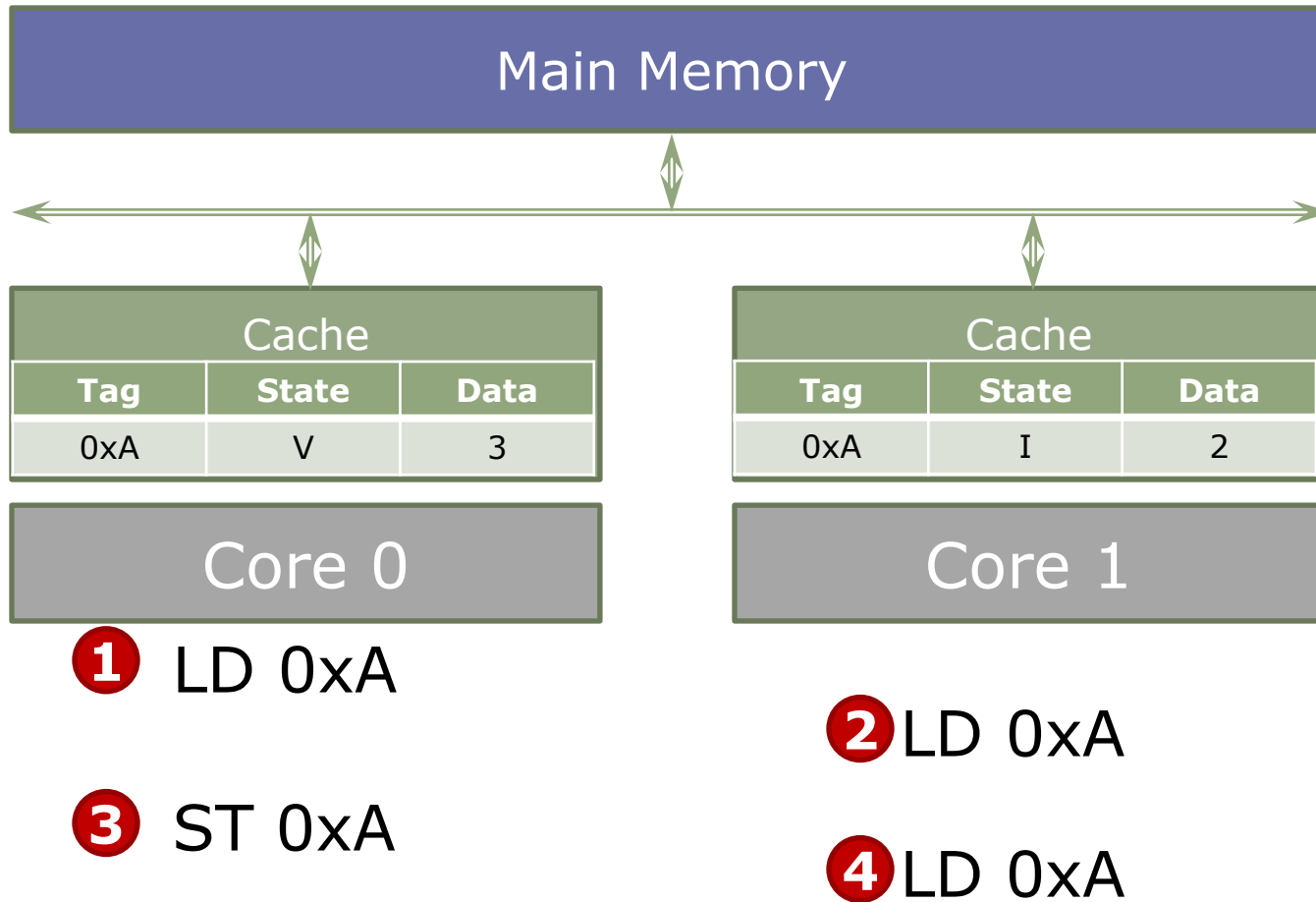
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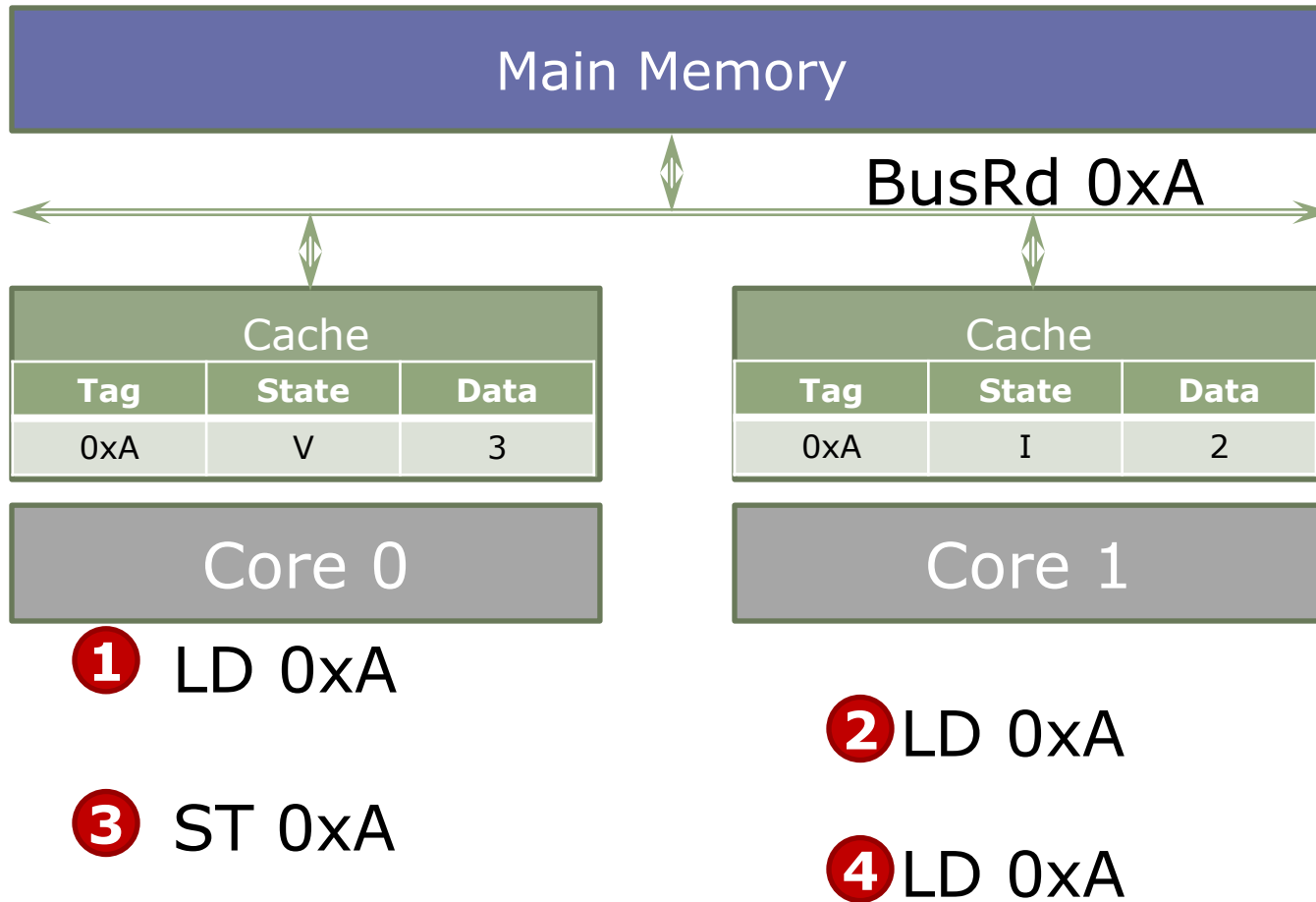
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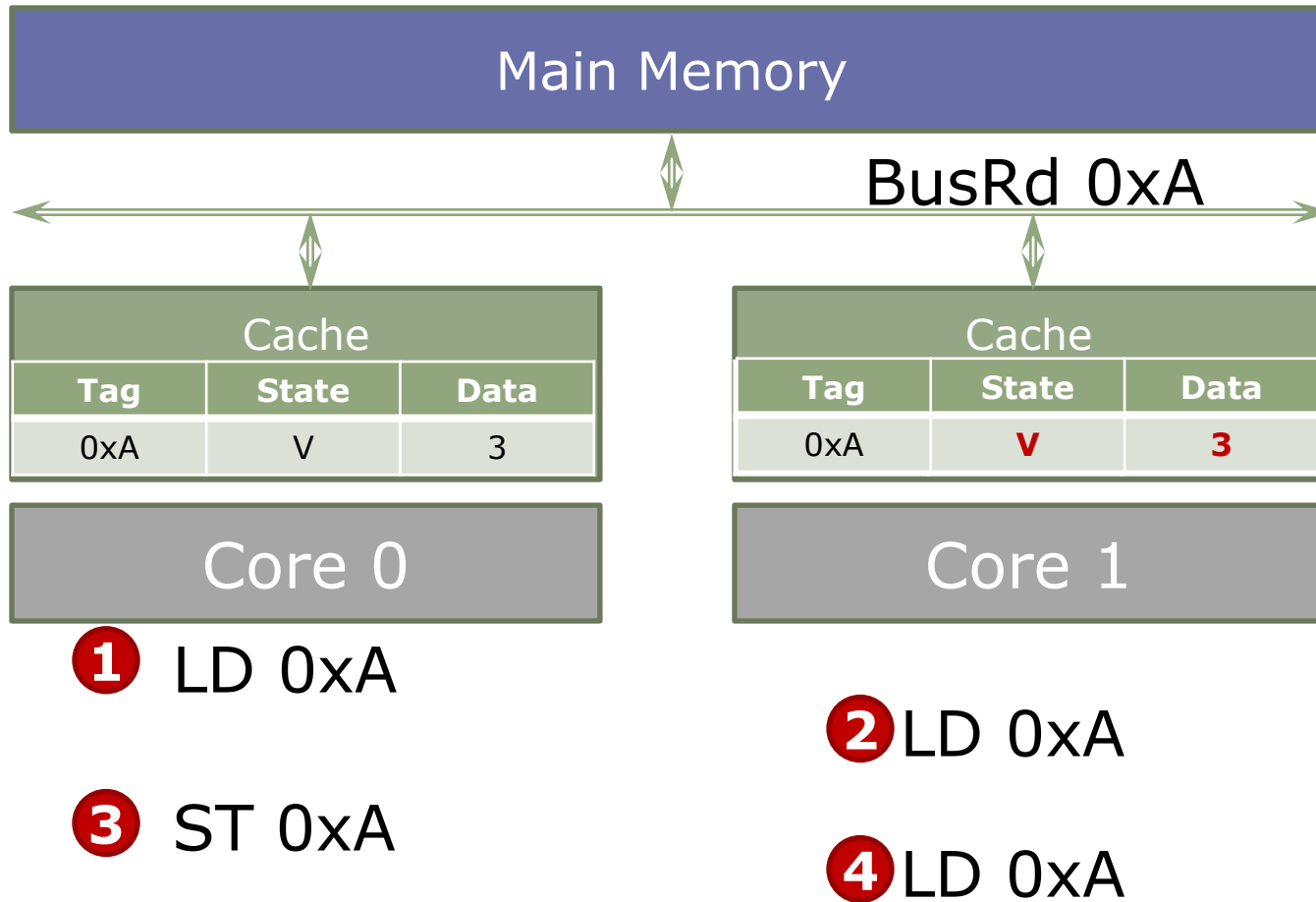
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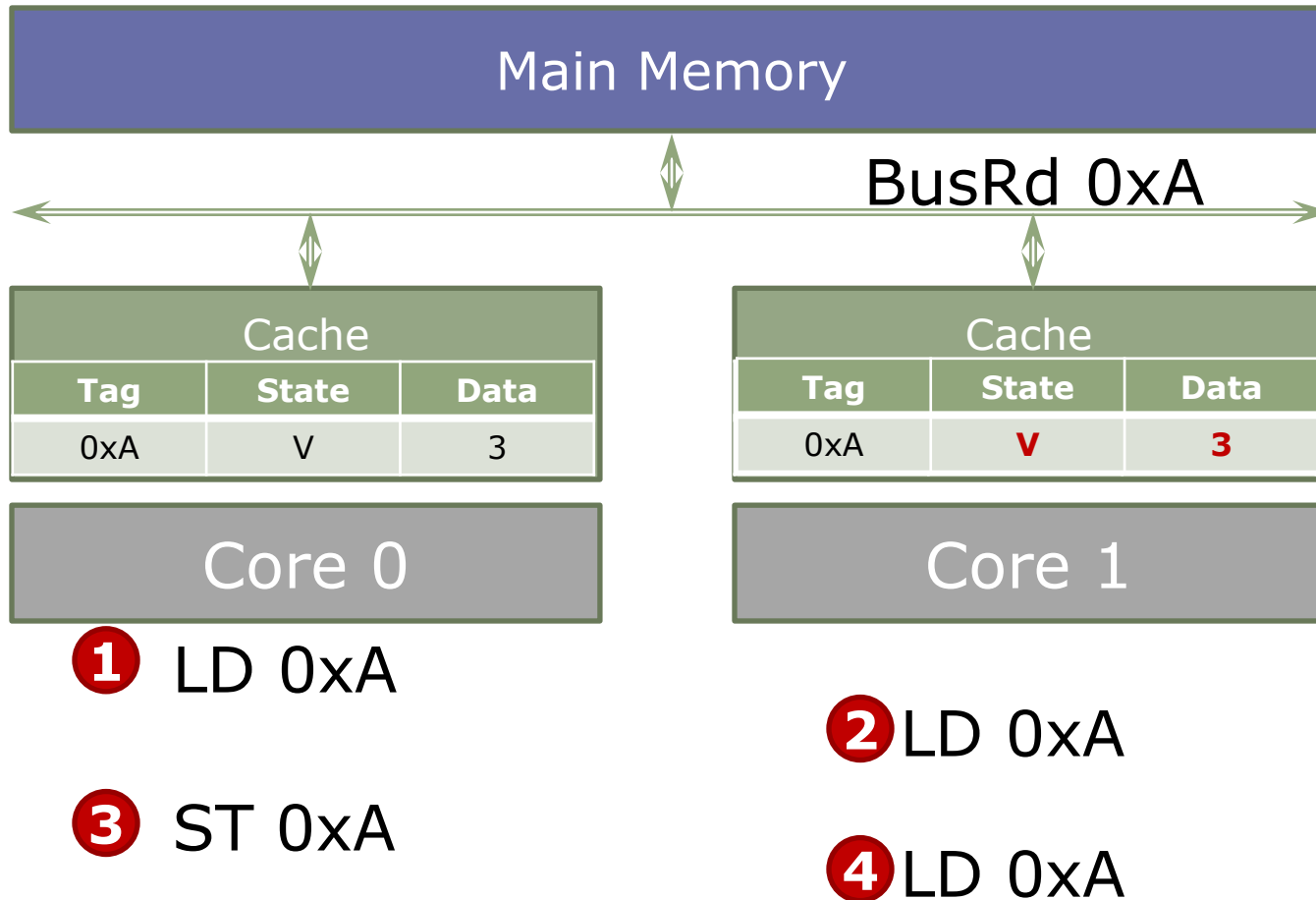
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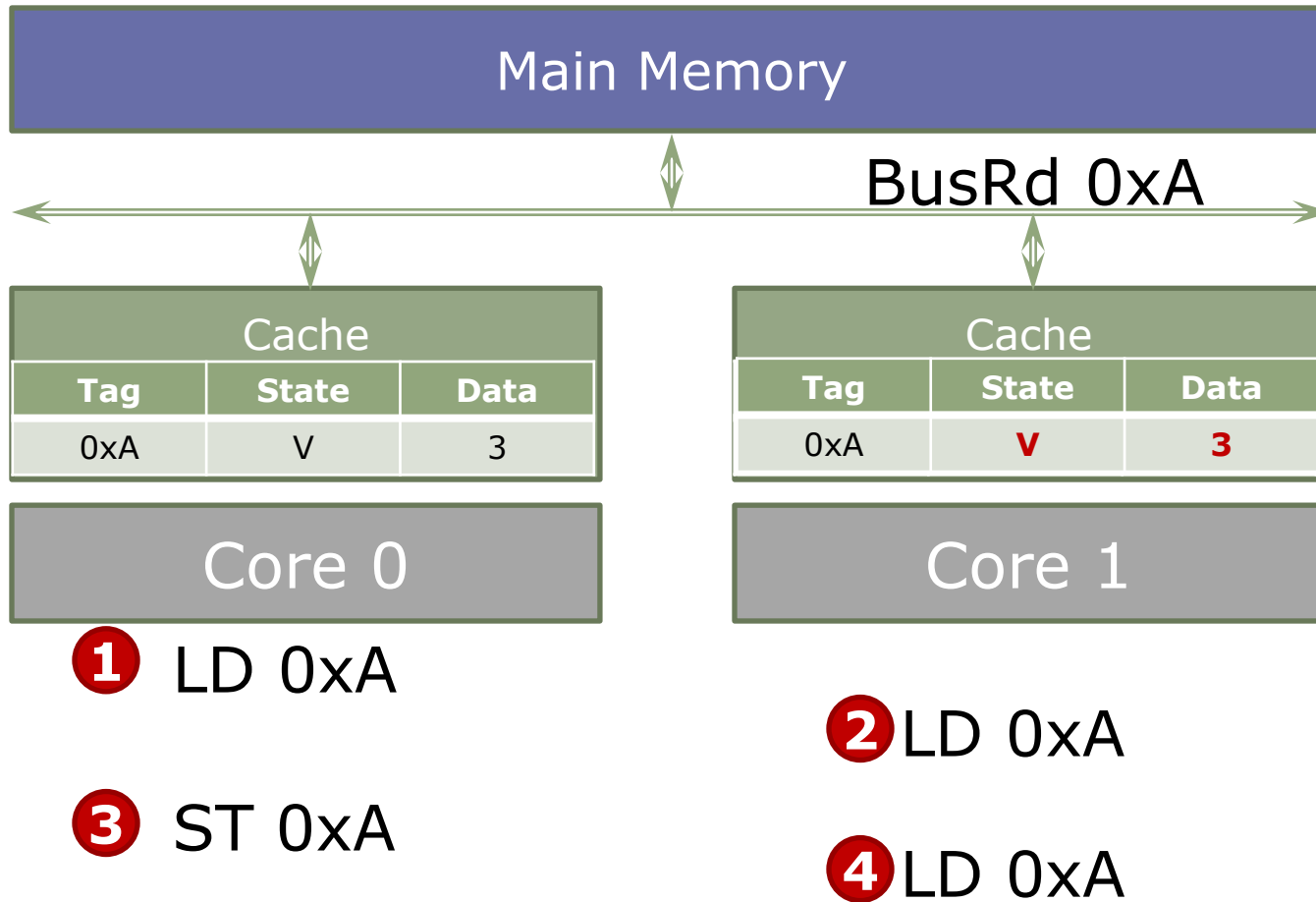


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VI Problems?

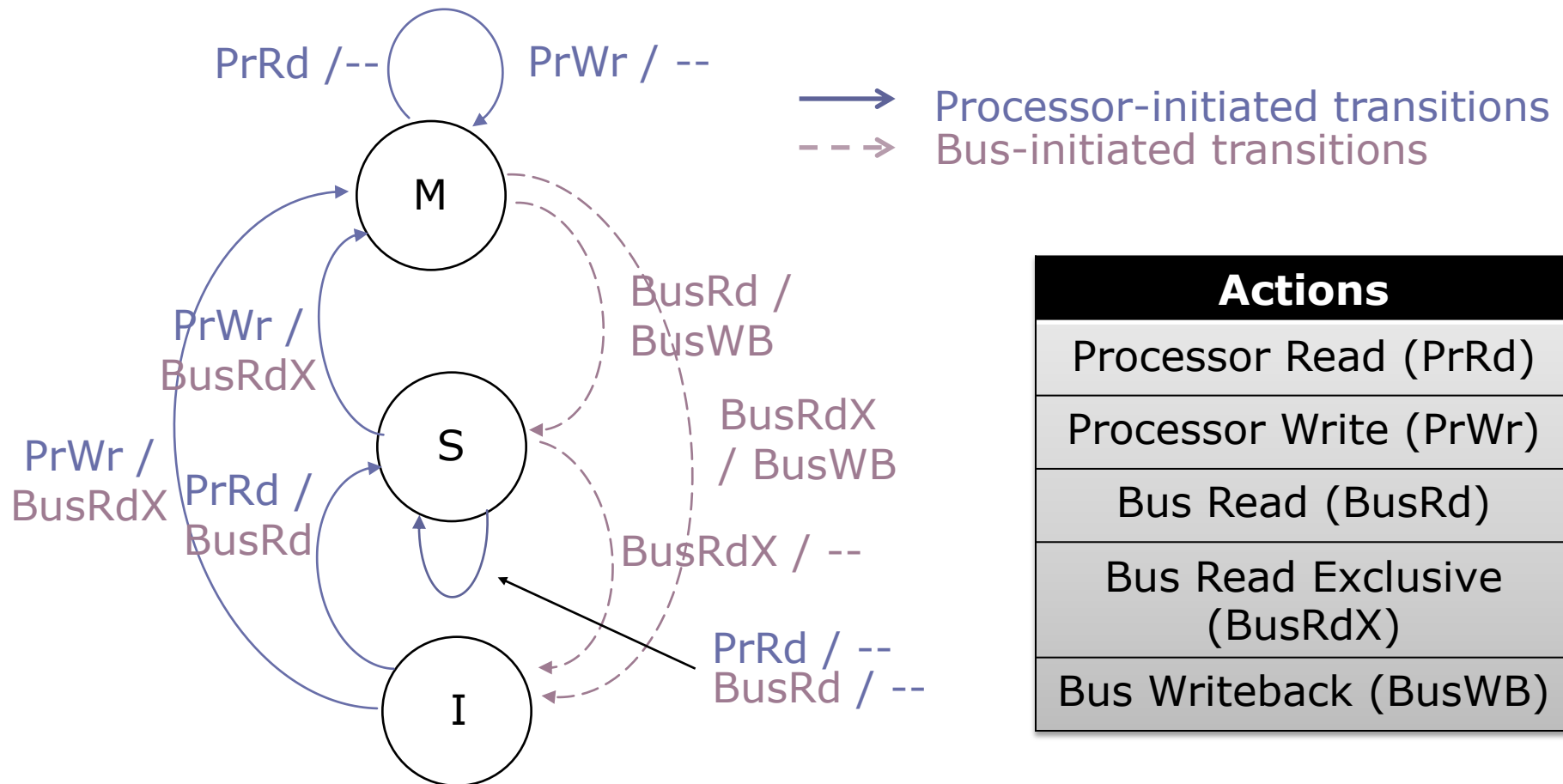
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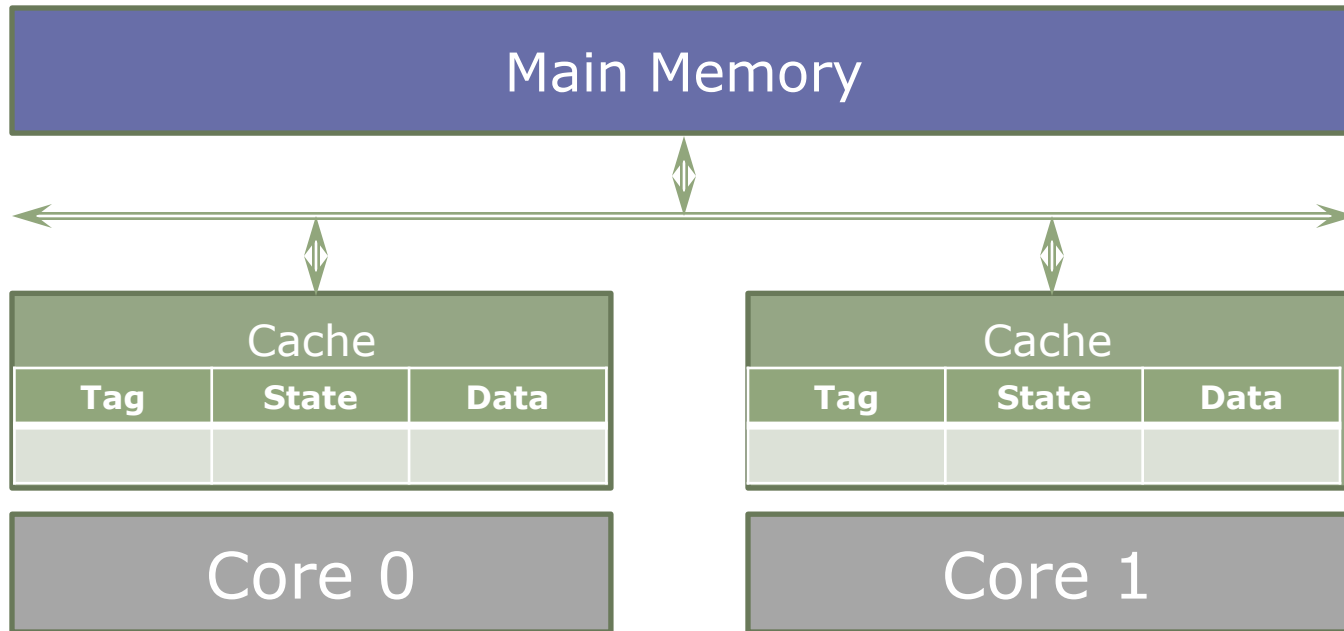
VI Problems? **Every write updates main memory**
Every write requires broadcast & snoop

Modified/Shared/Invalid (MSI) Protocol

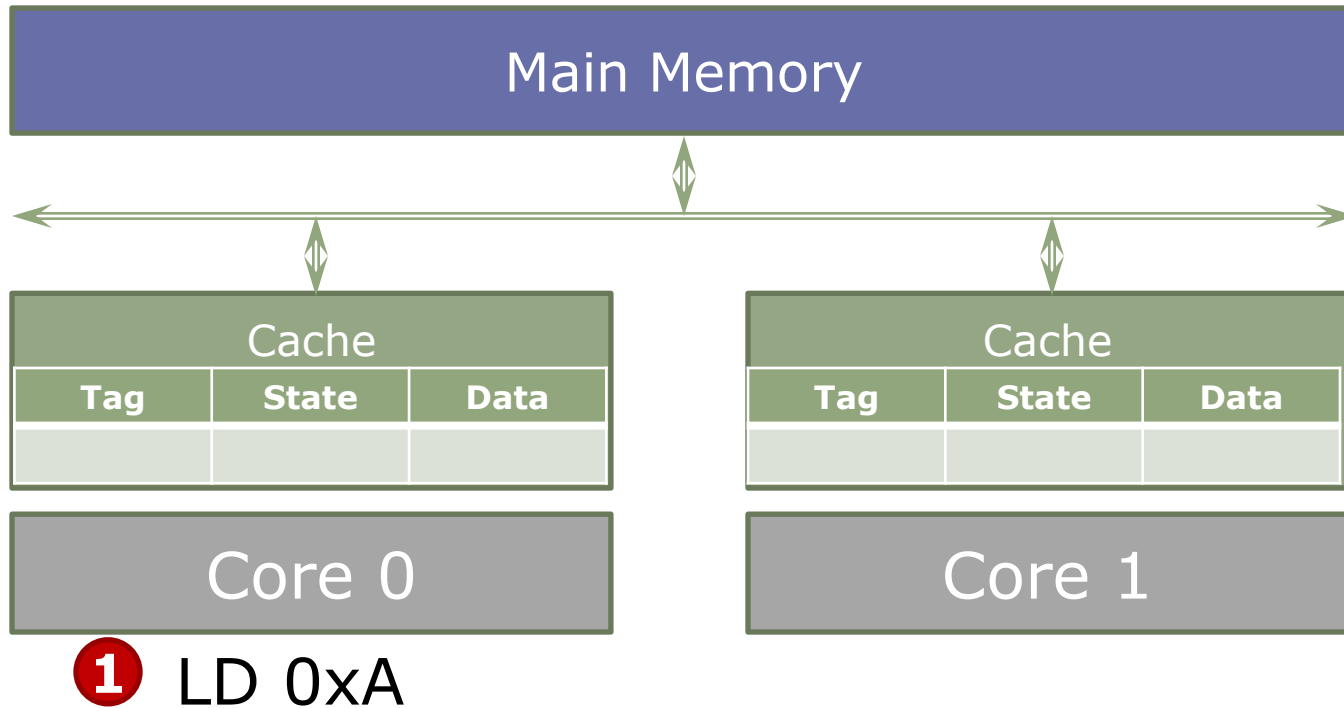
- Allows writeback caches + satisfying writes locally



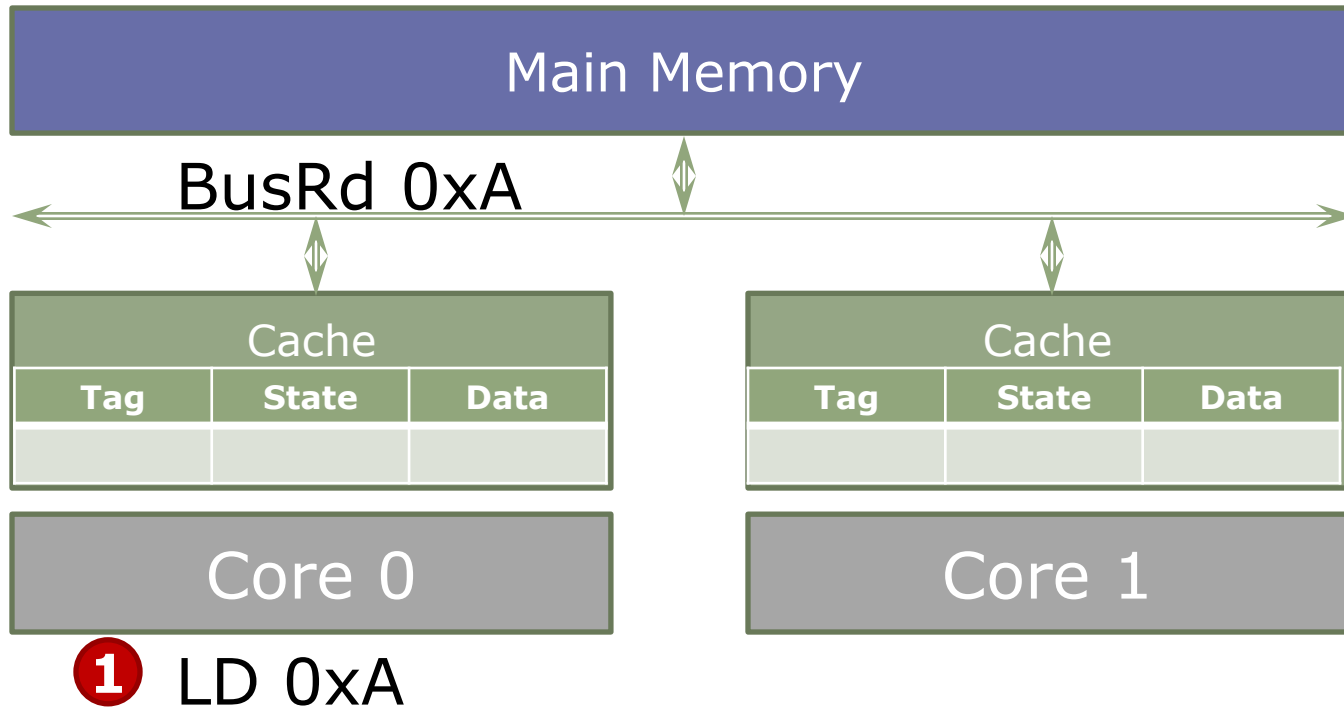
MSI Example



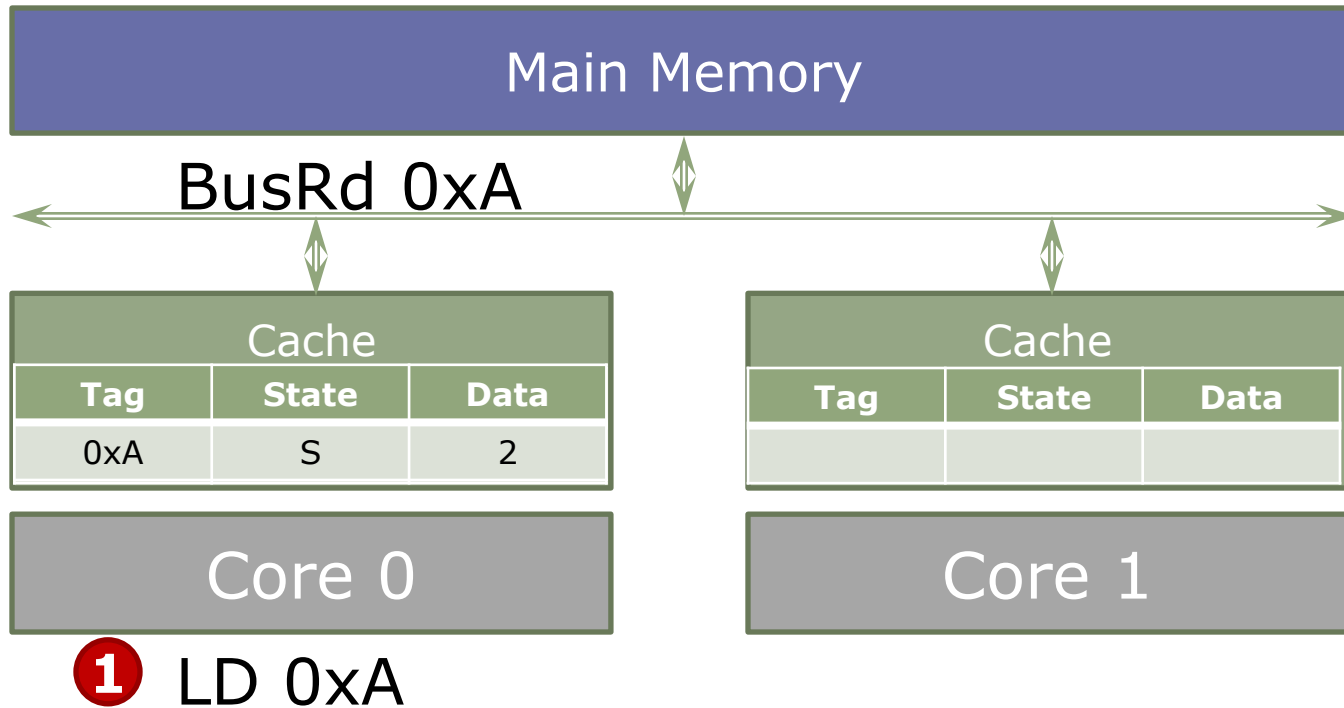
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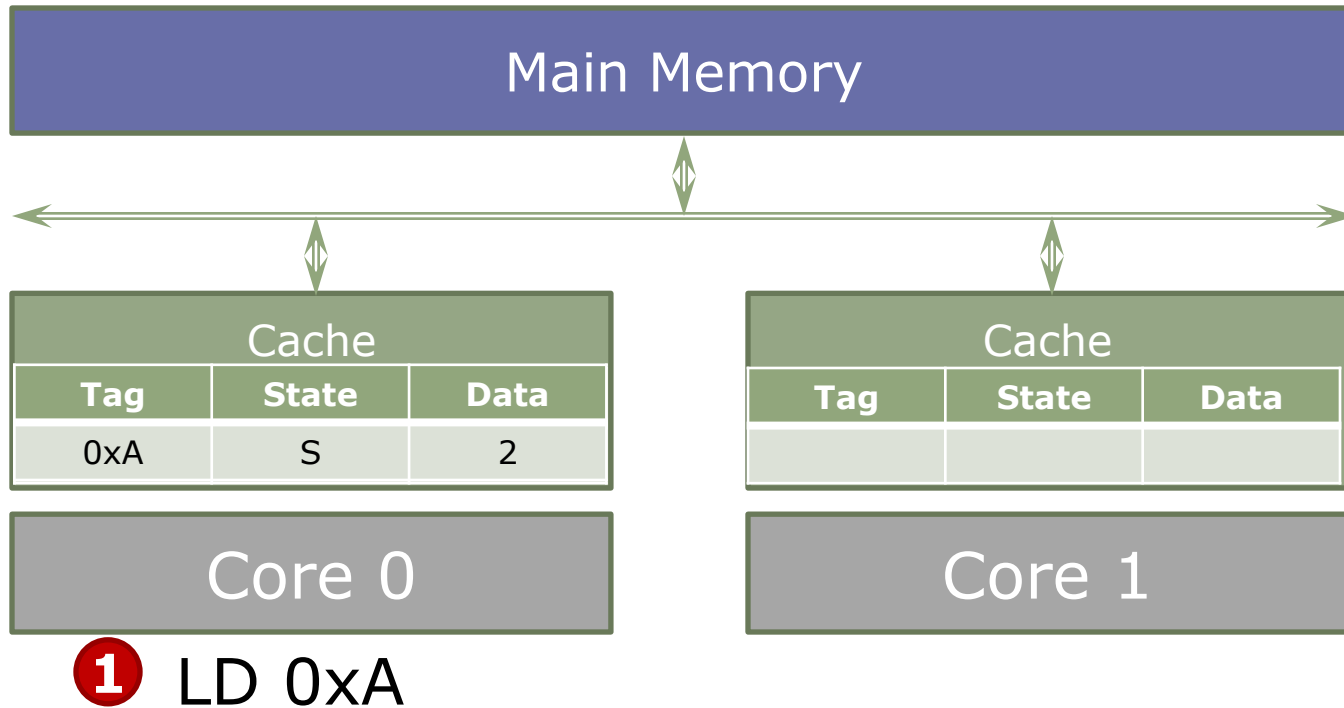
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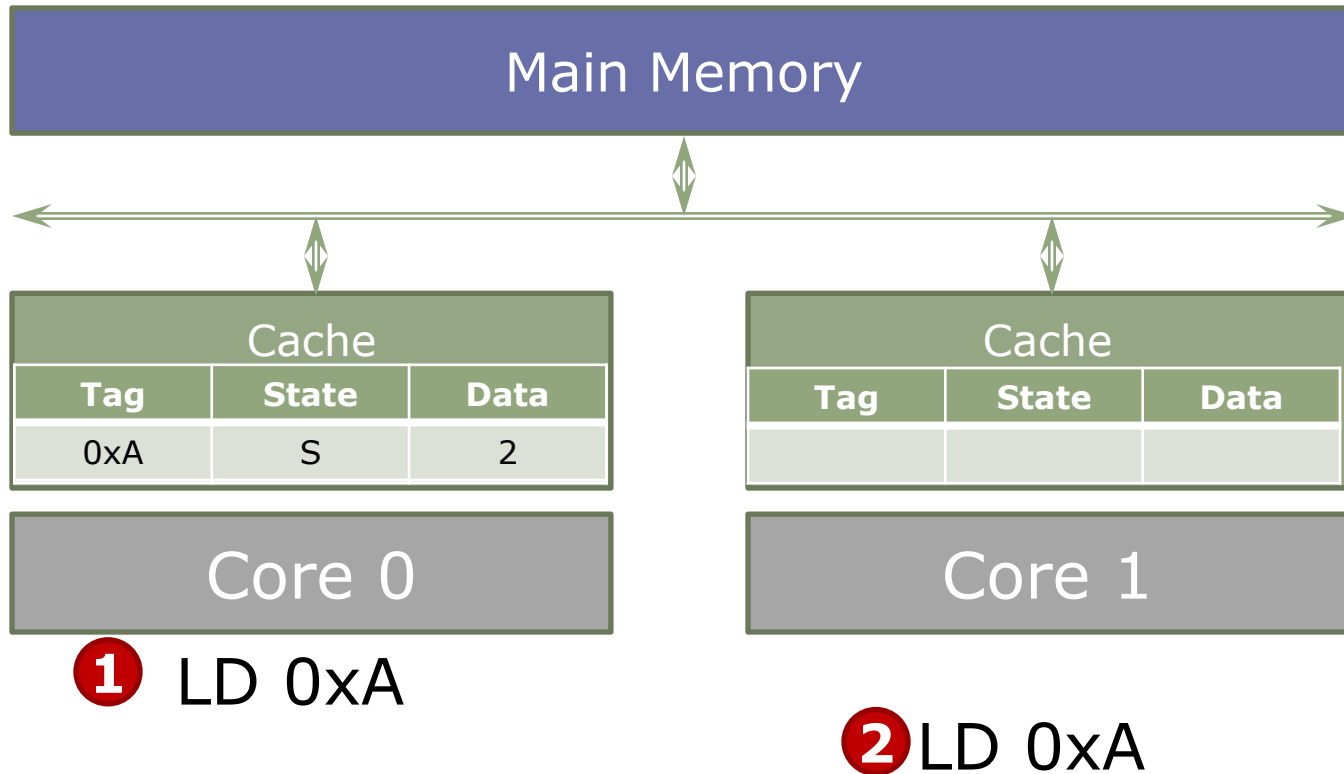
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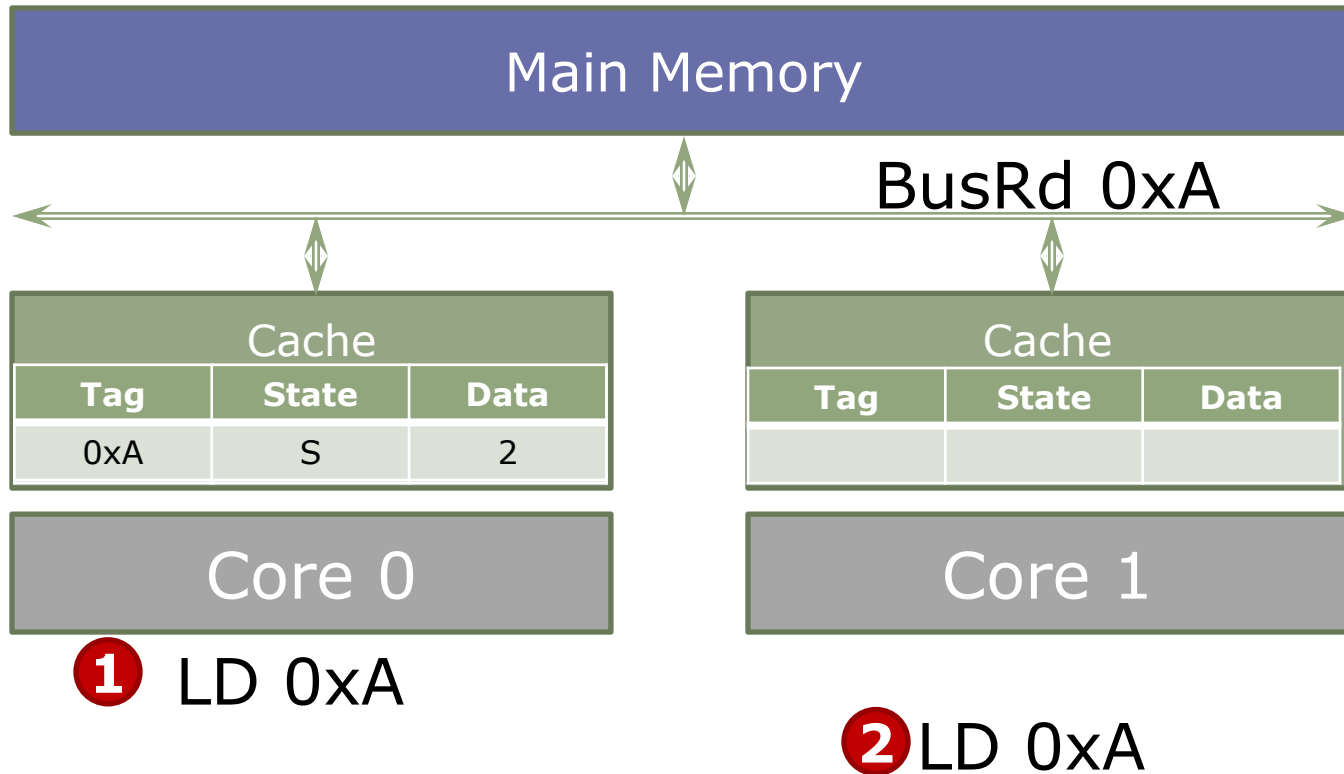
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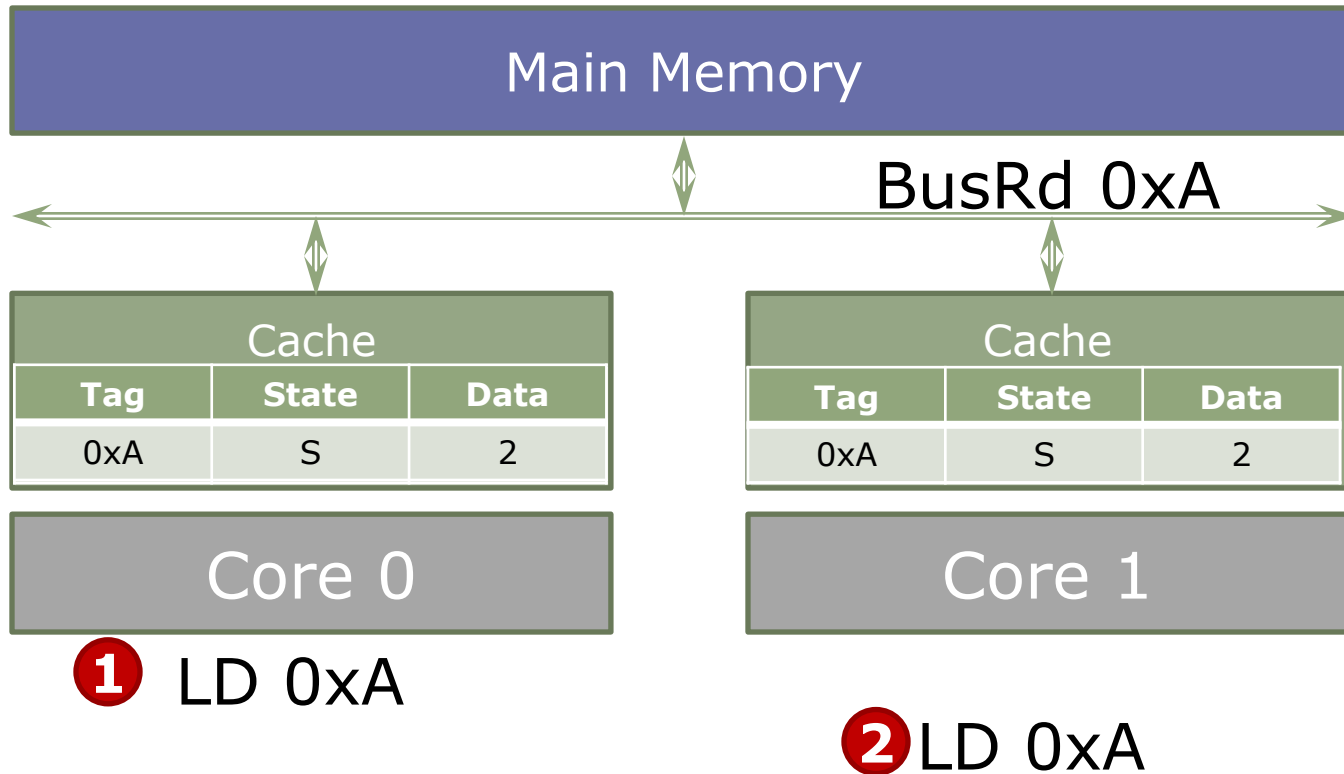
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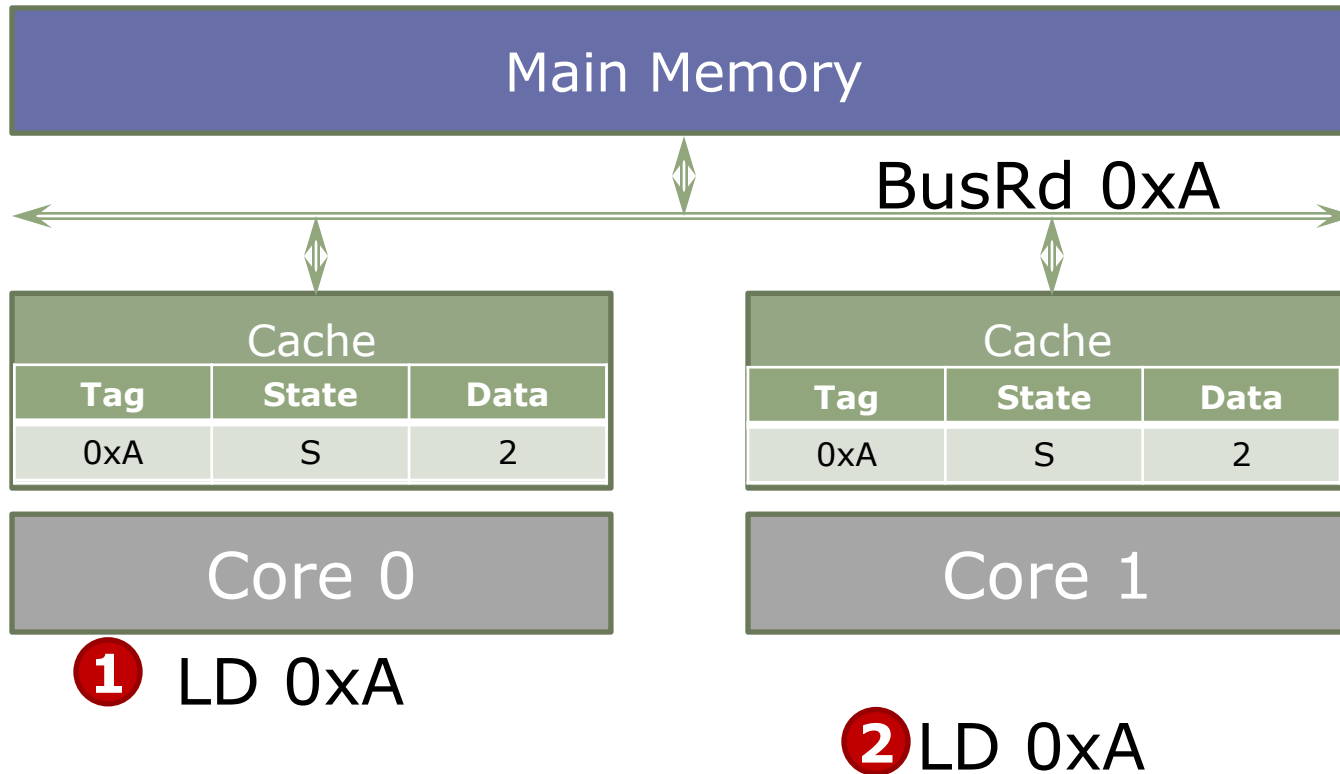
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MSI Example

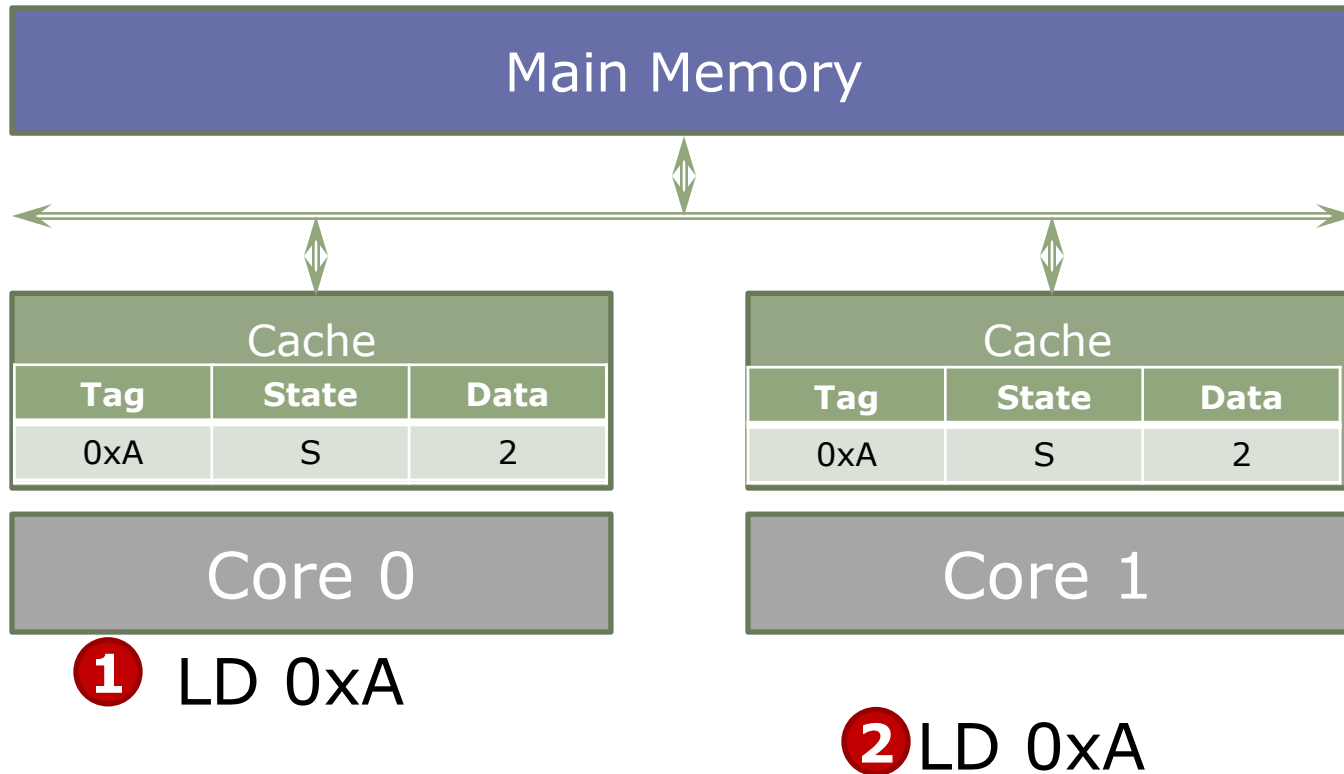


MSI Example

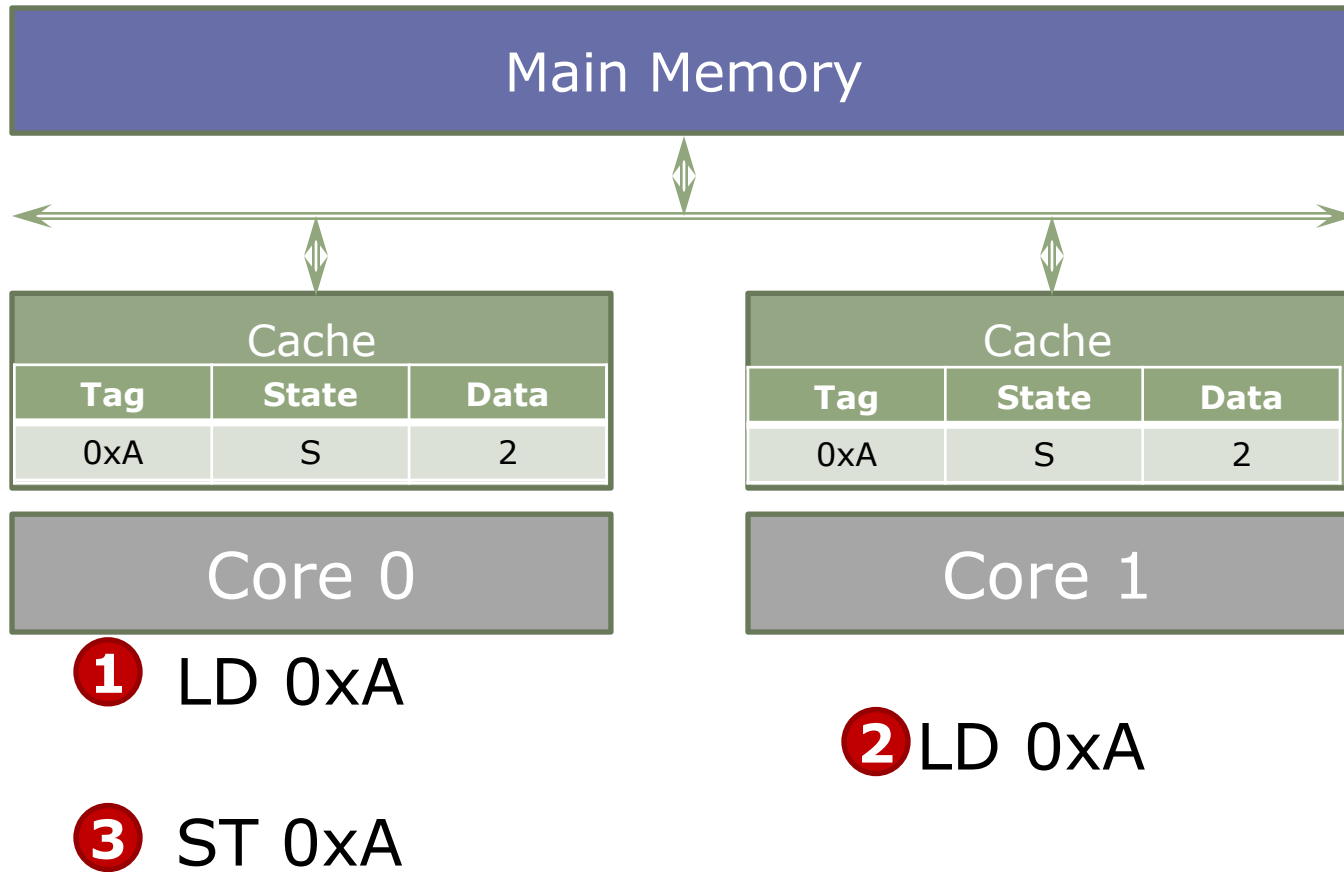


Additional loads satisfied locally, without BusRd
(like in VI)

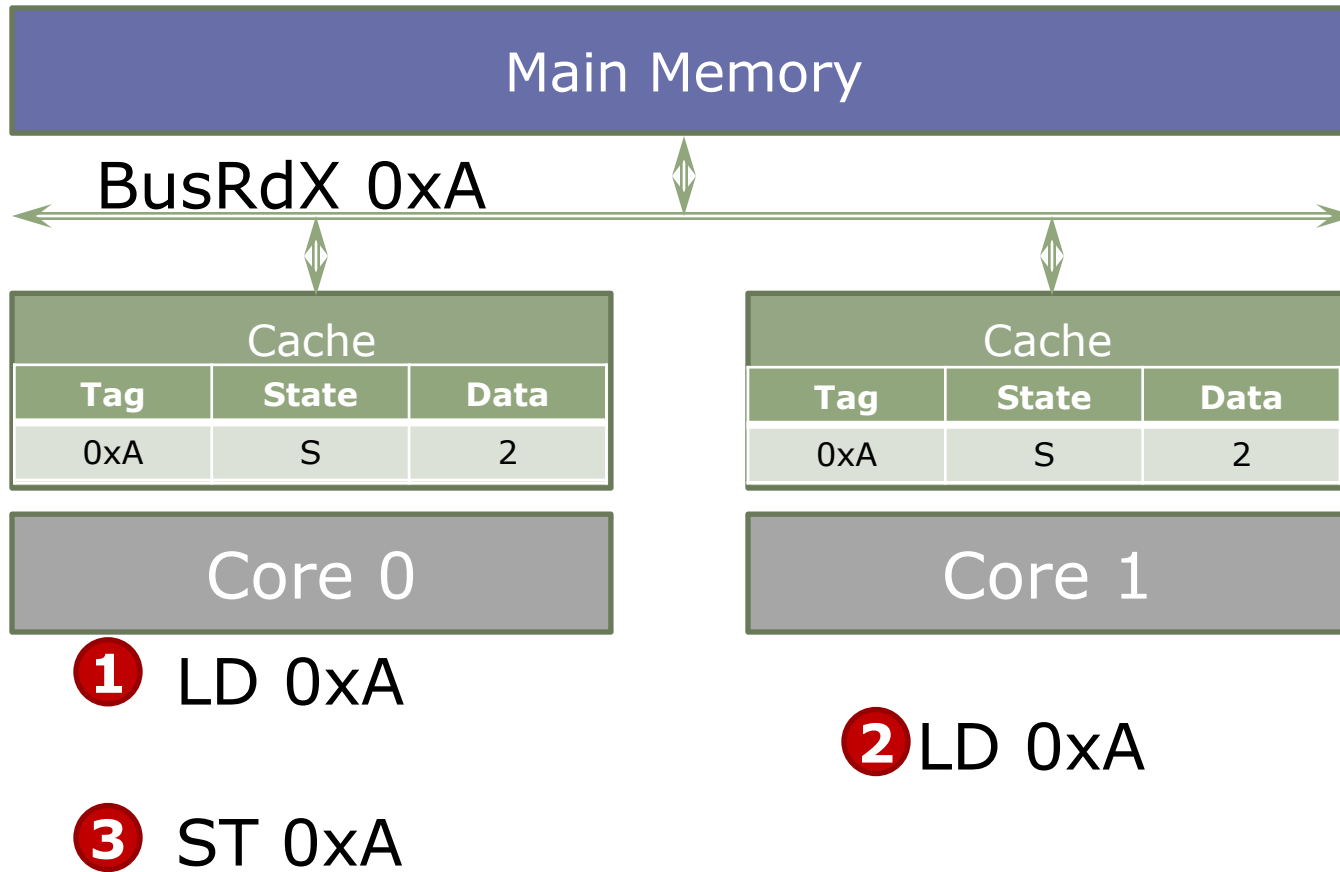
MSI Example



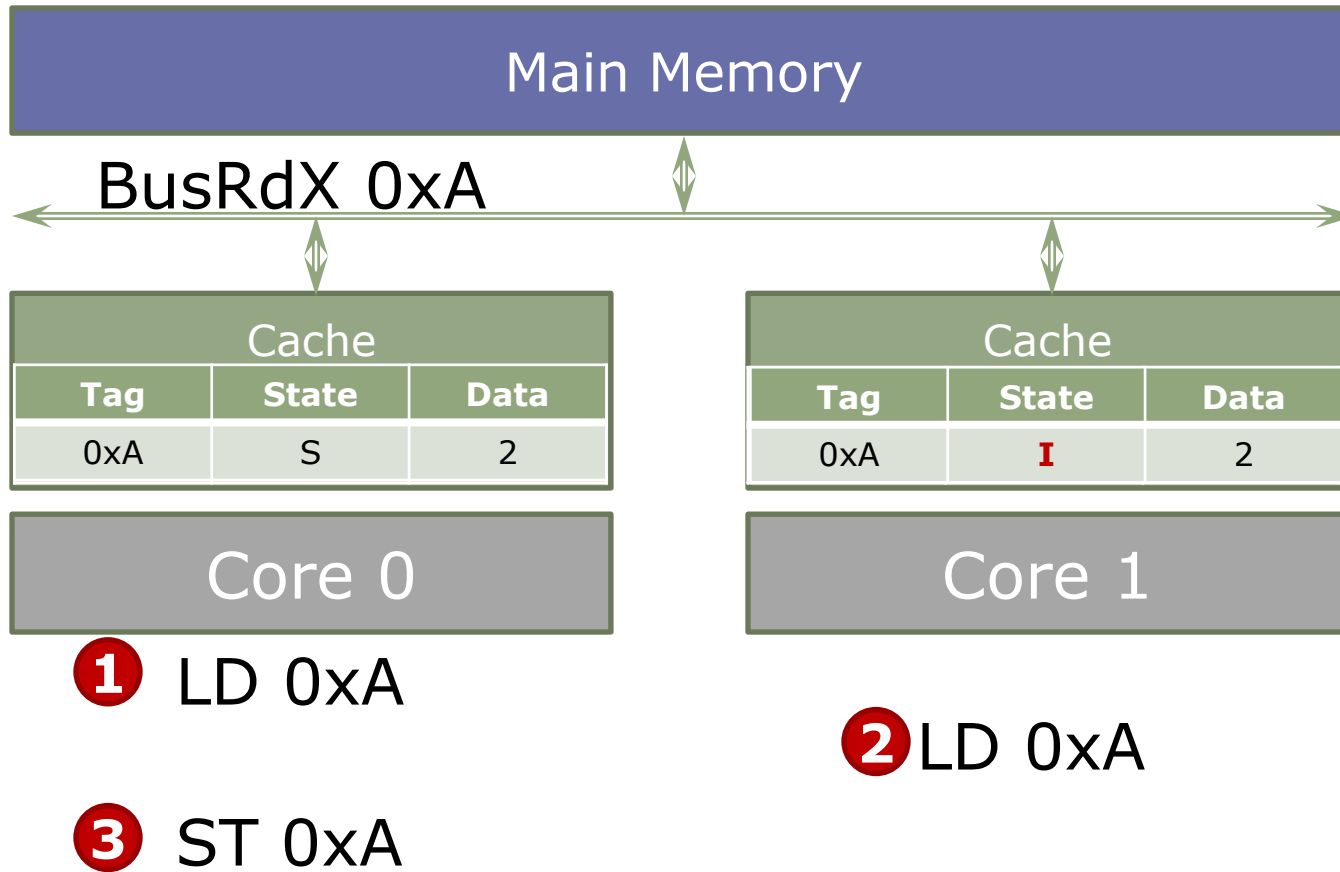
MSI Example



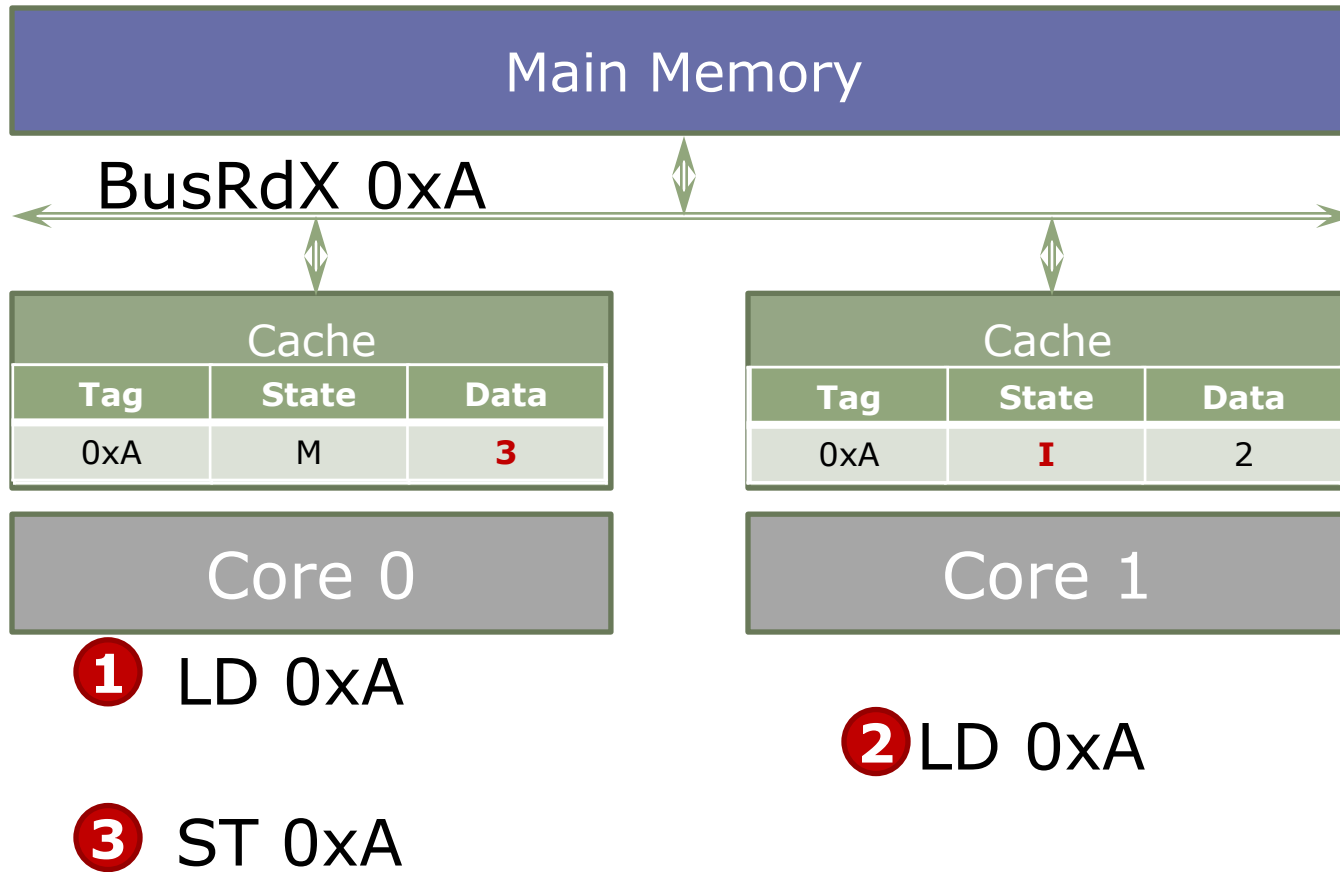
MSI Example



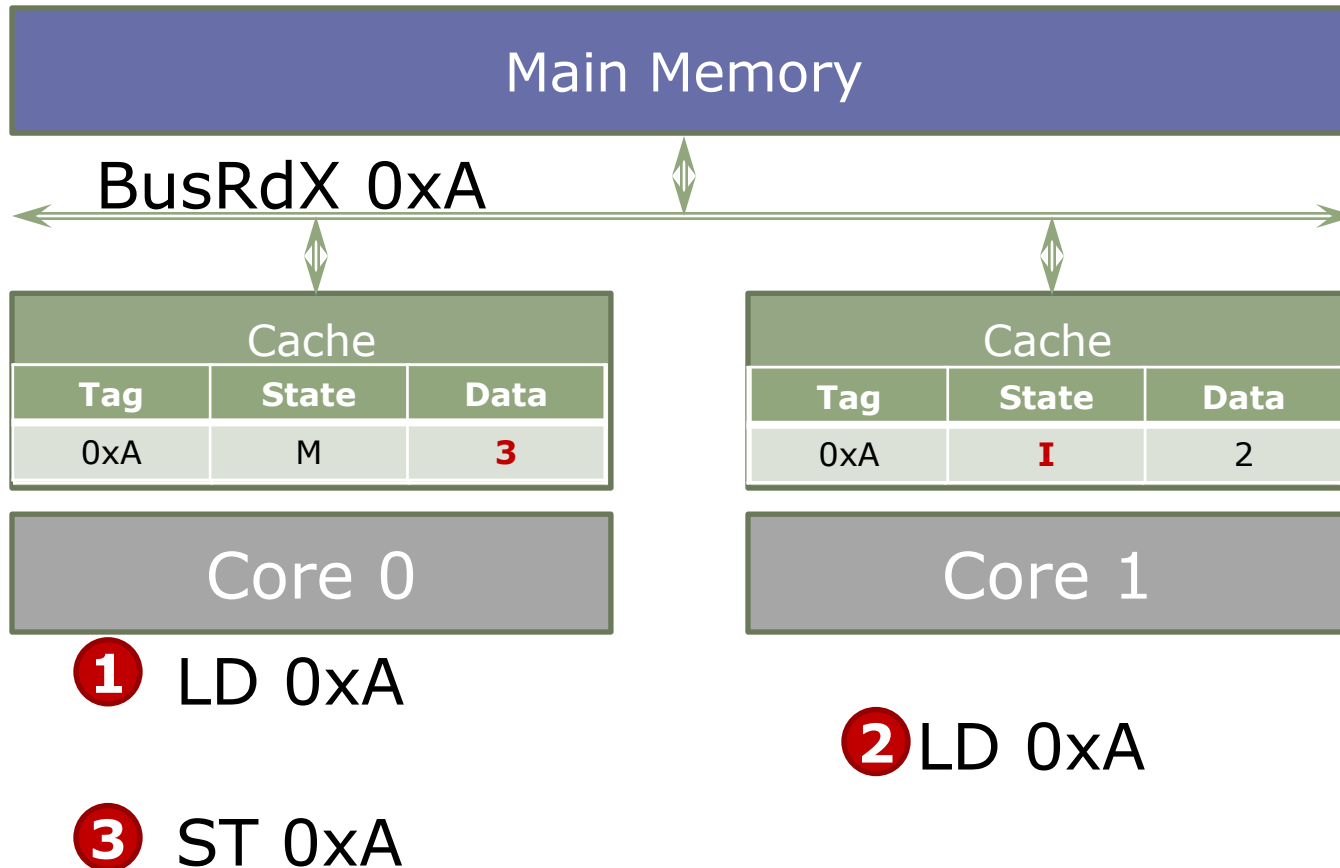
MSI Example



MSI Example

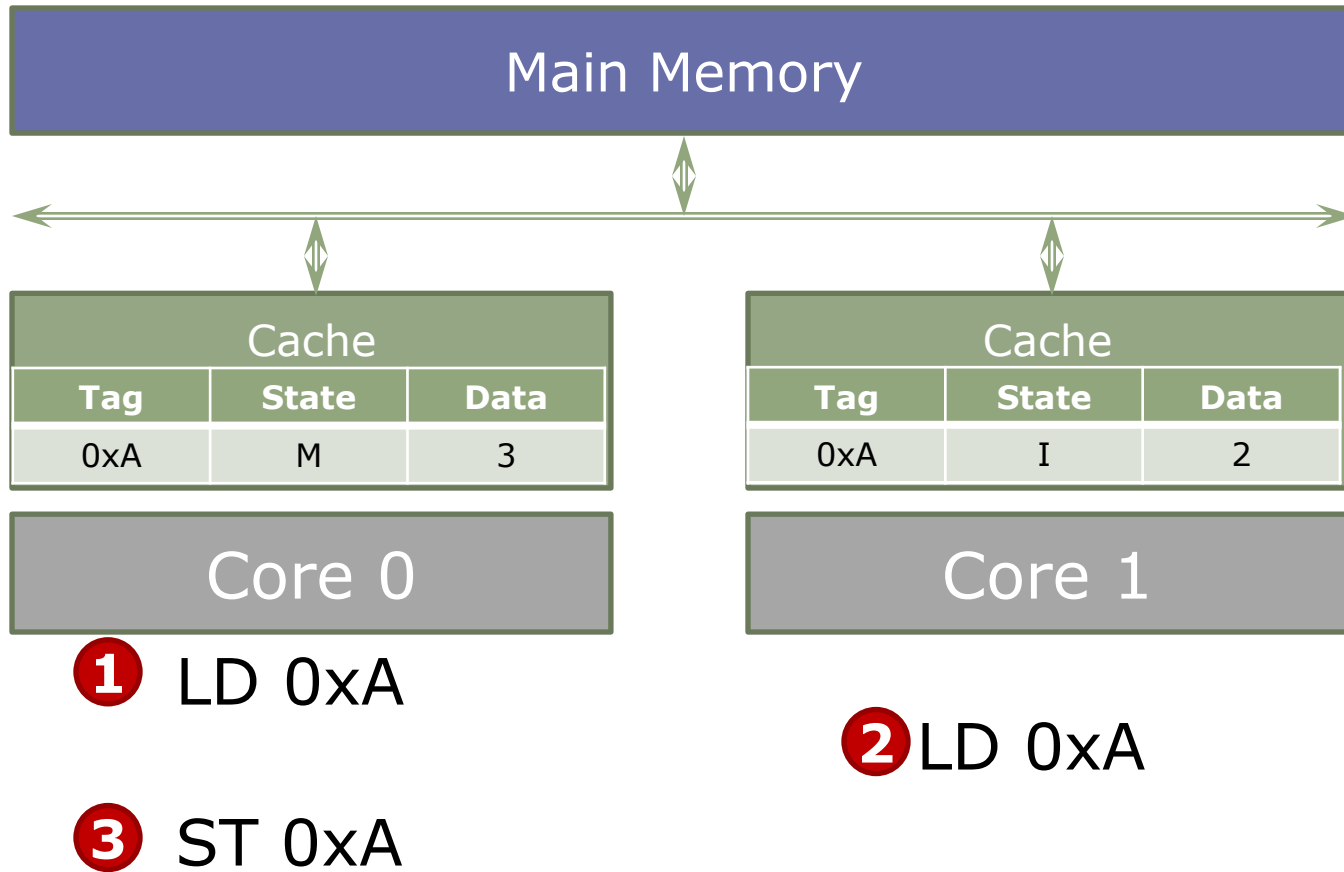


MSI Example

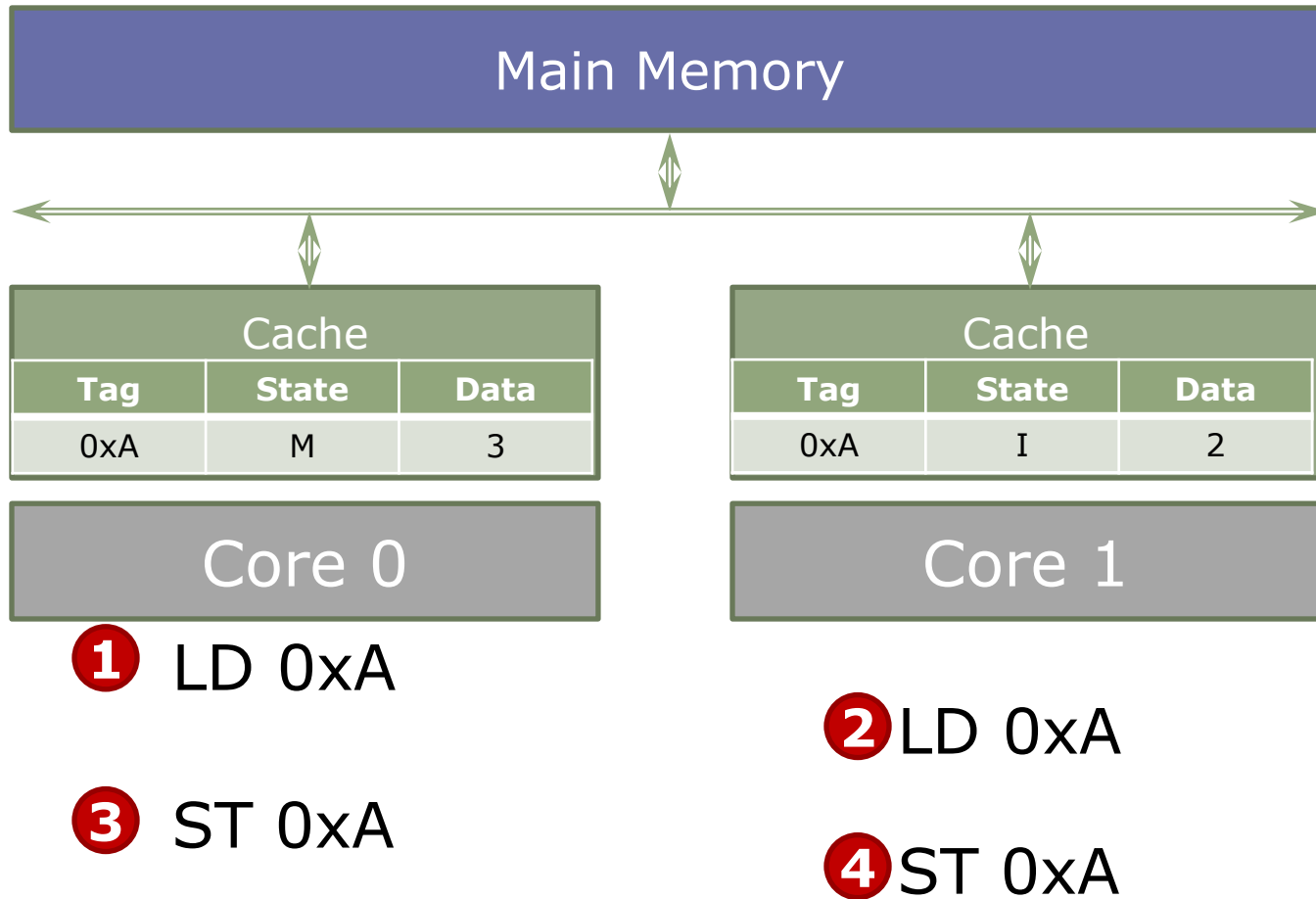


Additional loads *and* stores from core 0 satisfied locally, without bus transactions (unlike in VI)

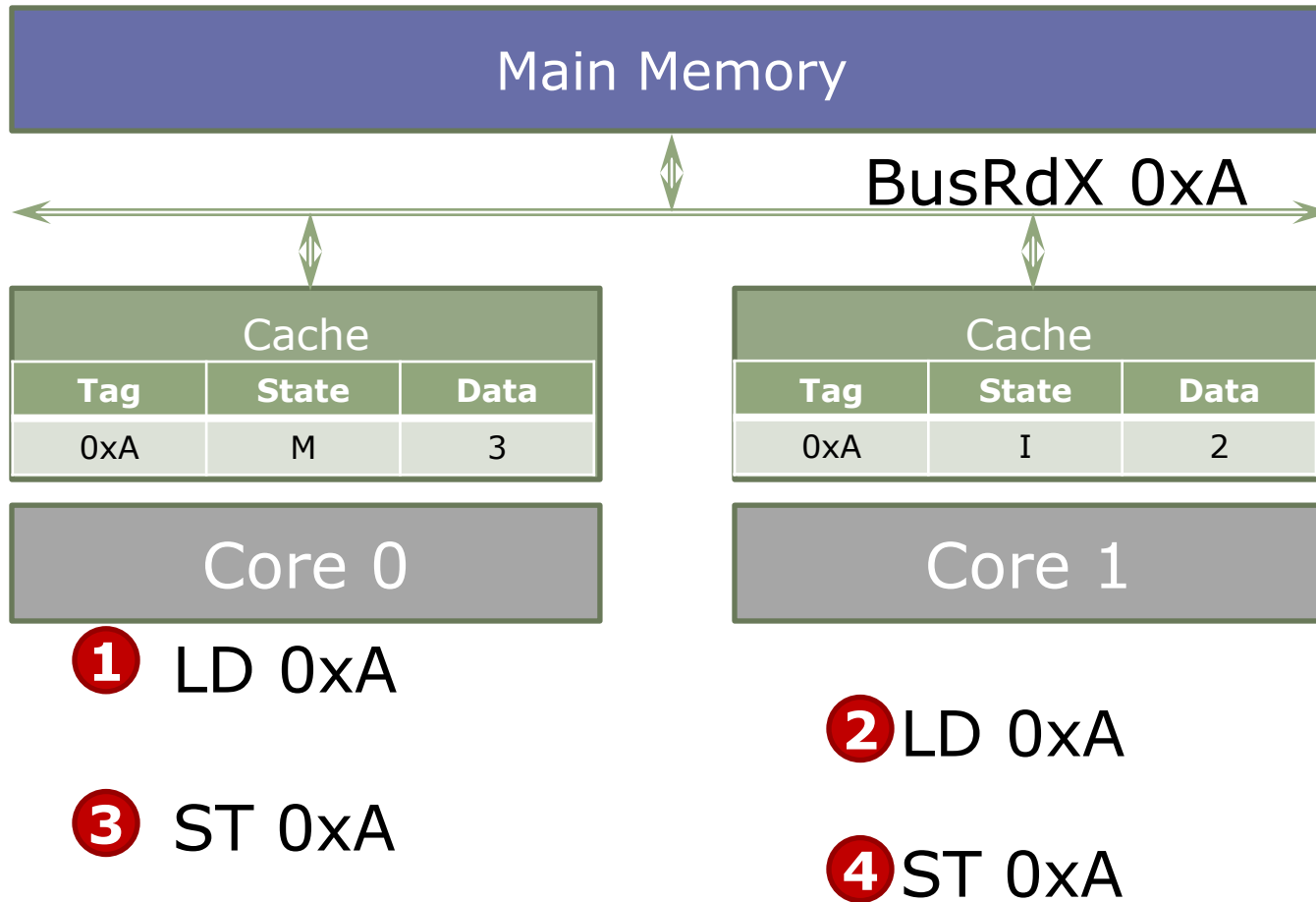
MSI Example



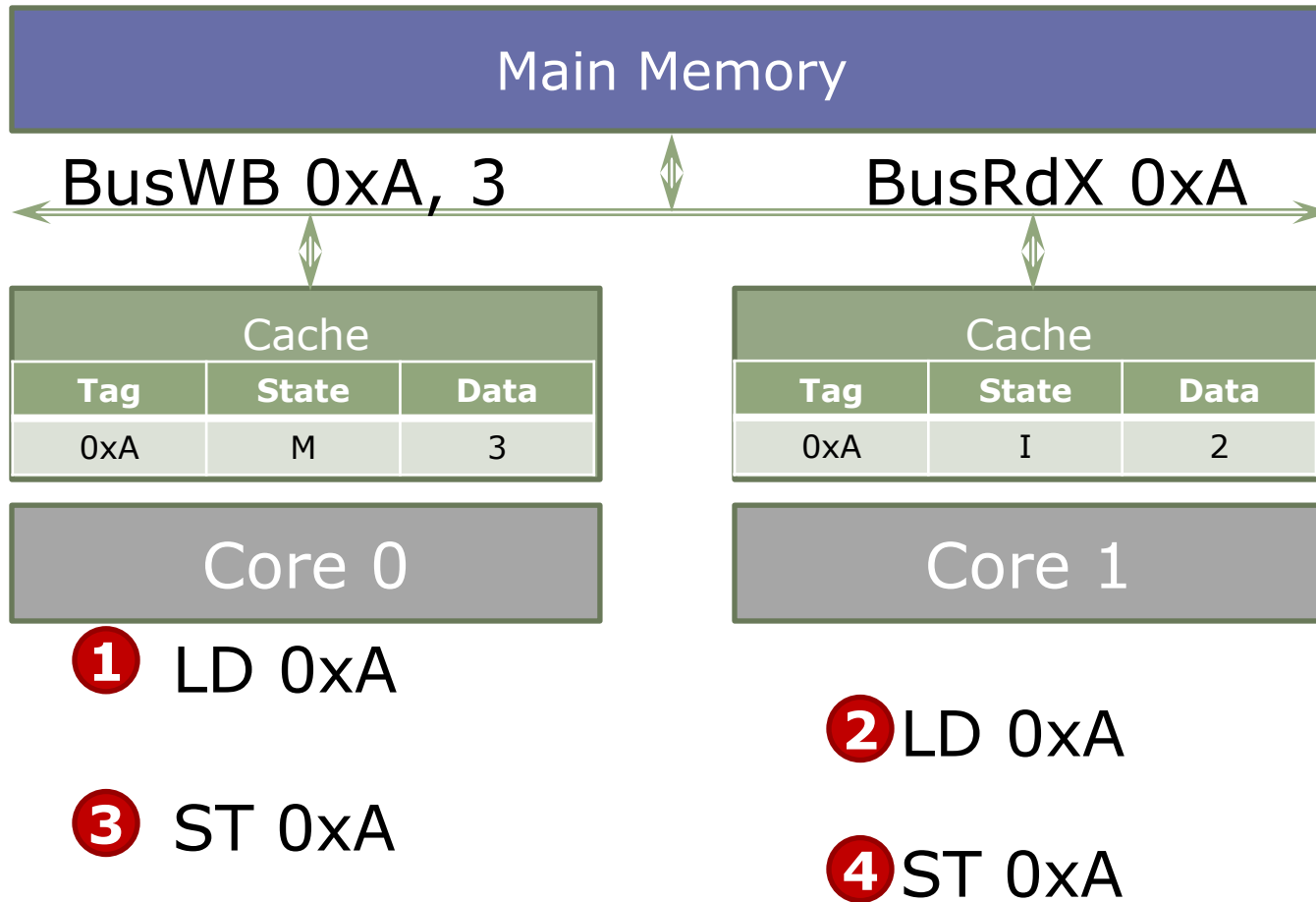
MSI Example



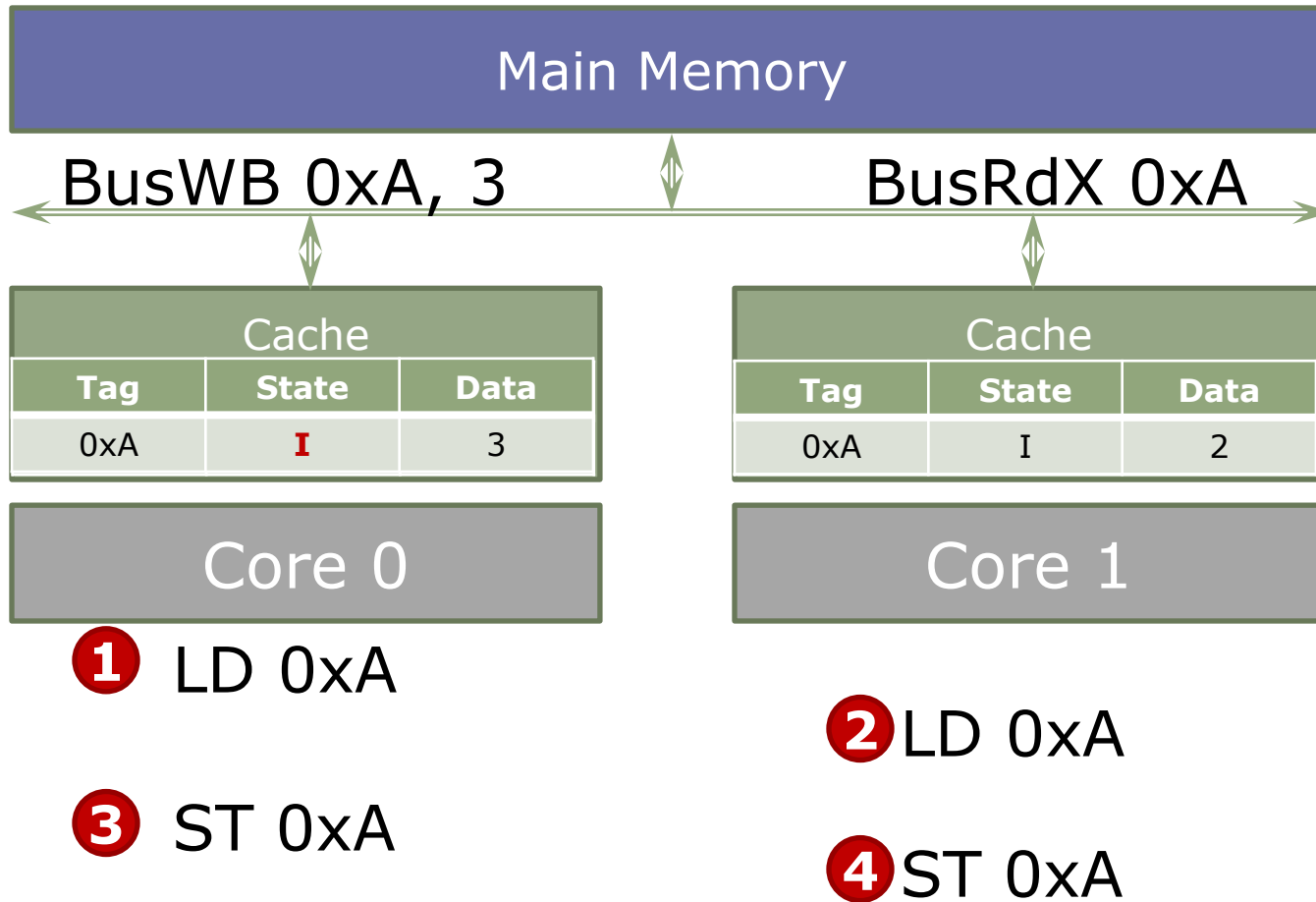
MSI Example



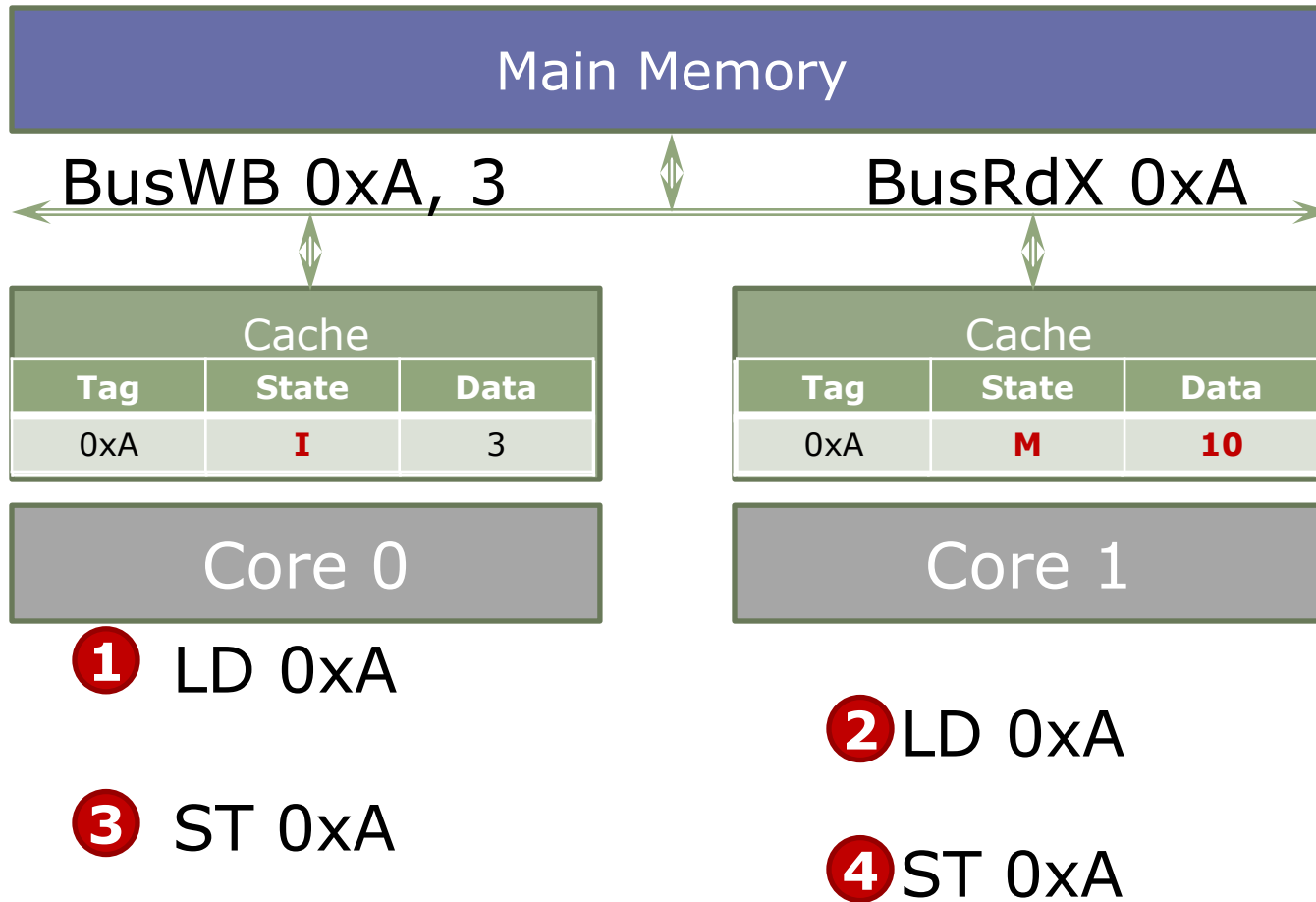
MSI Example



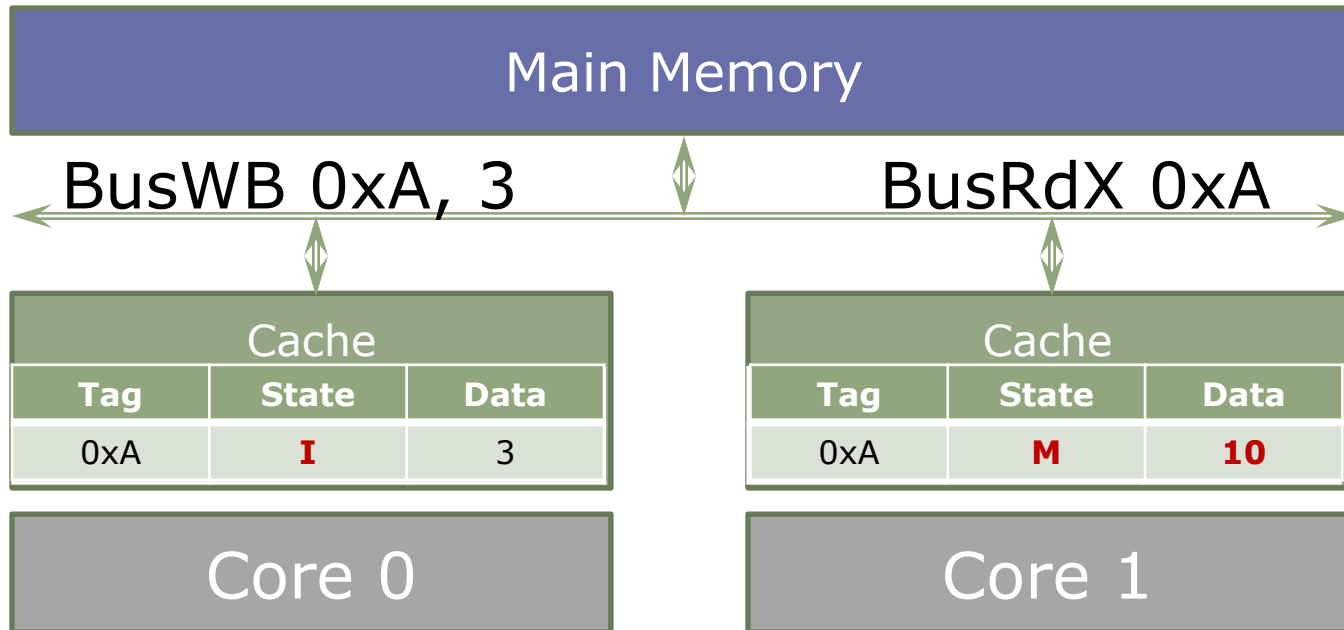
MSI Example



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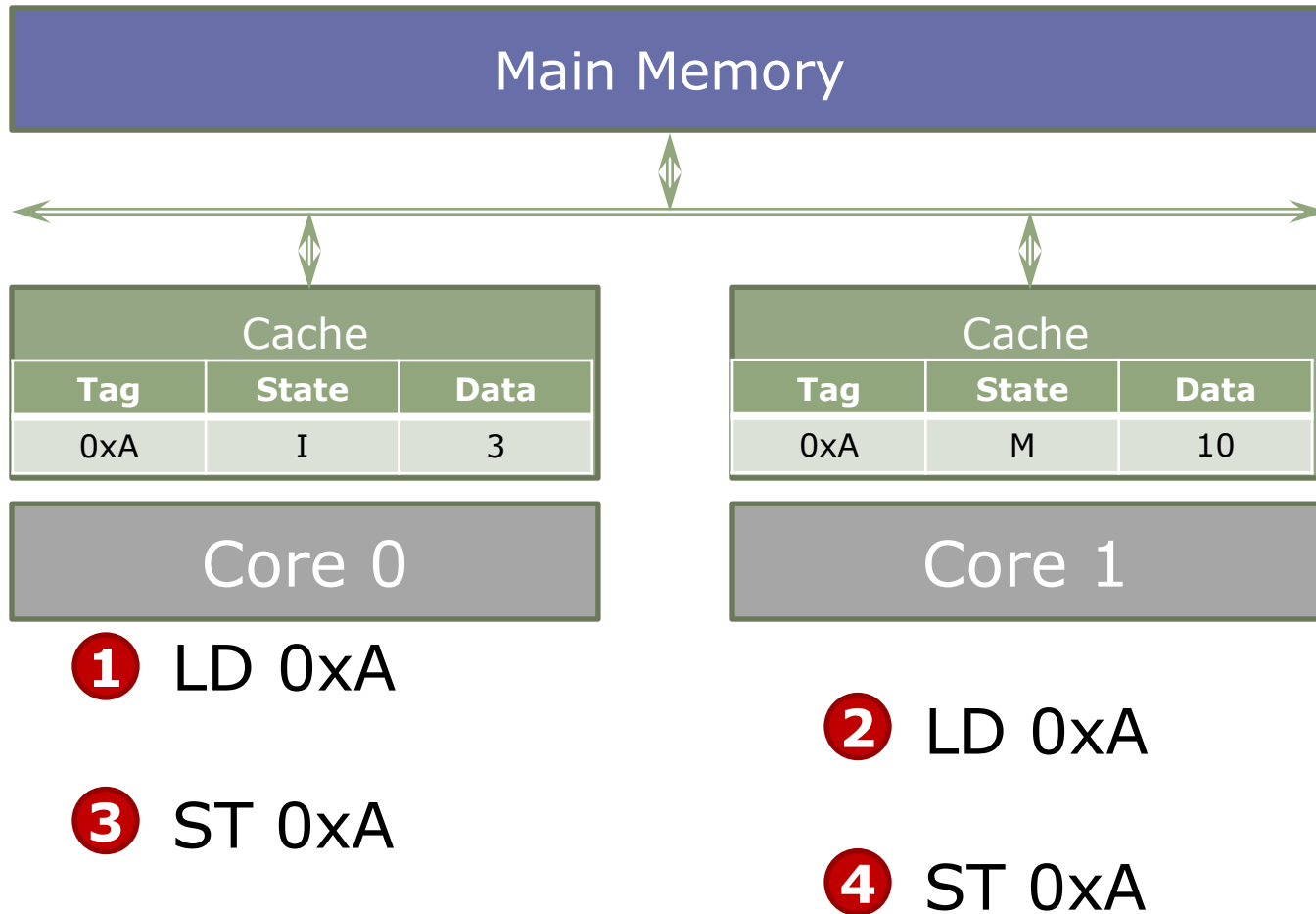


Cache interventions

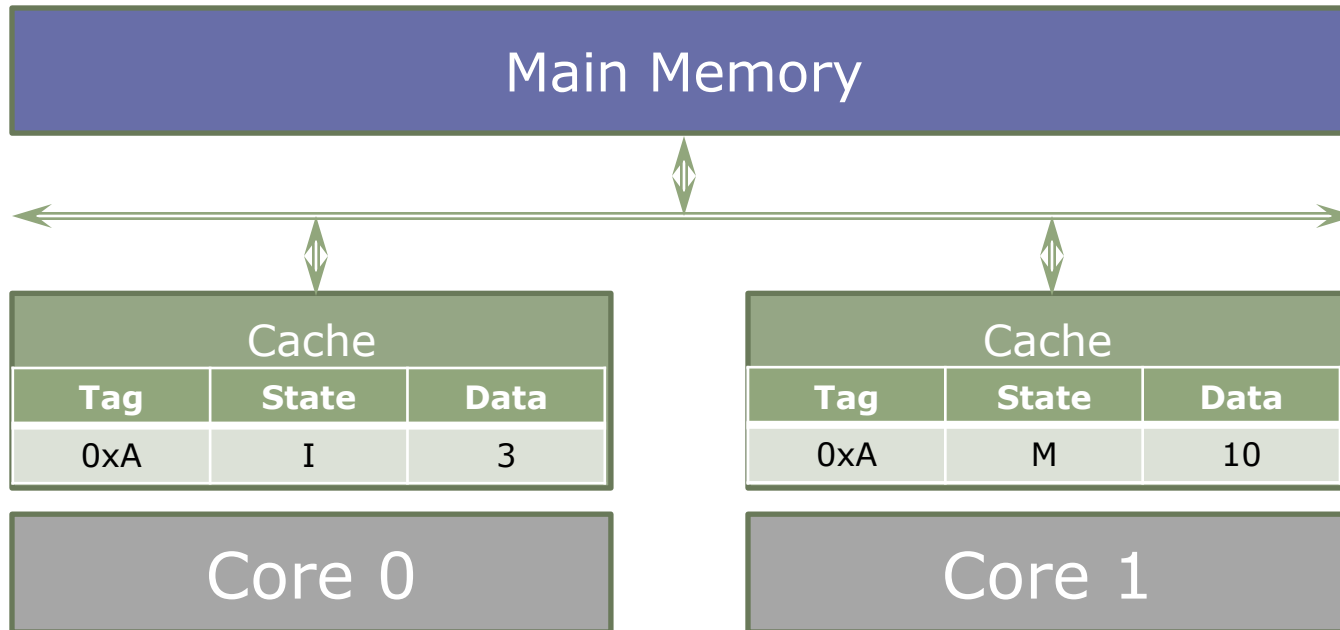


- MSI allows caches to serve writes without updating memory, so main memory can have stale data
 - Core 0's cache needs to supply data
 - But main memory may also respond!
- Cache must override response from main memory

MSI Example



MSI Example



1 LD 0xA

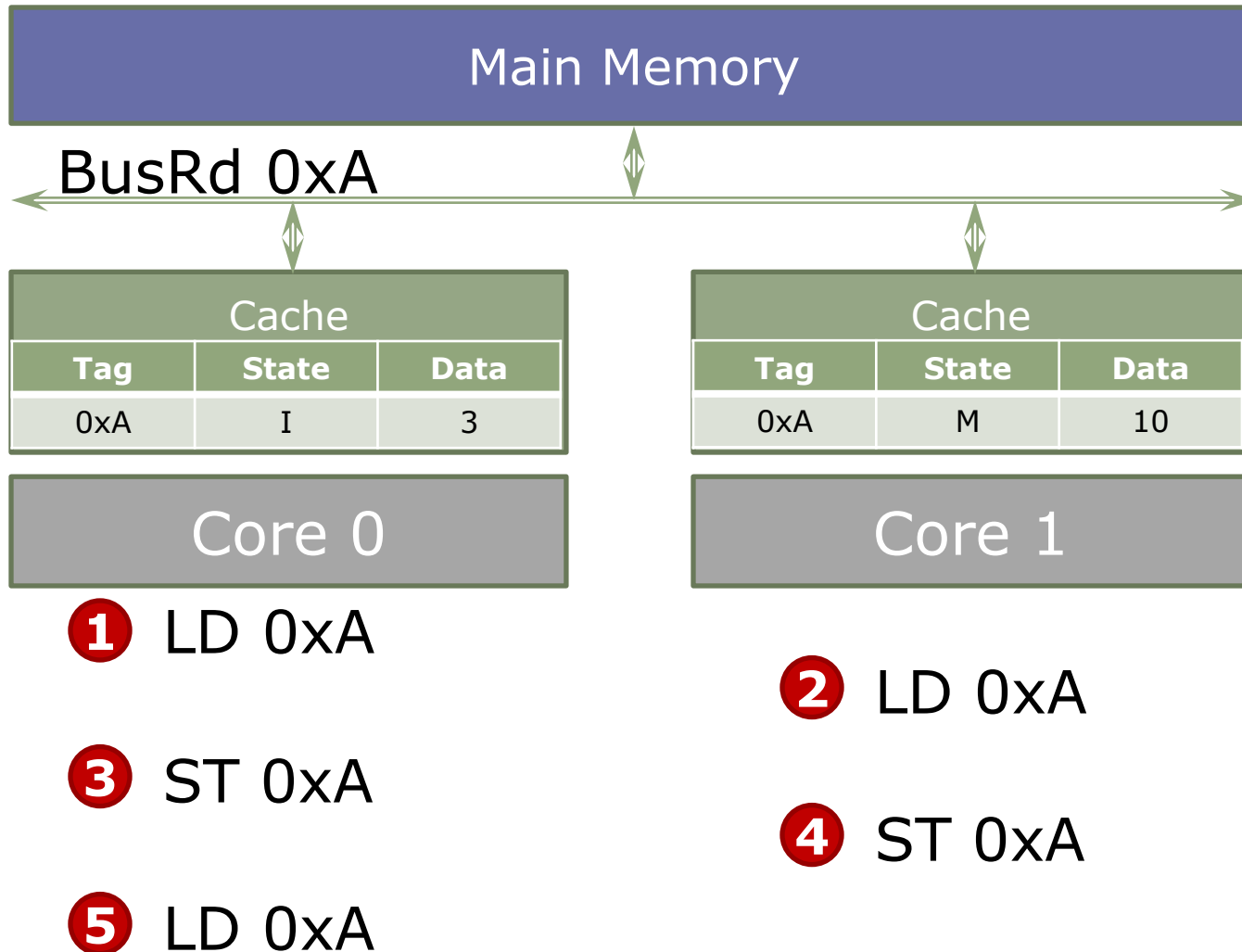
2 LD 0xA

3 ST 0xA

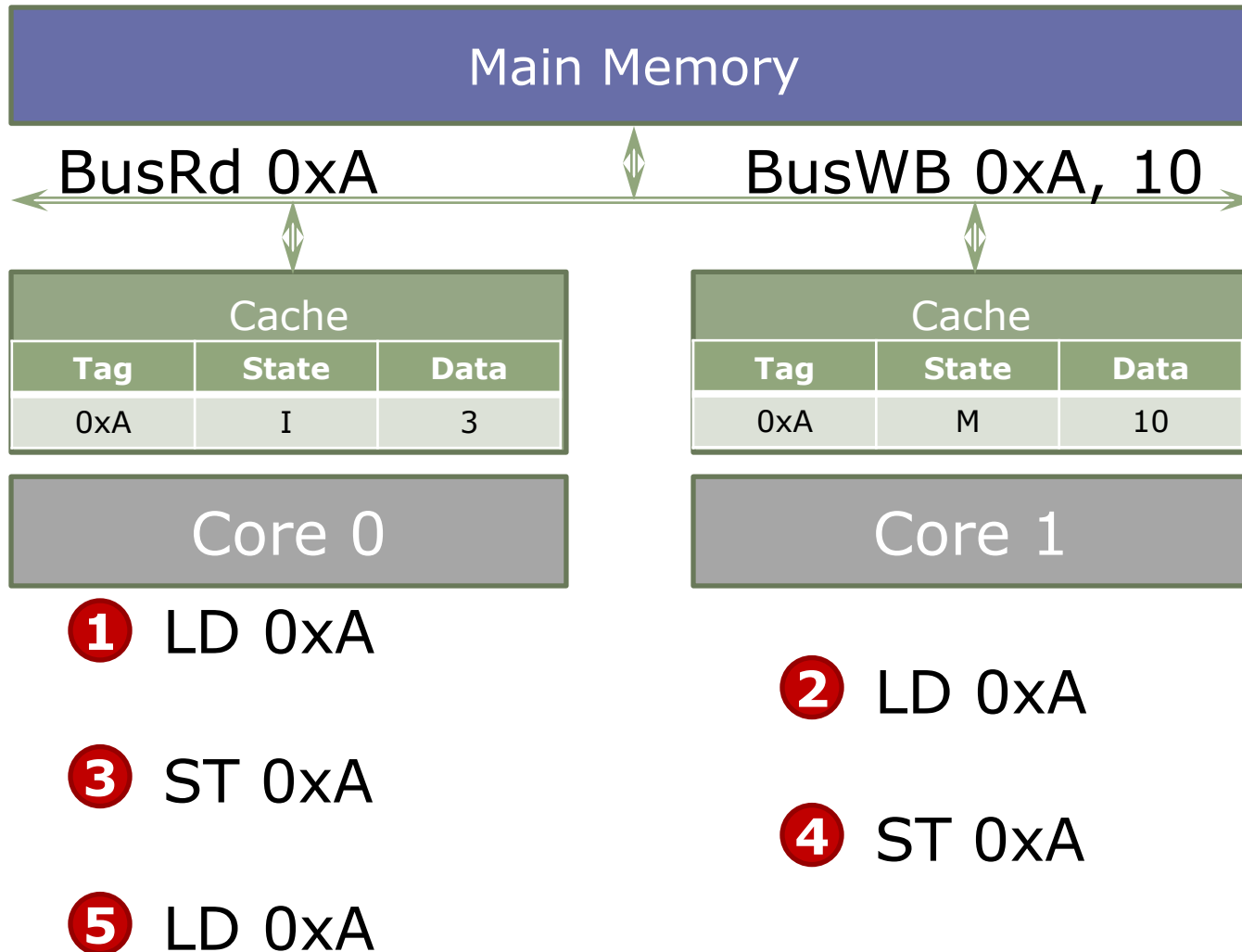
4 ST 0xA

5 LD 0xA

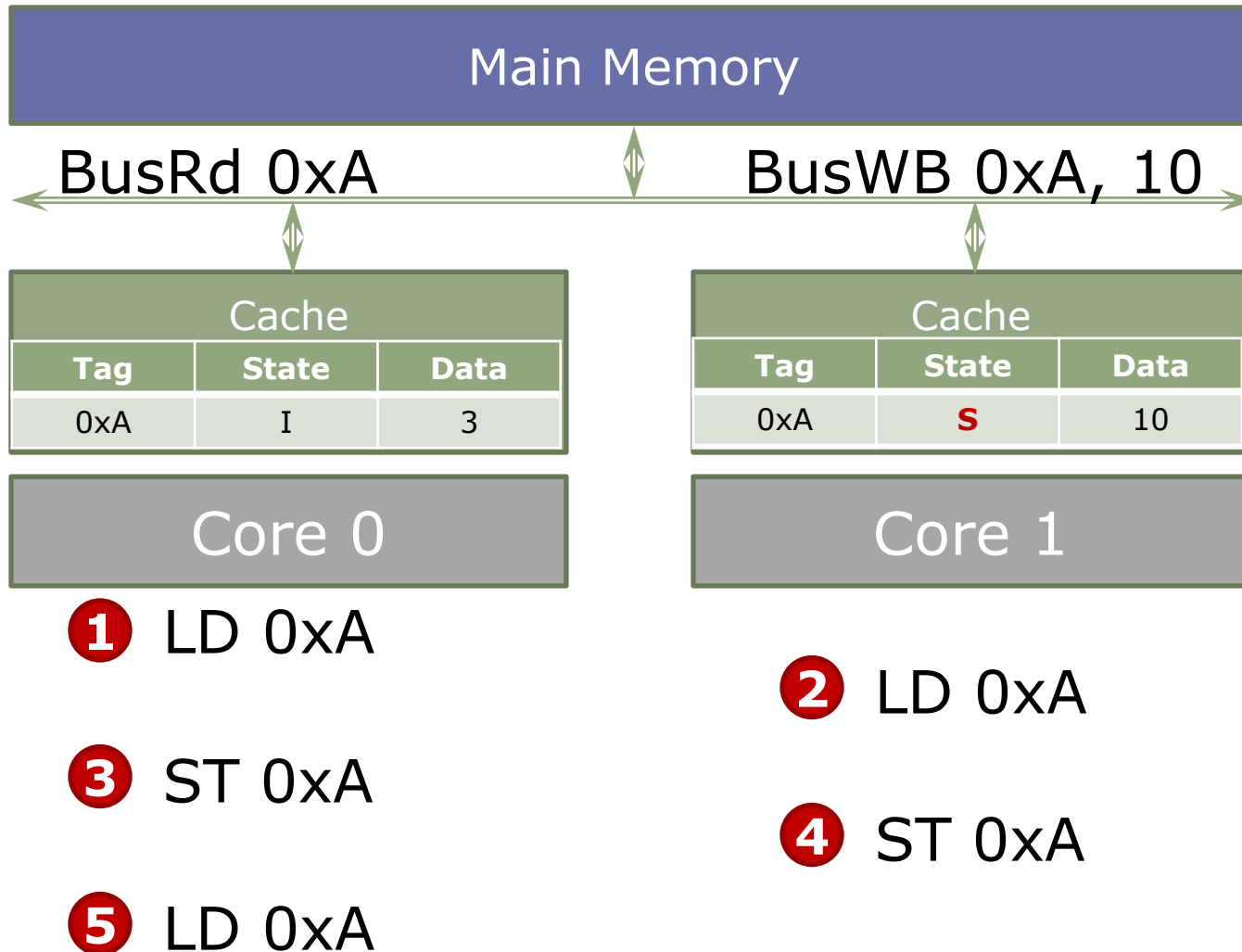
MSI Example



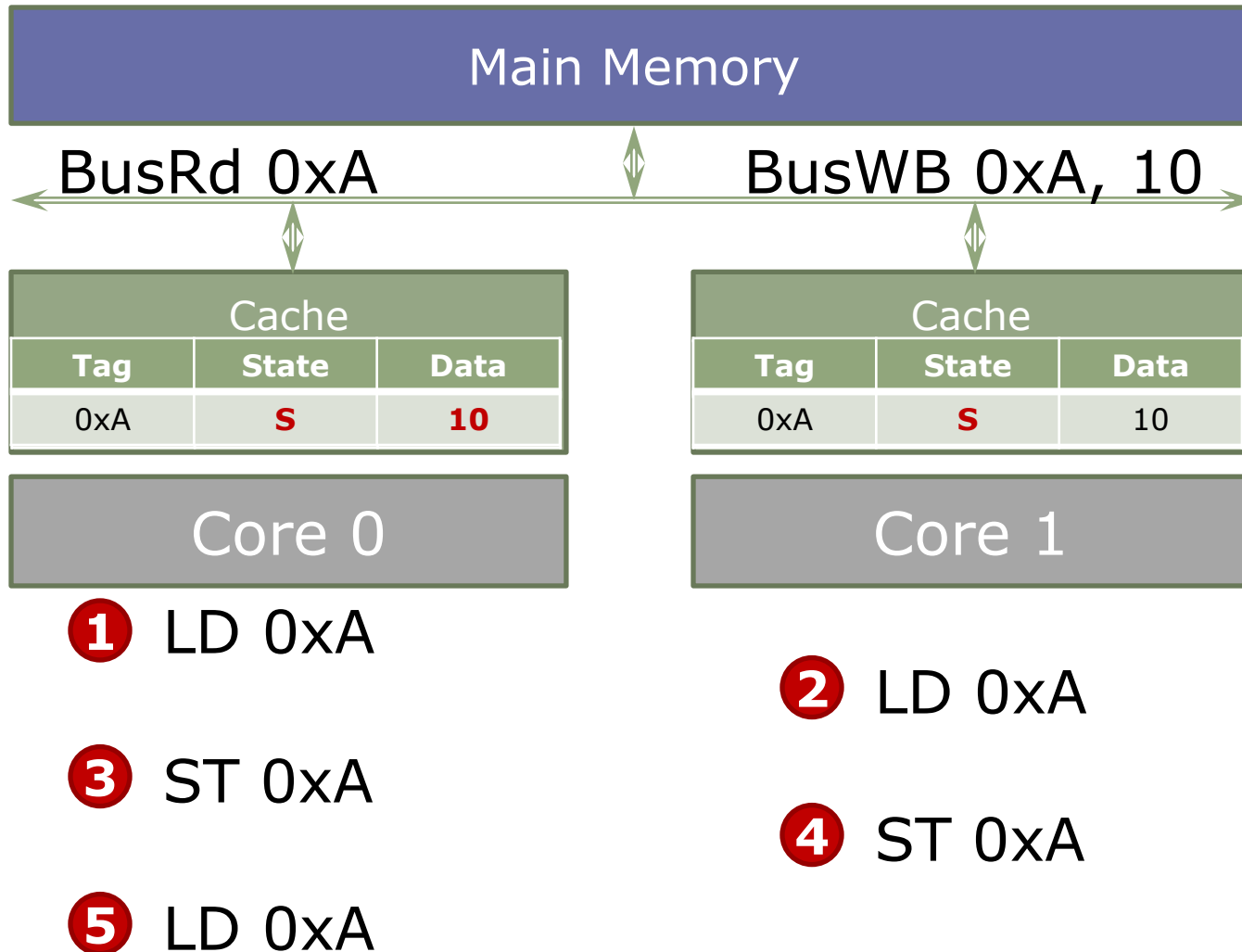
MSI Example



MSI Example



MSI Example



MSI Optimizations: Exclusive State

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 - What's the problem with MSI?
- Solution: E state (exclusive, clean)
 - If no other sharers, a read acquires line in E instead of S
 - Writes silently cause E→M (exclusive, dirty)

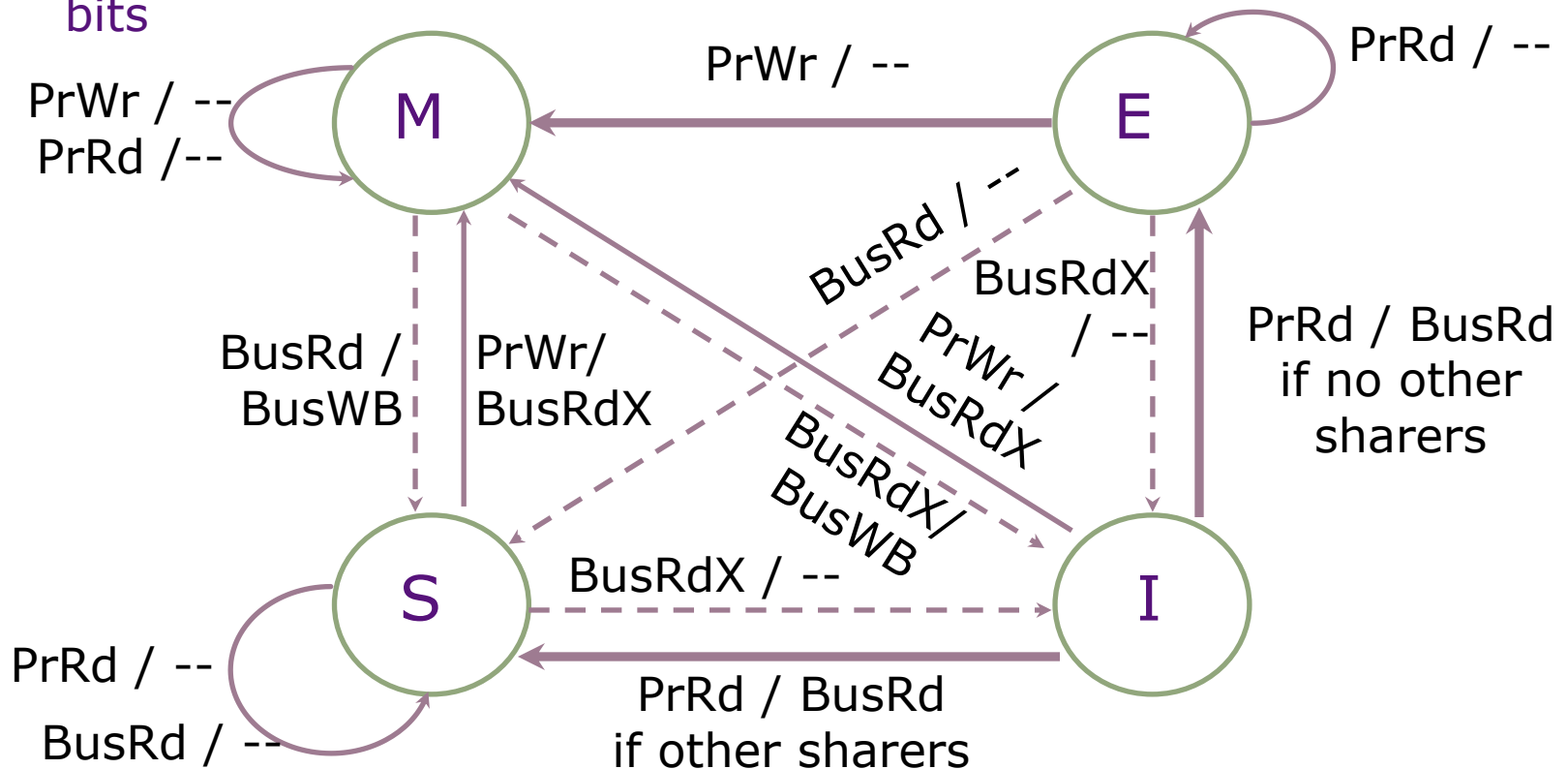
MESI: An Enhanced MSI protocol

increased performance for private read-write data

Each cache line has a tag



M: Modified Exclusive
 E: Exclusive, unmodified
 S: Shared
 I: Invalid



MSI Optimizations: Owner State

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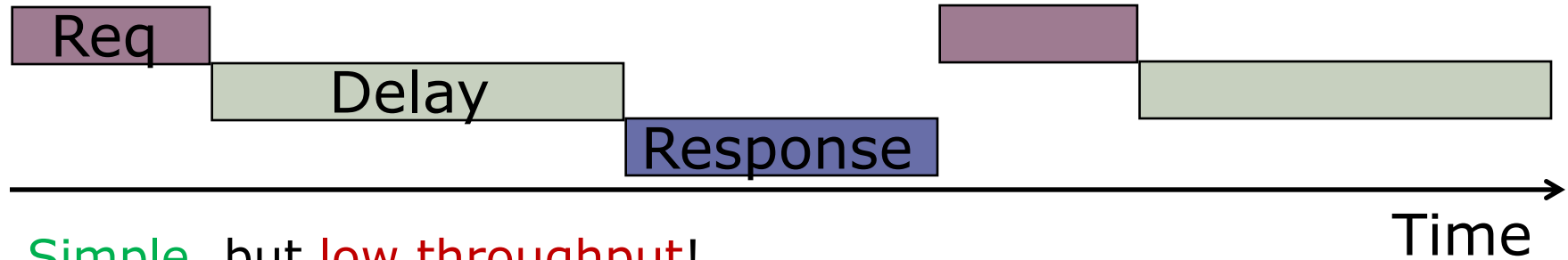
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- MSI, MESI, MOSI, MOESI...
 - Typically E if private read-write \gg shared read-only (common)
 - Typically O only if writebacks are expensive (main mem vs L3)

Split-Transaction and Pipelined Buses

Atomic Transaction Bus

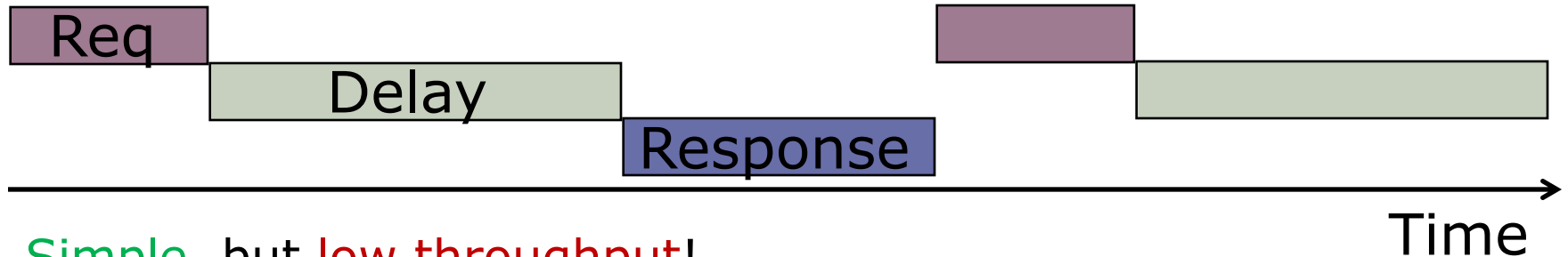


Simple, but low throughput!

Time

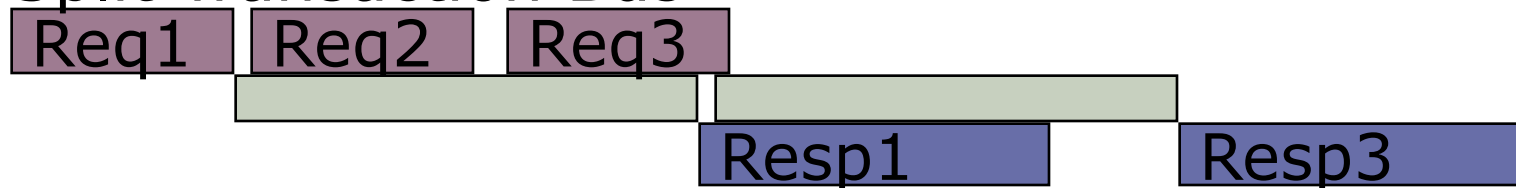
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Split-Transaction Bus

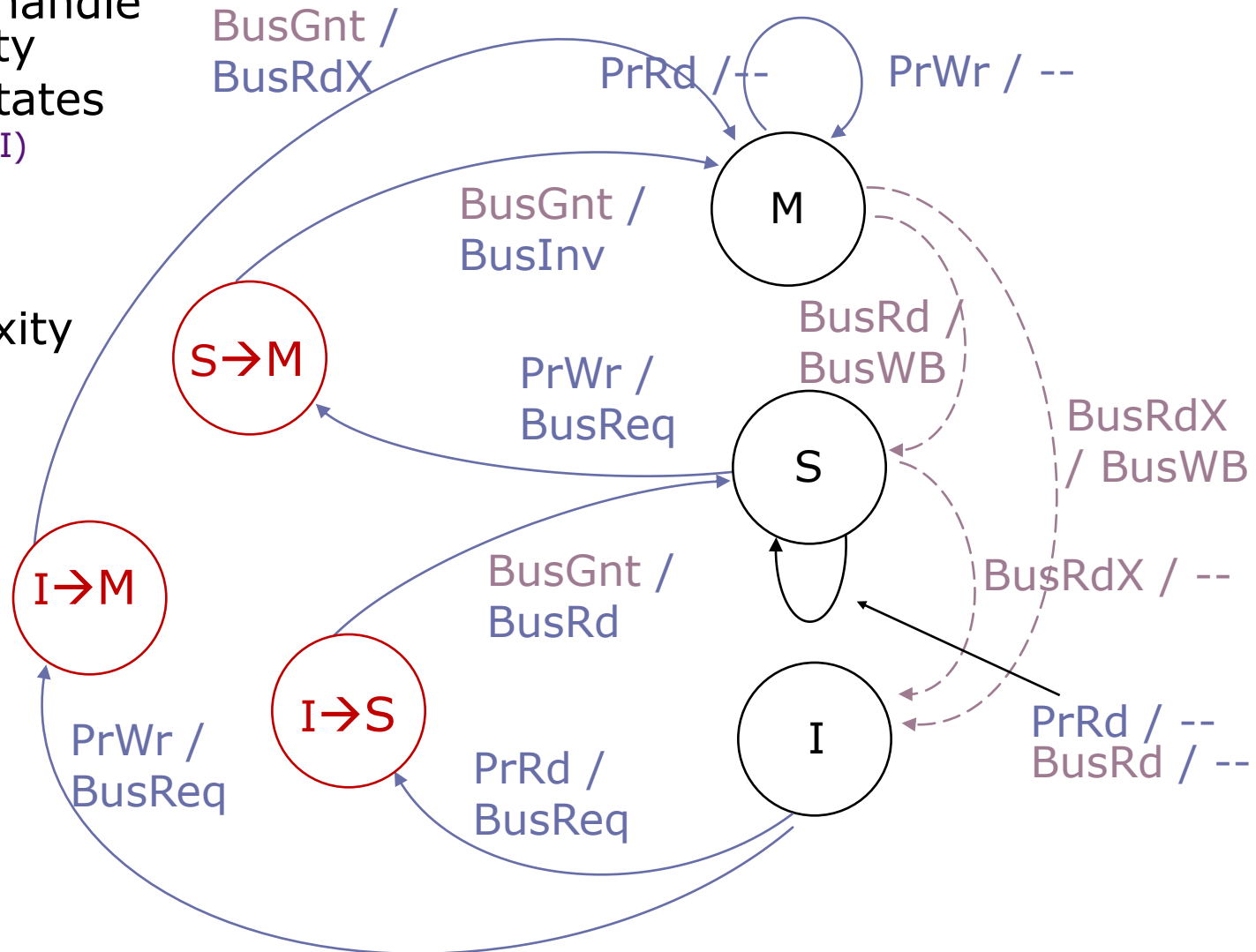


- Supports multiple simultaneous transactions
 - Higher throughput
 - Responses may arrive out of order
- Often implemented as multiple buses (req+resp)

Non-Atomicity → Transient States

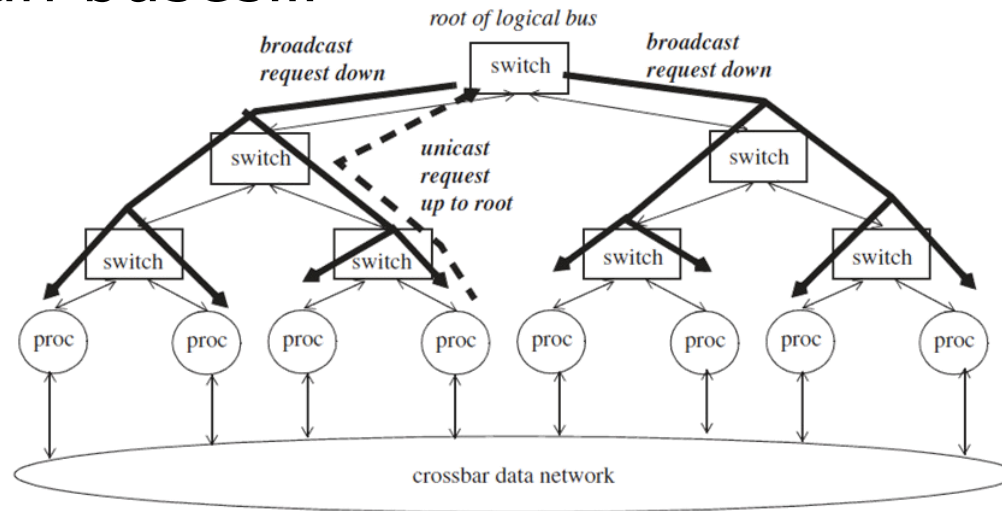
- Protocol must handle lack of atomicity
- Two types of states
 - Stable (e.g. MSI)
 - Transient
- Split + race transitions
- Higher complexity

Actions
Bus Request (BusReq)
Bus Grant (BusGnt)



Scaling Cache Coherence

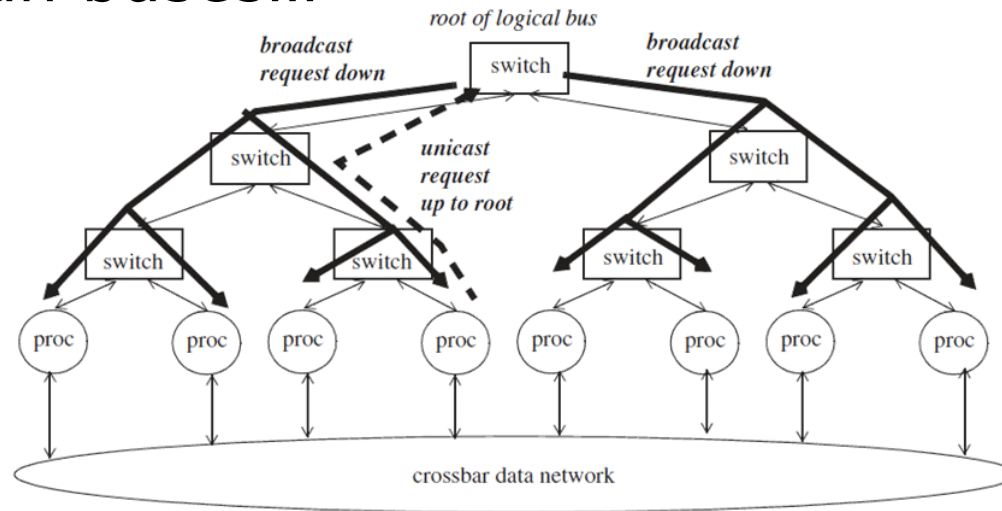
- Can implement ordered interconnects that scale better than buses...



Starfire E10000 (drawn with only eight processors for clarity). A coherence request is unicast up to the root, where it is serialized, before being broadcast down to all processors

Scaling Cache Coherence

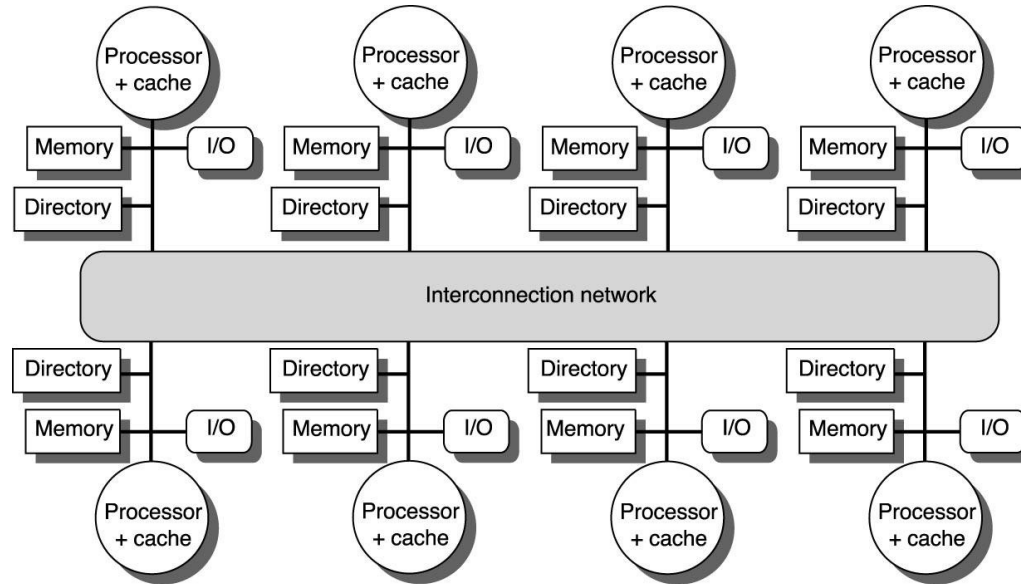
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Starfire E10000 (drawn with only eight processors for clarity). A coherence request is unicast up to the root, where it is serialized, before being broadcast down to all processors

- ... but broadcast is fundamentally unscalable
 - Bandwidth, energy of transactions with 100s of cache snoops?

Directory-Based Coherence



- Route all coherence transactions through a directory
 - Tracks contents of private caches → No broadcasts
 - Serves as ordering point for conflicting requests → Unordered networks

(more on next lecture)

CC and False Sharing

Performance Issue - 1



A cache block contains more than one word and cache coherence is done at the block-level and not word-level

Suppose P_1 writes $word_i$ and P_2 writes $word_k$ and both words have the same block address.

What can happen?

CC and False Sharing

Performance Issue - 1



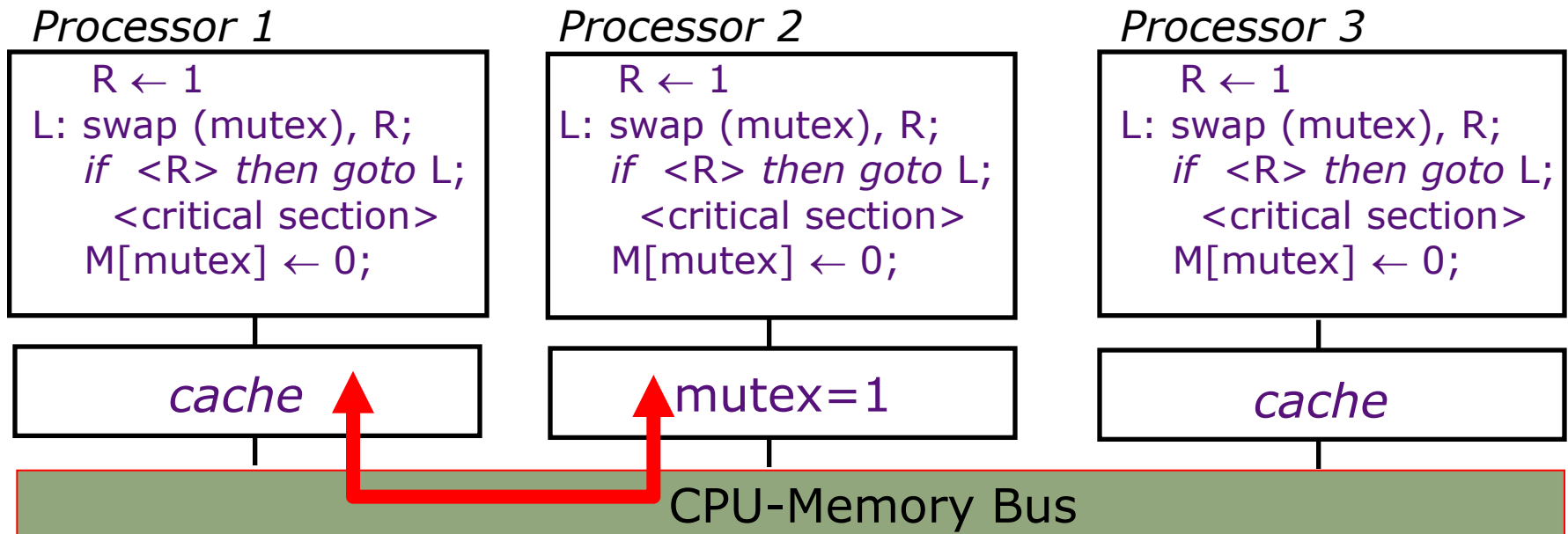
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Suppose P_1 writes $word_i$ and P_2 writes $word_k$ and both words have the same block address.

What can happen? The block may be invalidated (ping-pong) many times unnecessarily because addresses are in the same block.

CC and Synchronization

Performance Issue - 2



Cache coherence protocols will cause **mutex** to *ping-pong* between P1's and P2's caches.

Ping-ponging can be reduced by first reading the **mutex** location (*non-atomically*) and executing a swap only if it is found to be zero (test&test&set).

CC and Bus Occupancy

Performance Issue - 3

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In a multiprocessor setting, bus needs to be locked for the entire duration of the atomic read and write operation

⇒ expensive for simple buses

⇒ *very expensive* for split-transaction buses

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modern processors use

load-reserve

store-conditional

Load-reserve & Store-conditional

Special register(s) to hold reservation flag and address, and the outcome of store-conditional

```
Load-reserve R, (a):
  <flag, adr> ← <1, a>;
  R ← M[a];
```

```
Store-conditional (a), R:
  if <flag, adr> == <1, a>
  then cancel other procs'
    reservation on a;
    M[a] ← <R>;
    status ← succeed;
  else status ← fail;
```

If the snooper sees a store transaction to the address in the reserve register, the reserve bit is set to **0**

- Several processors may reserve 'a' simultaneously
- These instructions are like ordinary loads and stores with respect to the bus traffic

Performance:

Load-reserve & Store-conditional

The total number of memory (bus) transactions is not necessarily reduced, but splitting an atomic instruction into load-reserve & store-conditional:

- *increases bus utilization* (and reduces processor stall time), especially in split-transaction buses
- *reduces cache ping-pong effect* because processors trying to acquire a mutex do not have to perform stores each time