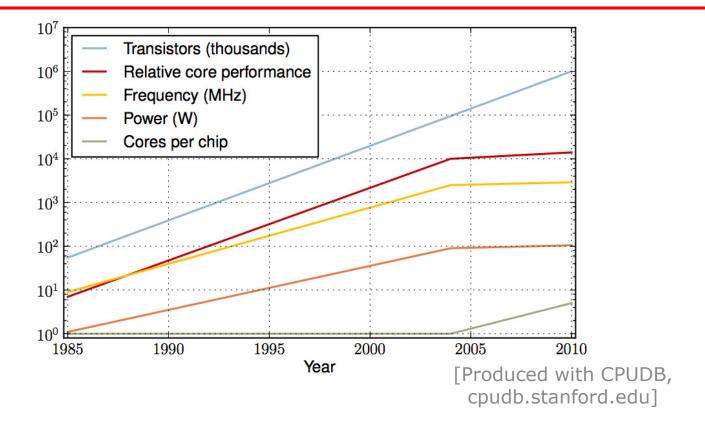
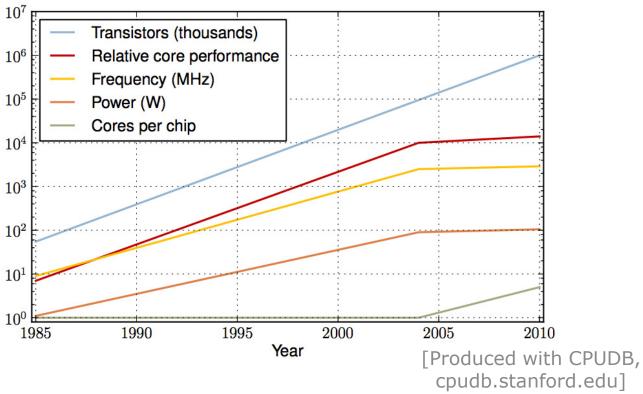
Cache Coherence

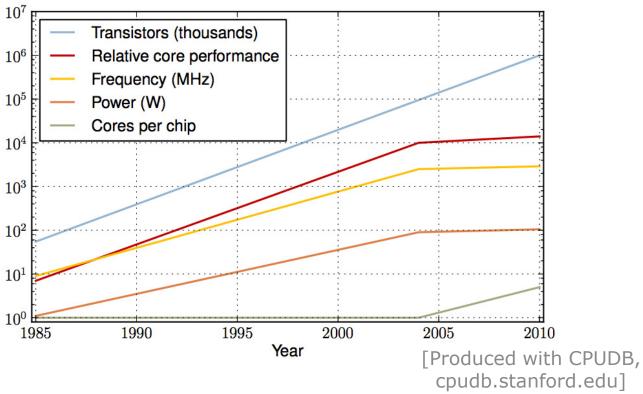
Daniel Sanchez
Computer Science and Artificial Intelligence Laboratory
M.I.T.

http://www.csg.csail.mit.edu/6.823

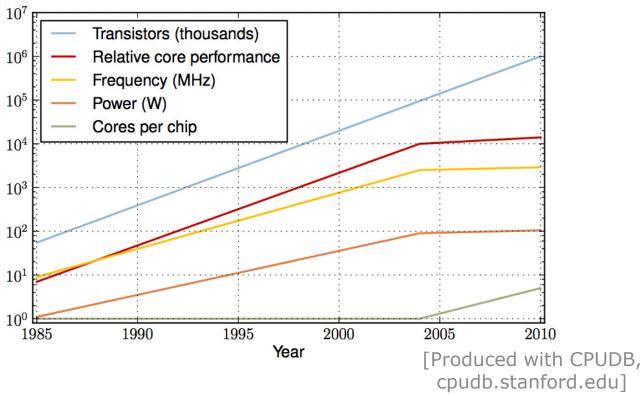




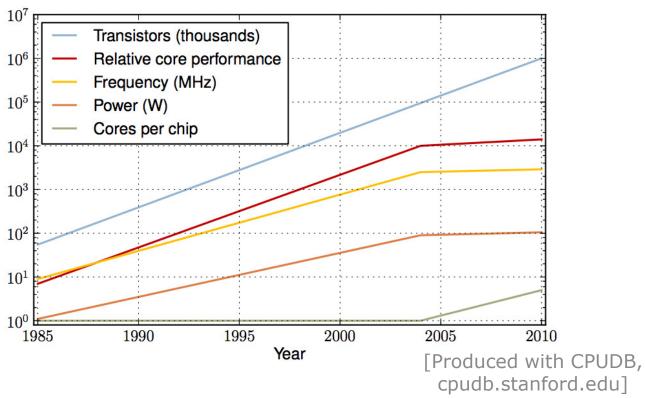
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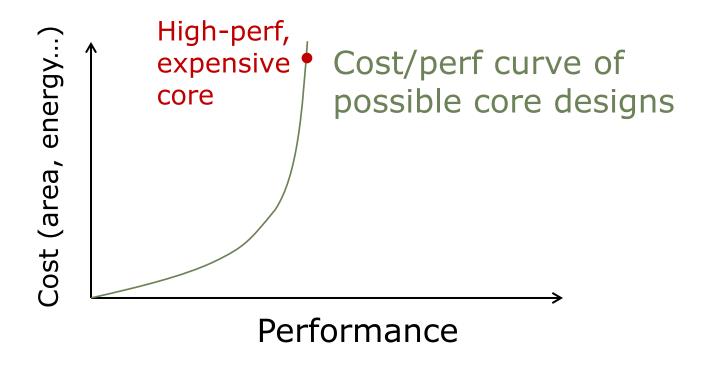
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- Why?

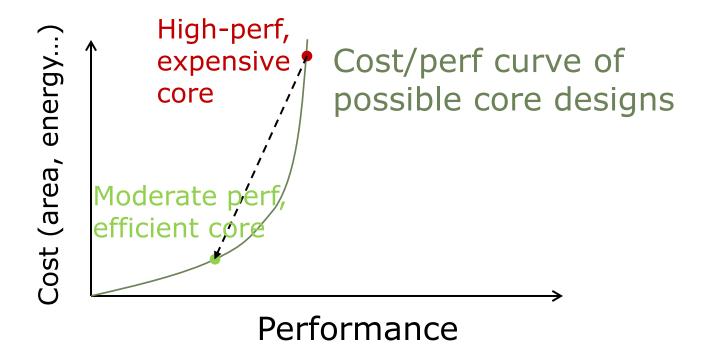


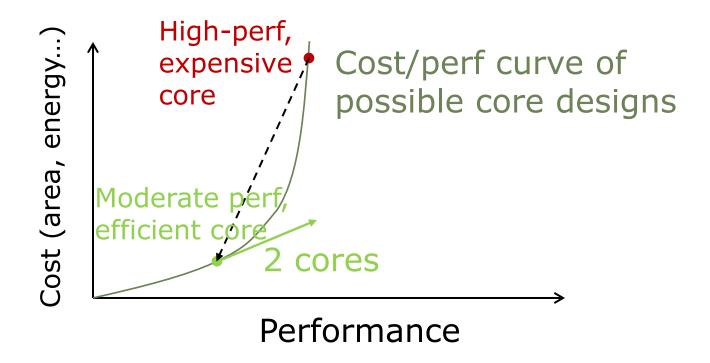
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- Limited instruction-level parallelism Why?

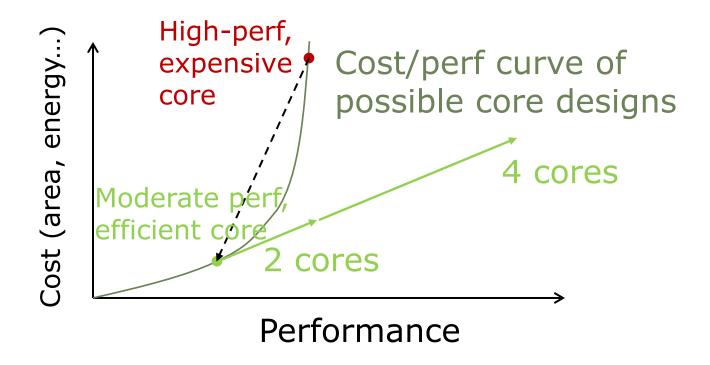


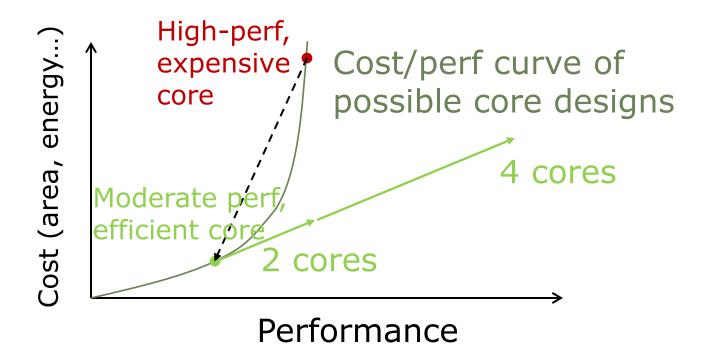
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- Why? Limited instruction-level parallelism Technology scaling



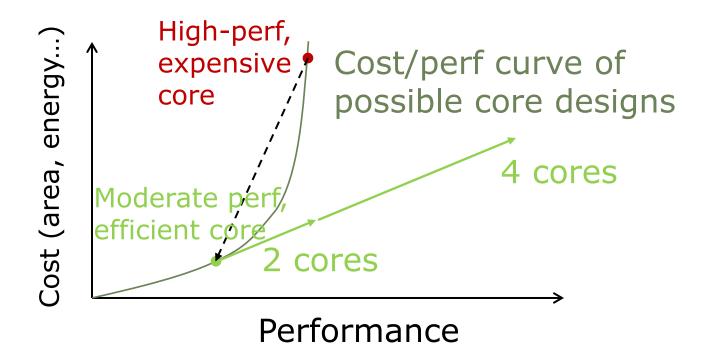






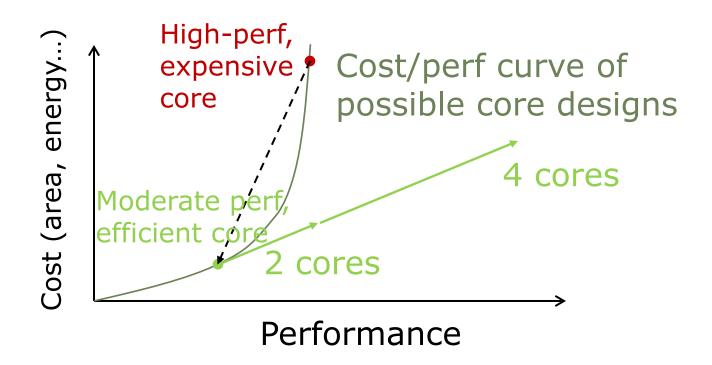


What factors may limit multicore performance?



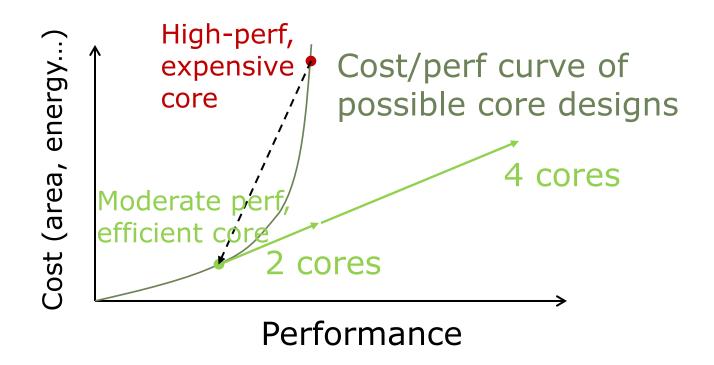
What factors may limit multicore performance?

Limited application parallelism



What factors may limit multicore performance?

Limited application parallelism
Memory accesses and inter-core communication



What factors may limit multicore performance?

Limited application parallelism

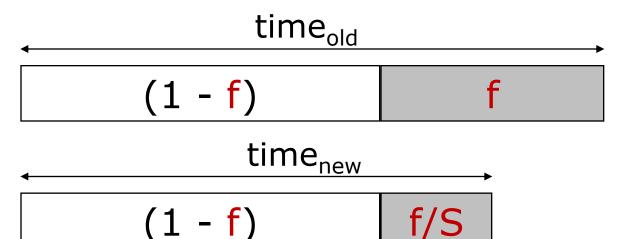
Memory accesses and inter-core communication

Programming complexity

Amdahl's Law

- Speedup= time_{without enhancement} / time_{with enhancement}
- Suppose an enhancement speeds up a fraction f of a task by a factor of S

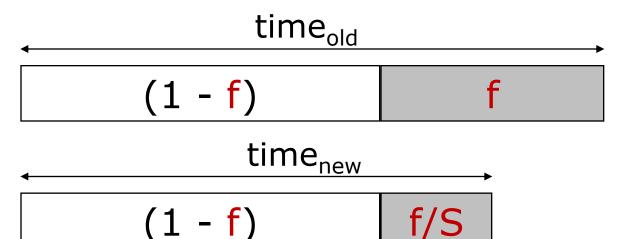
$$time_{new} = time_{old} \cdot ((1-f) + f/S)$$
$$S_{overall} = 1 / ((1-f) + f/S)$$



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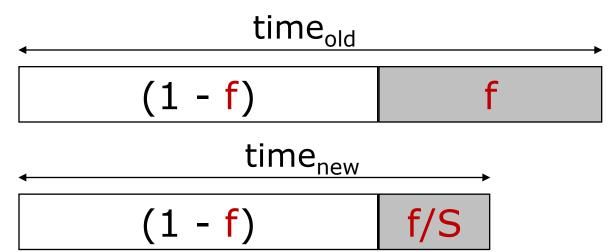


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Corollary: Make the common case fast

- Say you write a program that can do 90% of the work in parallel, but the other 10% is sequential
- What is the maximum speedup you can get by running on a multicore machine?

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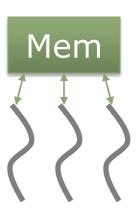
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What f do you need to use a 1000-core machine well?

Communication Models

Shared memory:

- Single address space
- Implicit communication by reading/writing memory
 - Data
 - Control (semaphores, locks, barriers, ...)
- Low-level programming model: threads



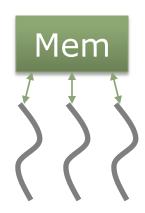
Communication Models

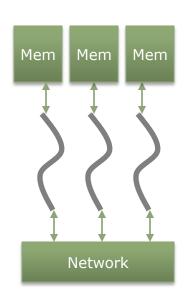
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 - Data & control (blocking msgs, barriers, ...)
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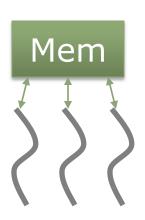
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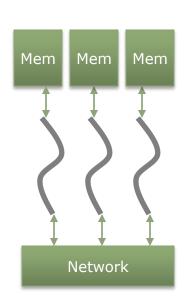
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- Pros/cons of each model?



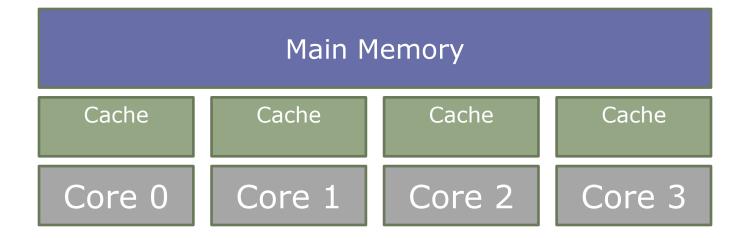


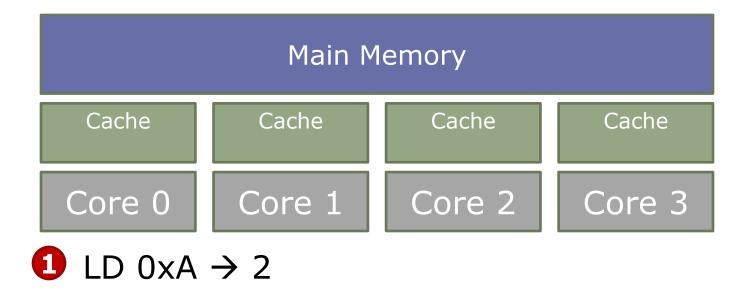
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 - Have multiple private caches for performance reasons
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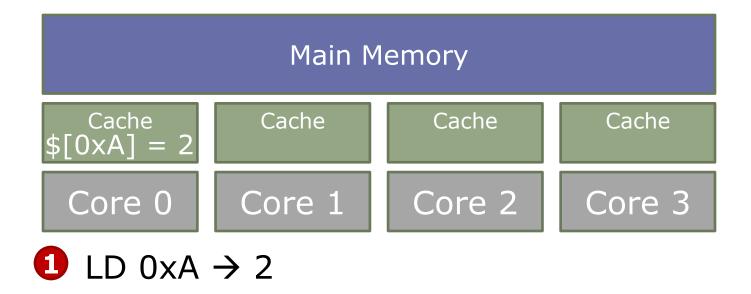
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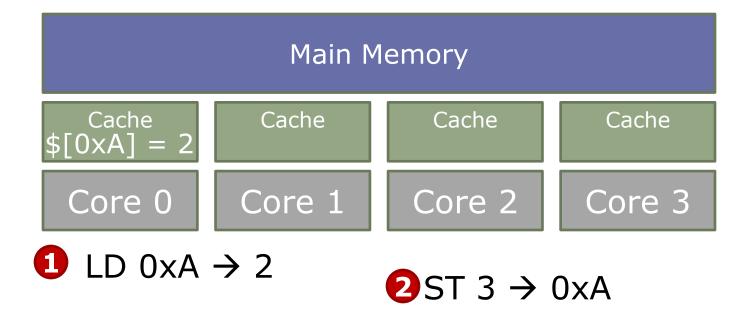
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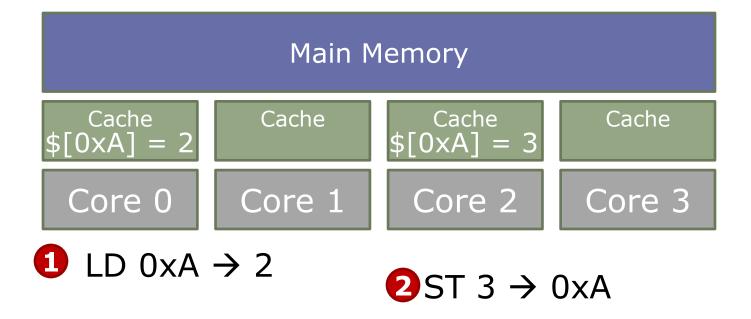
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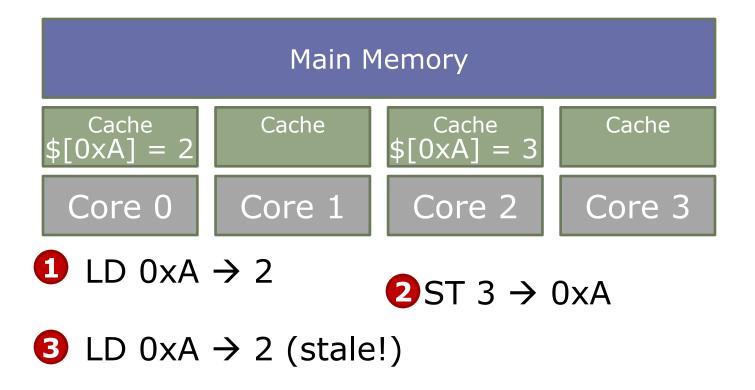


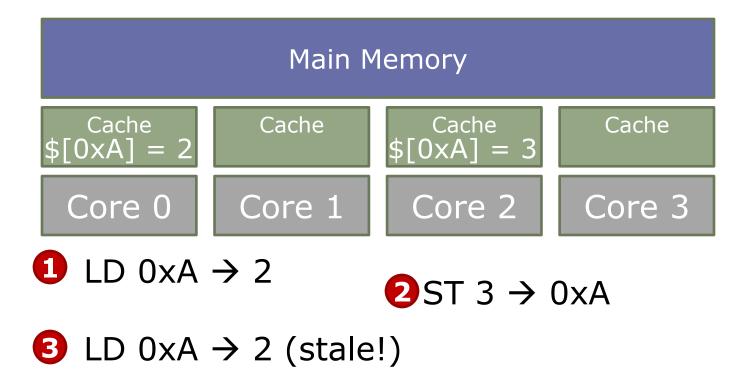












 A cache coherence protocol controls cache contents to avoid stale cache lines

Implementing Cache Coherence

- Coherence protocols must enforce two rules:
 - Write propagation: Writes eventually become visible to all processors
 - Write serialization: Writes to the same location are serialized (all processors see them in the same order)

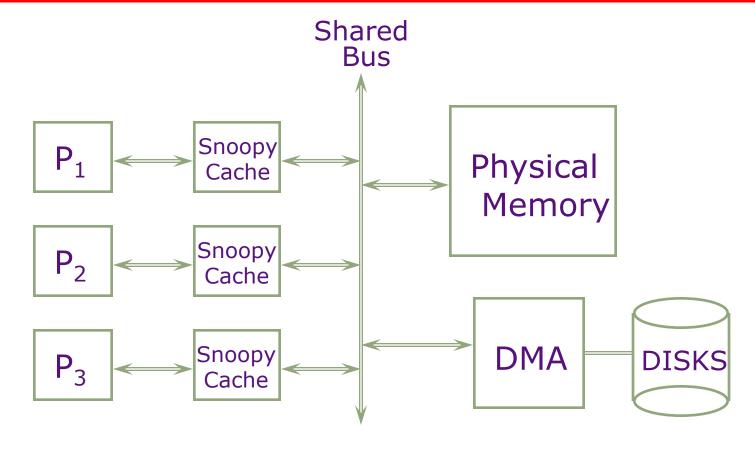
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- How to track sharing state of cached data and serialize requests to the same address?
 - Snooping-based protocols: All caches observe each other's actions through a shared bus
 - Directory-based protocols: A coherence directory tracks contents of private caches and serializes requests

Snooping-Based Coherence [Goodman 1983]

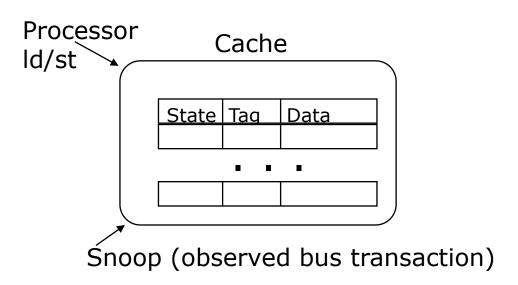


Caches watch (snoop on) bus to keep all processors' view of memory coherent

Snooping-Based Coherence

Bus provides serialization point

- Broadcast, totally ordered
- Each cache controller "snoops" all bus transactions
- Controller updates state of cache in response to processor and snoop events and generates bus transactions



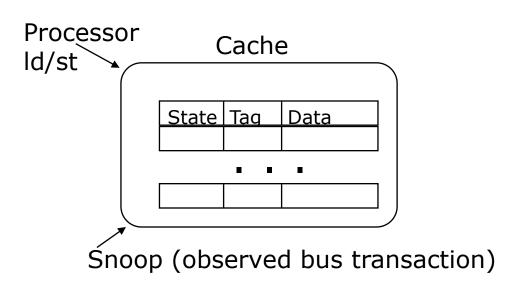
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- State-transition diagram
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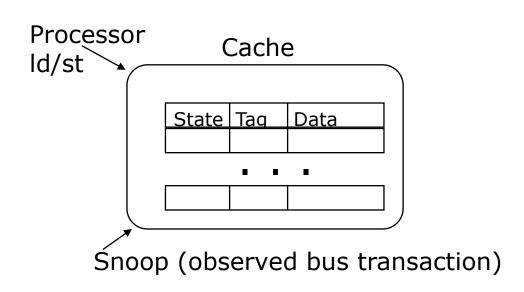
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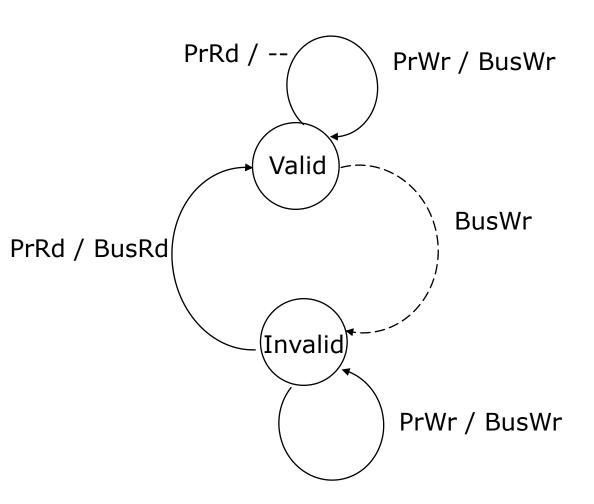
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Handling writes:

- Write-invalidate
- Write-update



A Simple Protocol: Valid/Invalid (VI)



 Assume writethrough caches

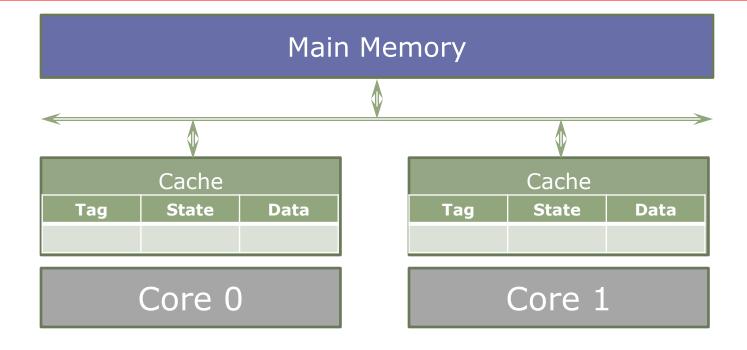
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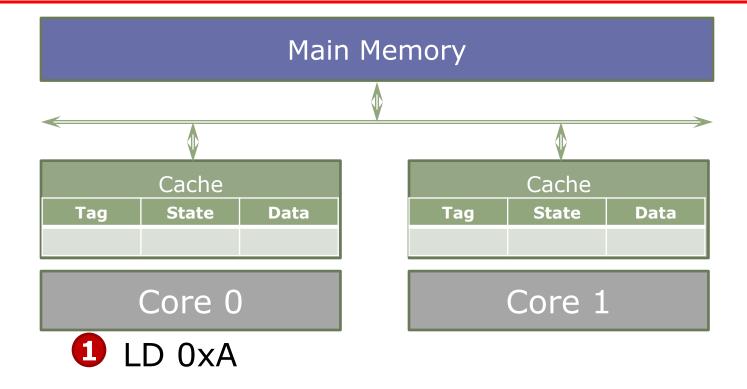
Processor Read (PrRd)

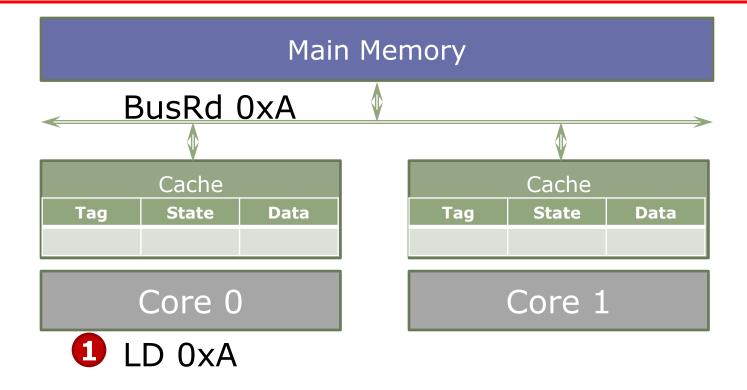
Processor Write (PrWr)

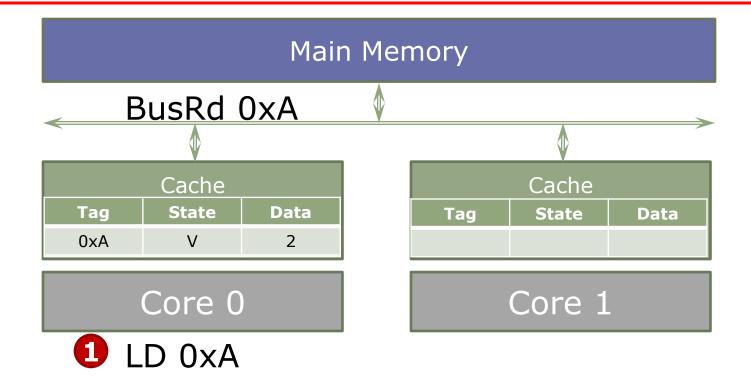
Bus Read (BusRd)

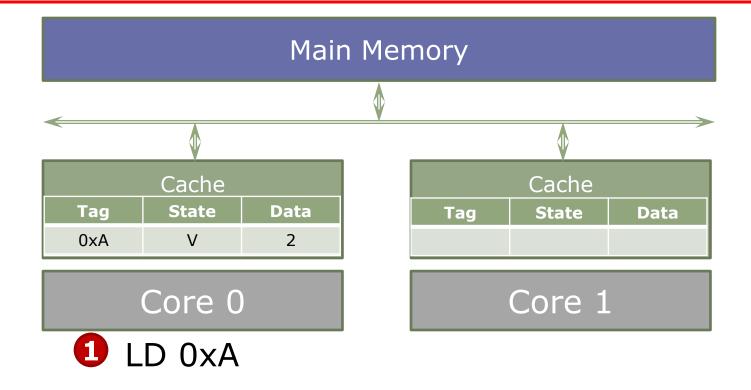
Bus Write (BusWr)

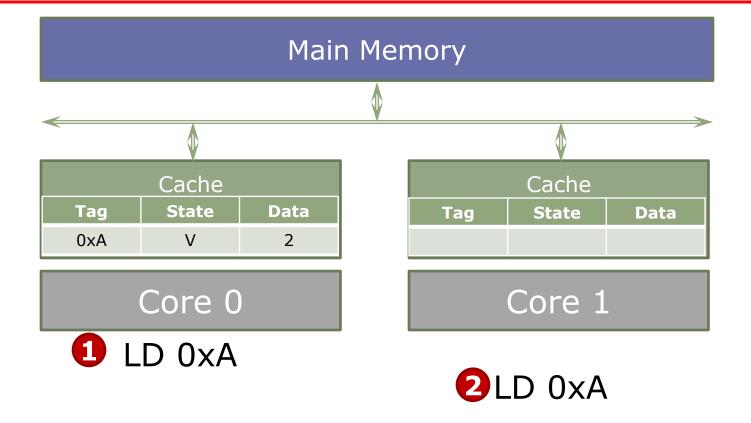


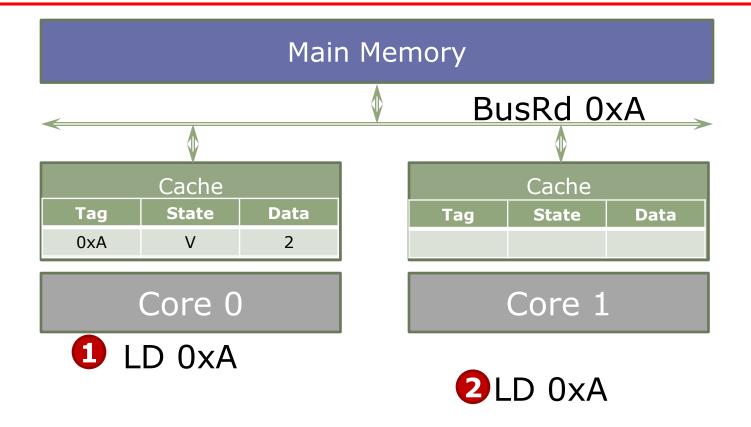


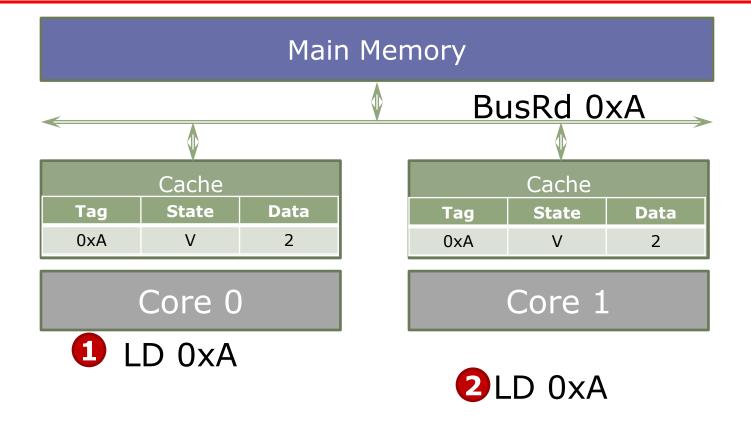


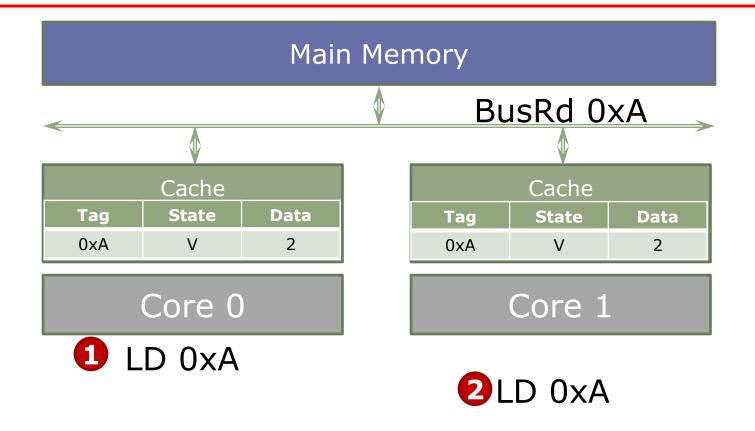




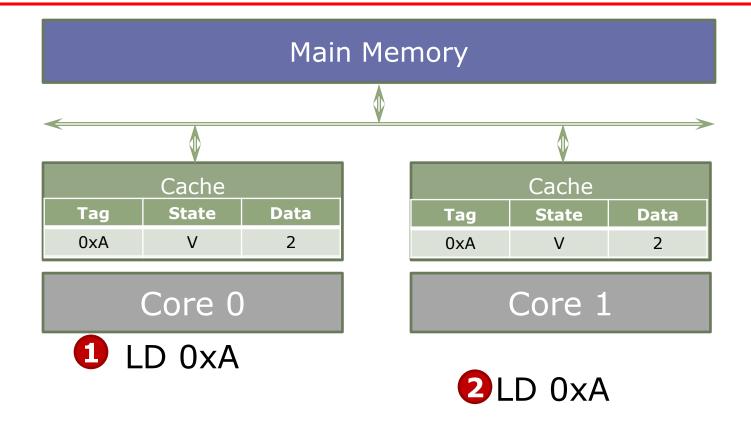


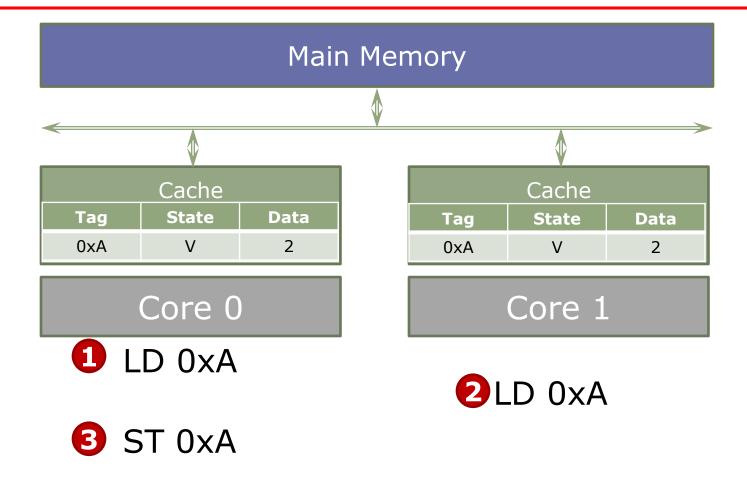


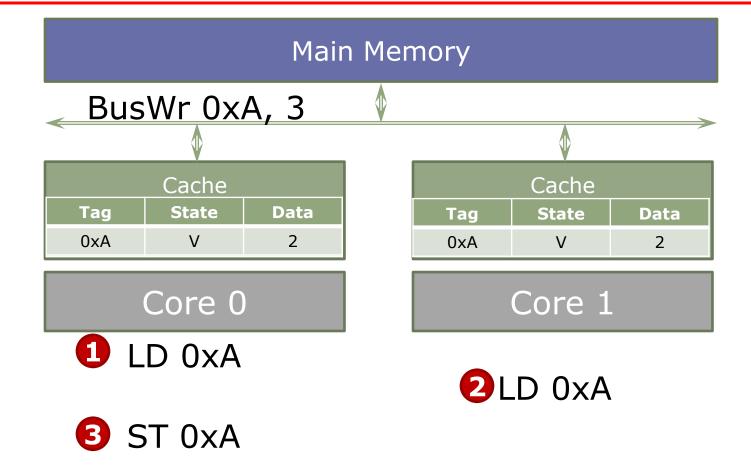


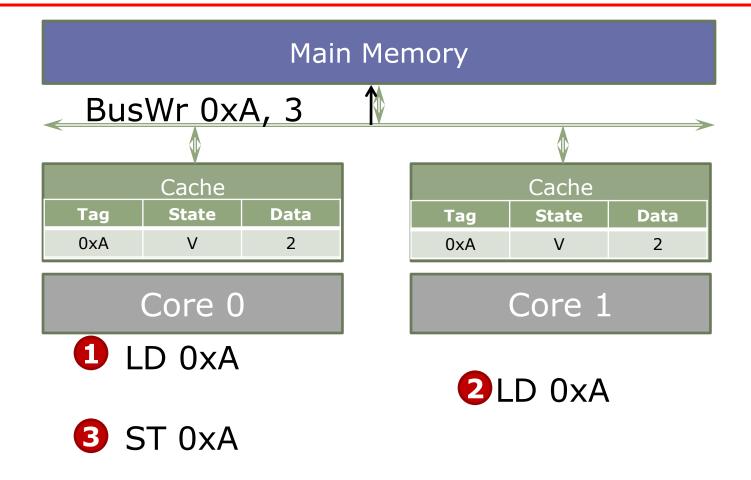


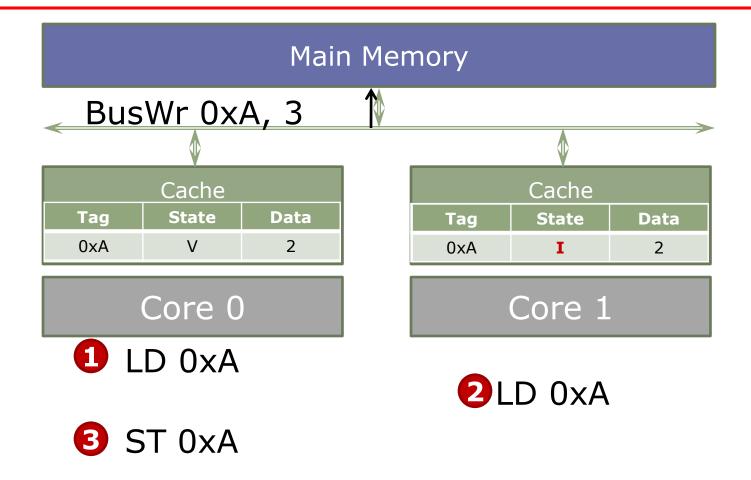
Additional loads satisfied locally, without BusRd

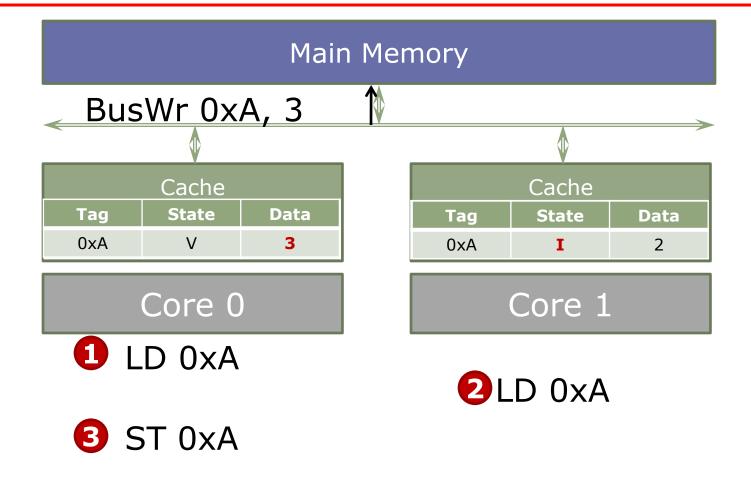


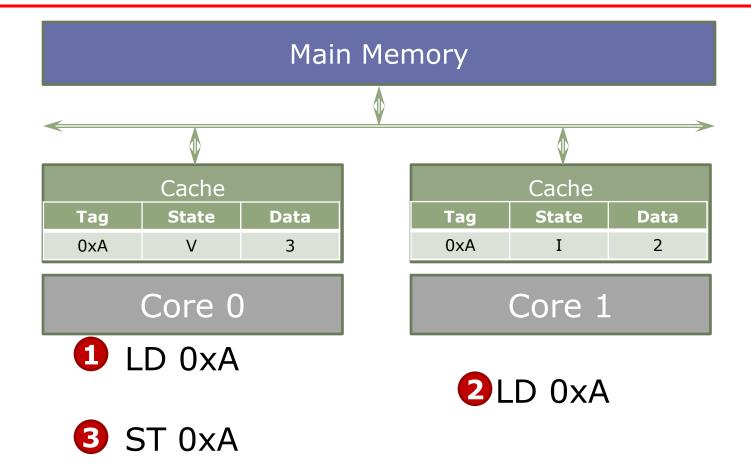


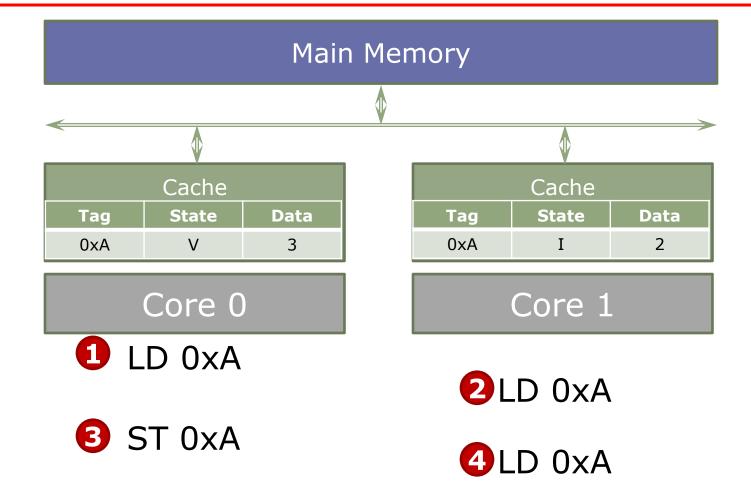


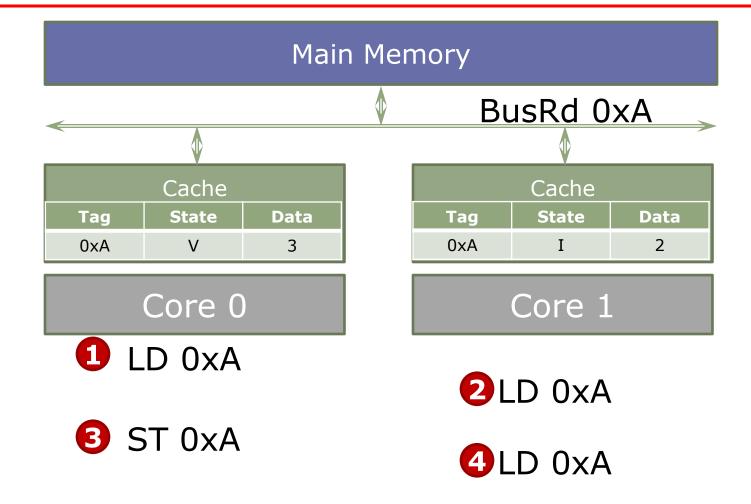


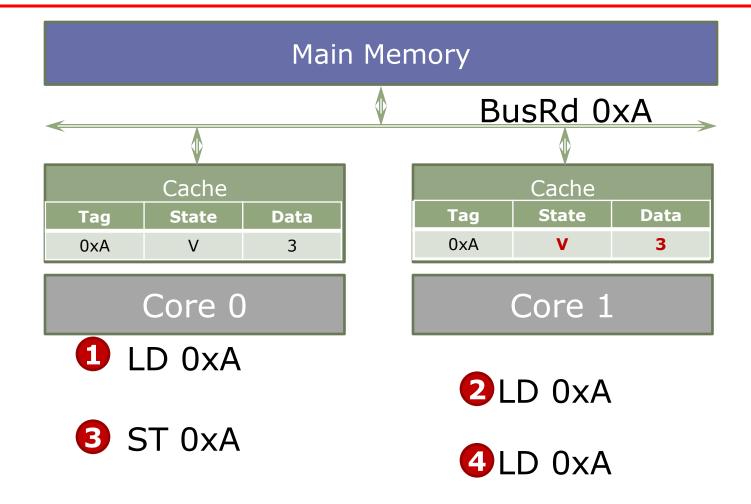


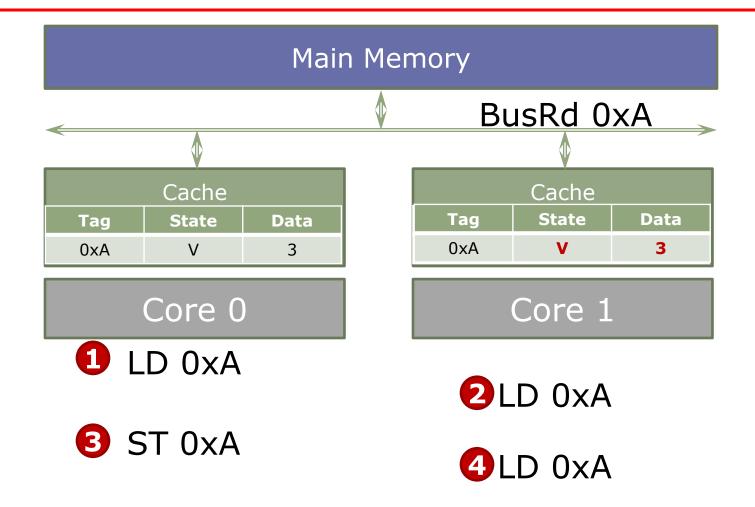




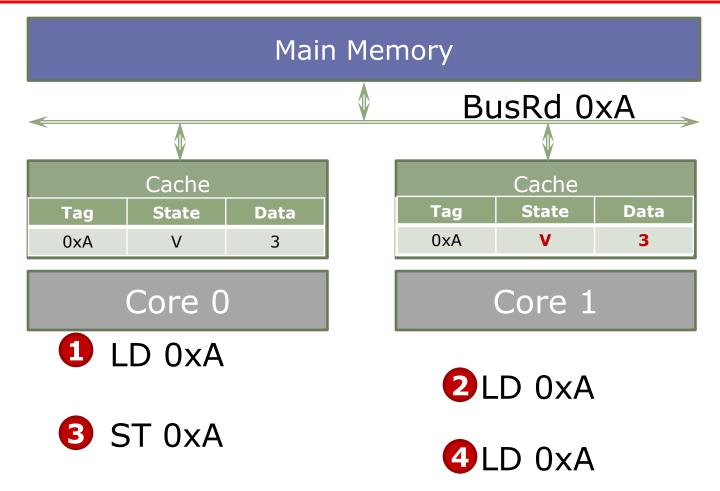








VI Problems?

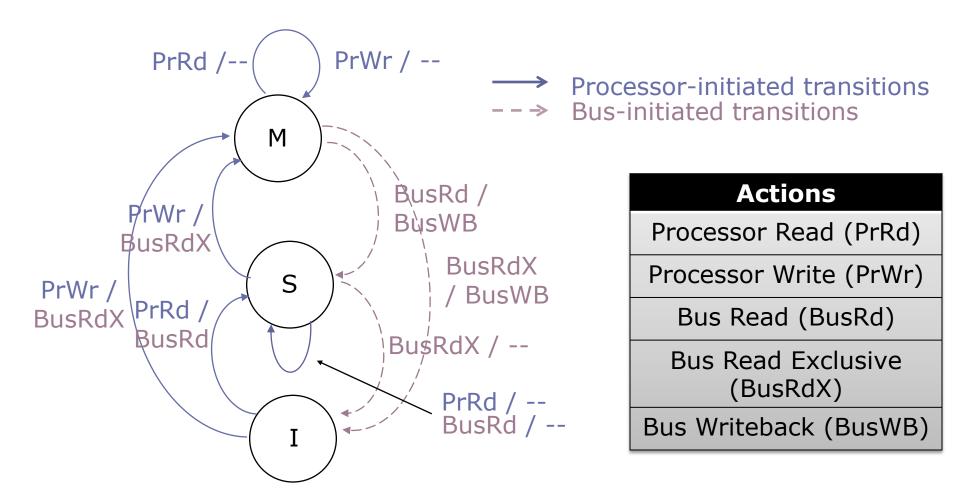


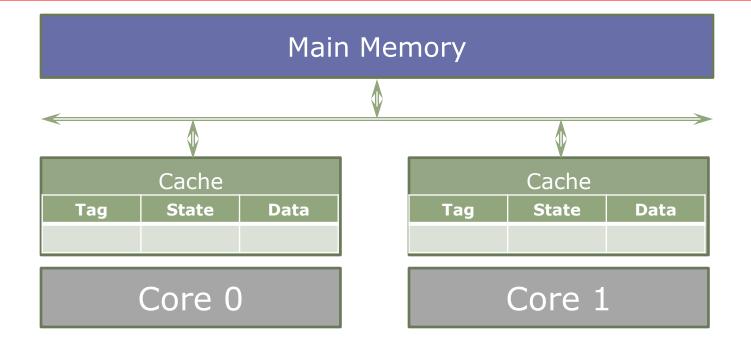
VI Problems?

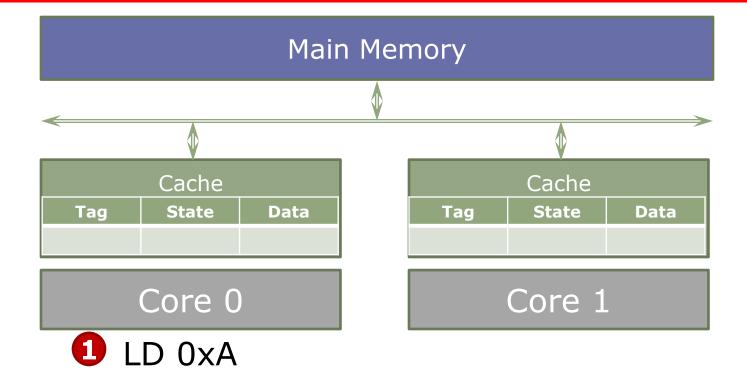
Every write updates main memory Every write requires broadcast & snoop

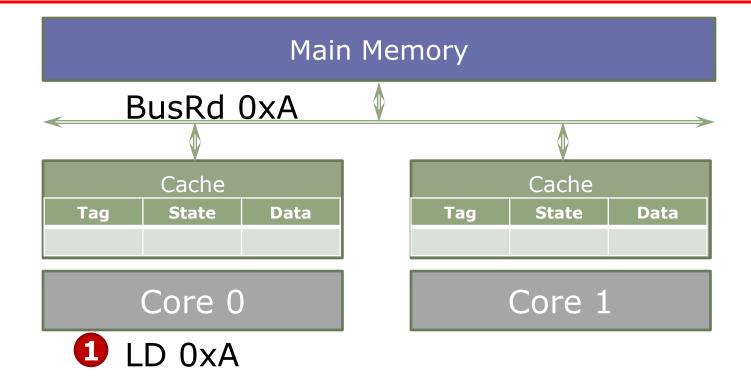
Modified/Shared/Invalid (MSI) Protocol

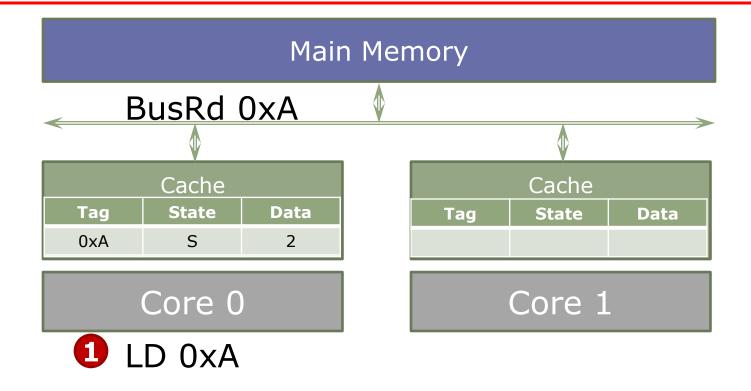
Allows writeback caches + satisfying writes locally

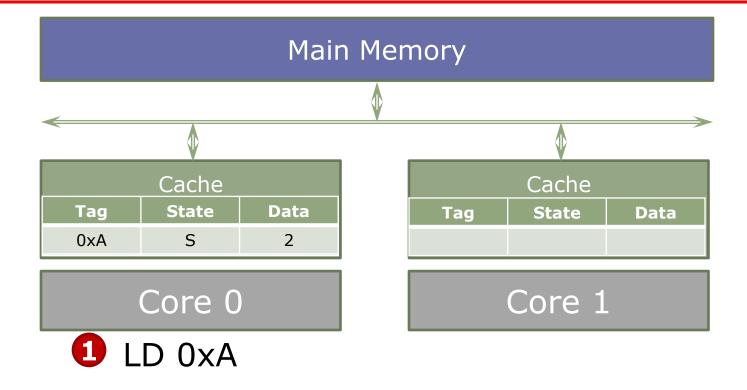


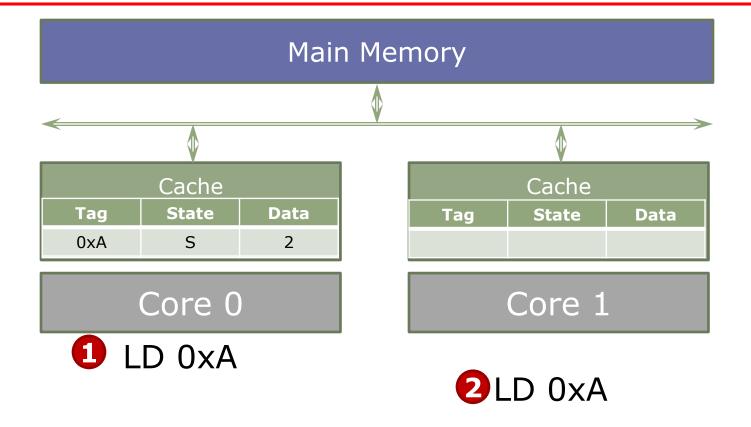


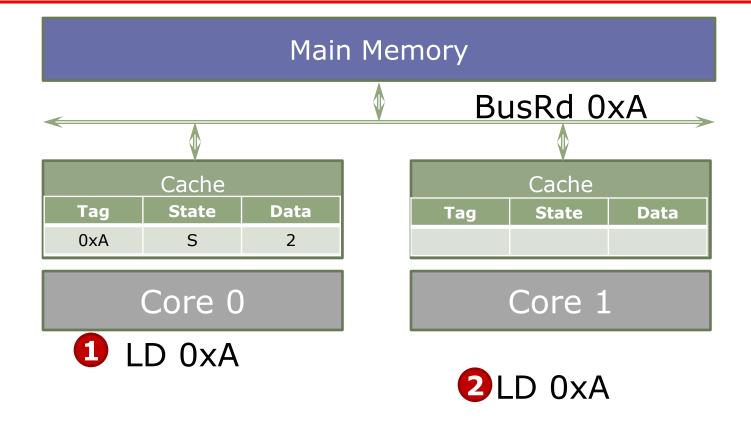


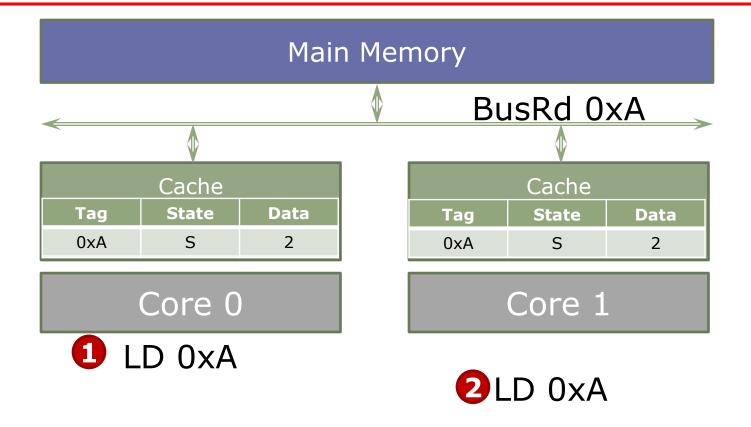


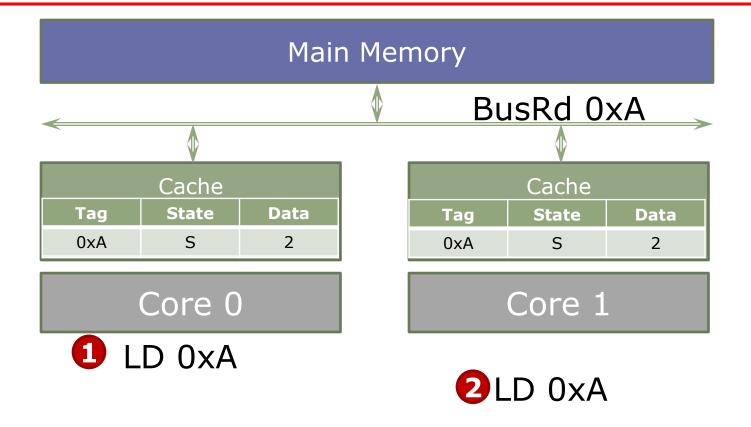




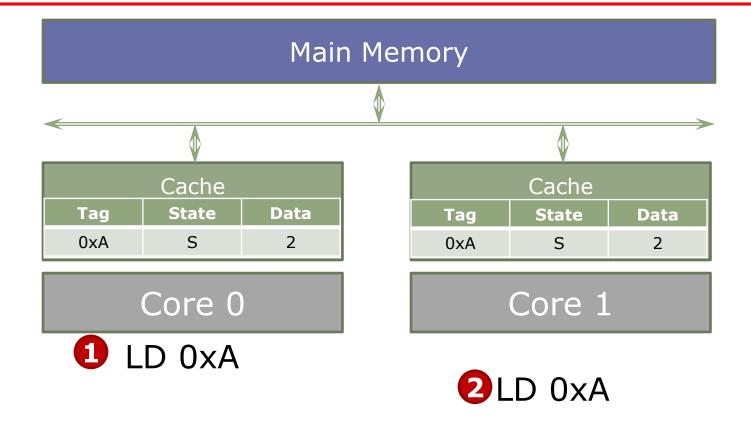


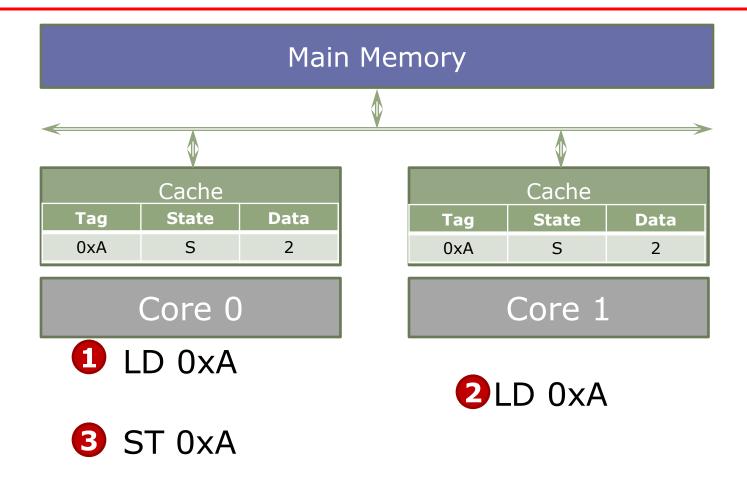


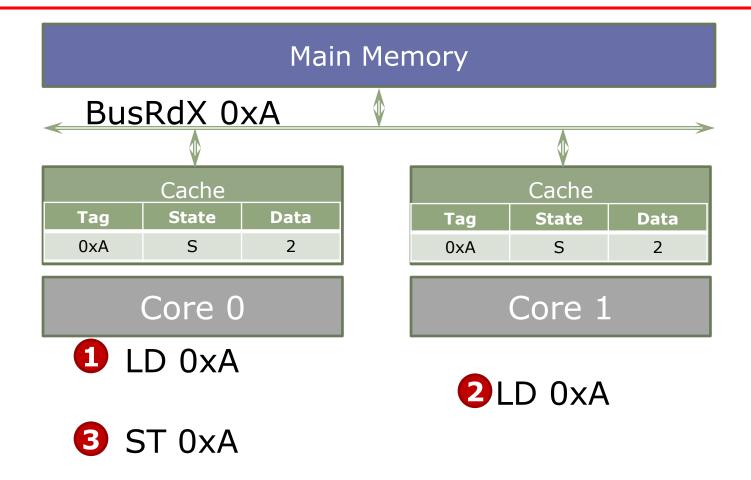


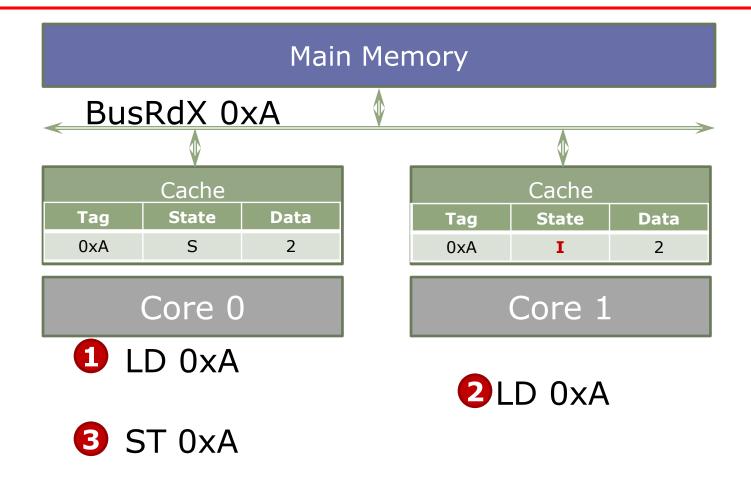


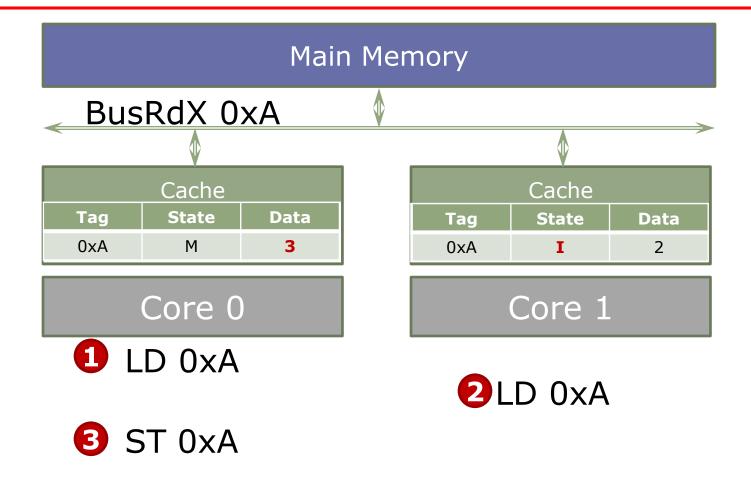
Additional loads satisfied locally, without BusRd (like in VI)

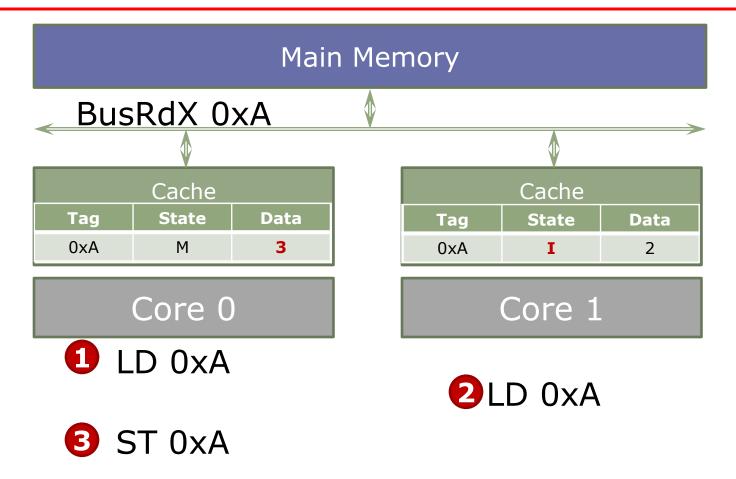




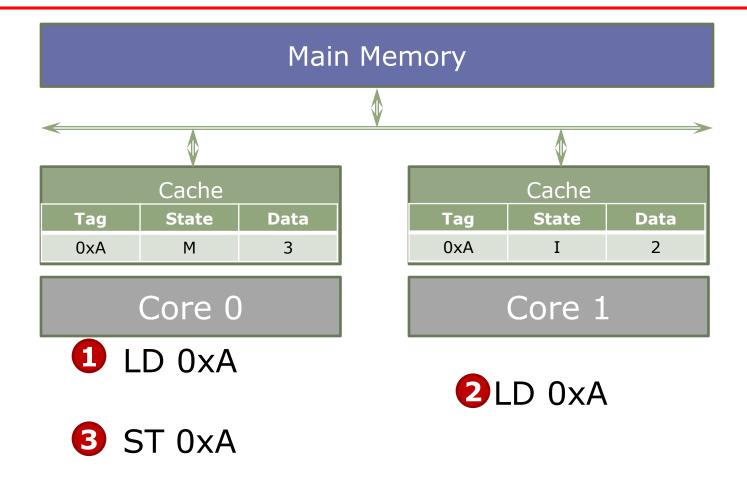


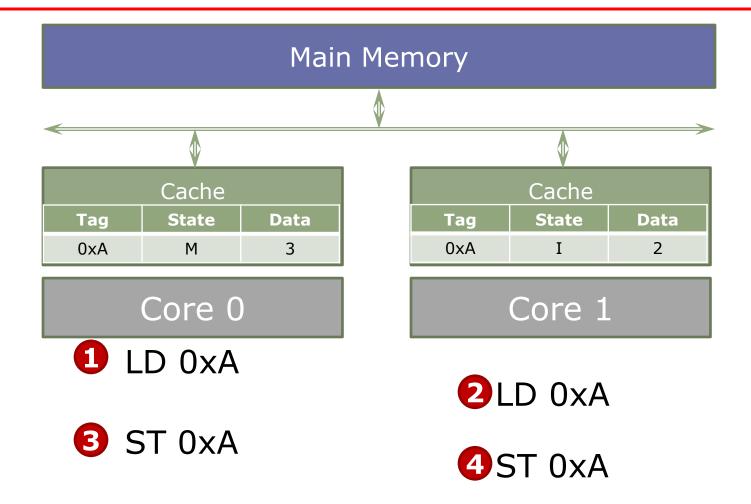


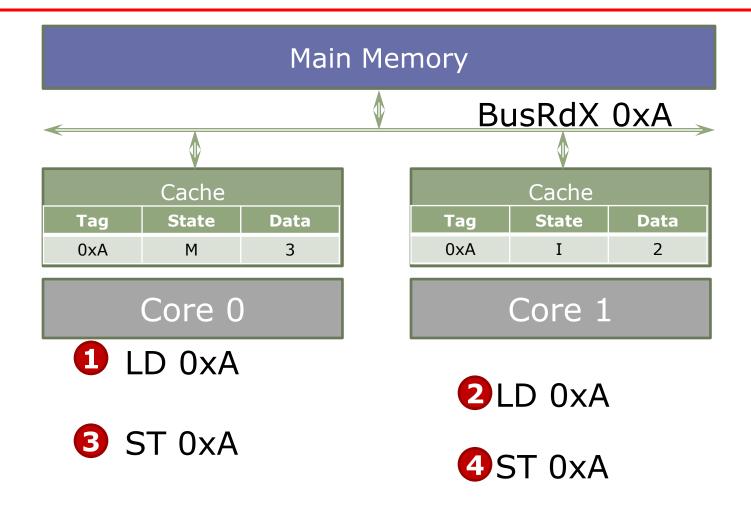


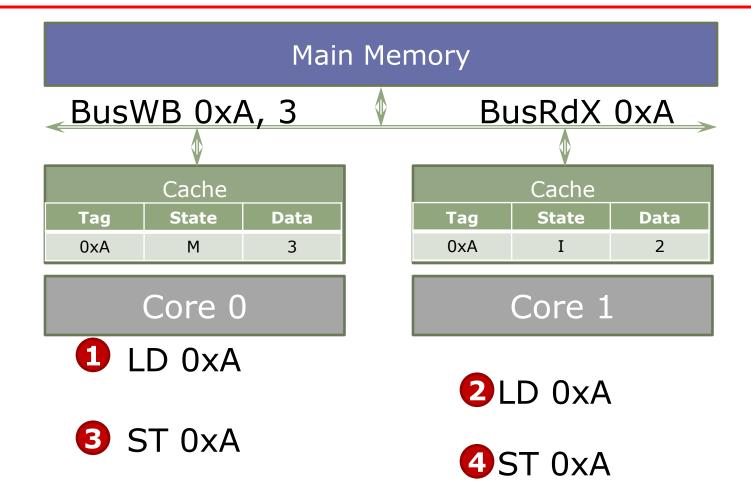


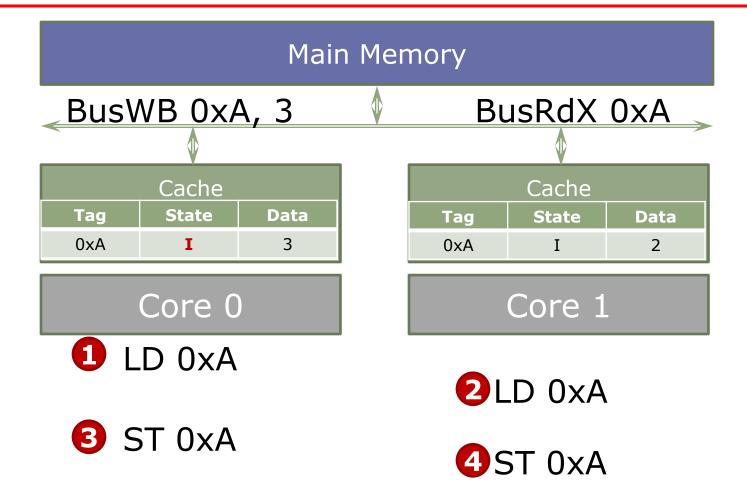
Additional loads and stores from core 0 satisfied locally, without bus transactions (unlike in VI)

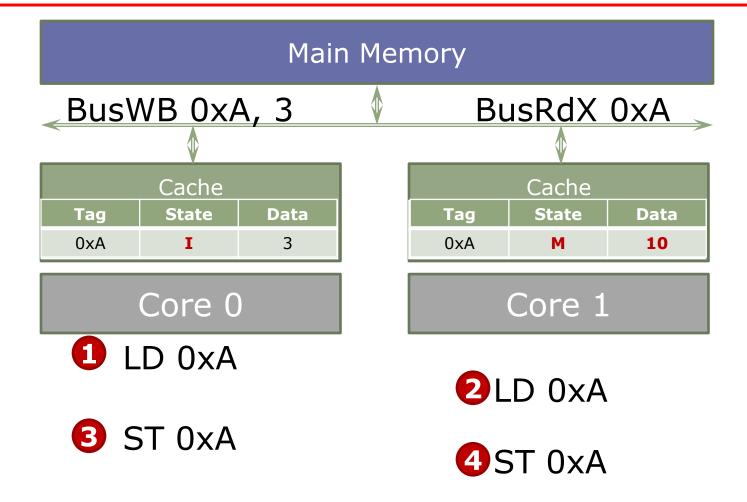




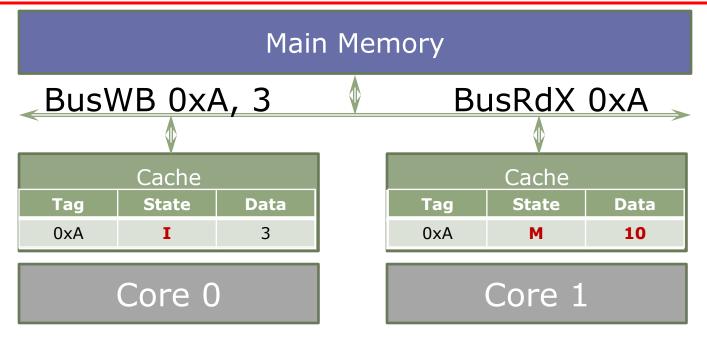




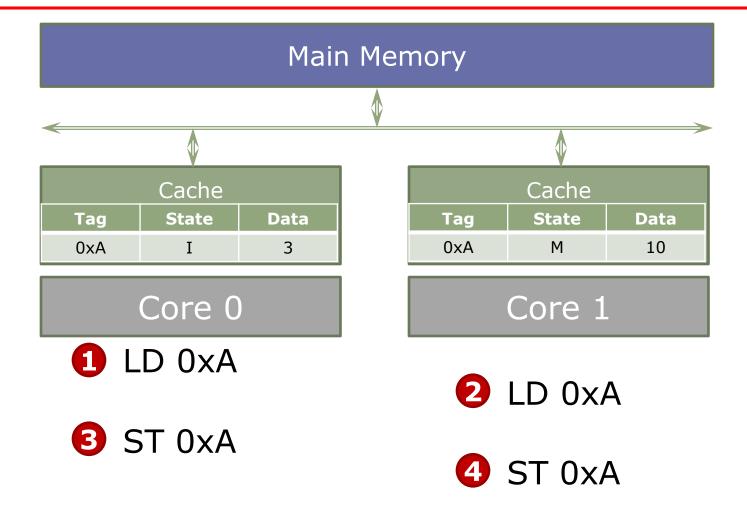


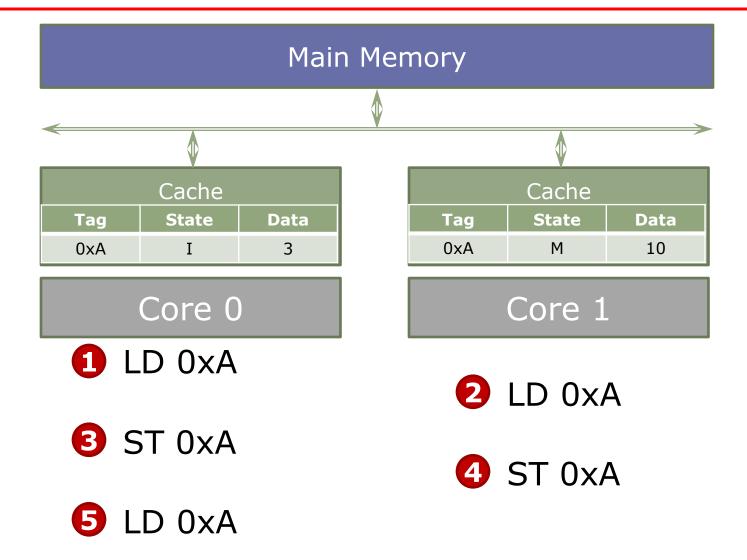


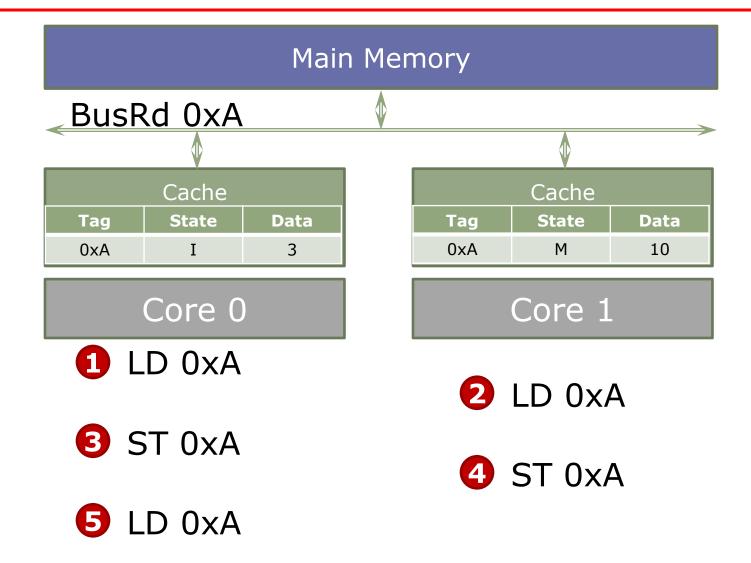
Cache interventions

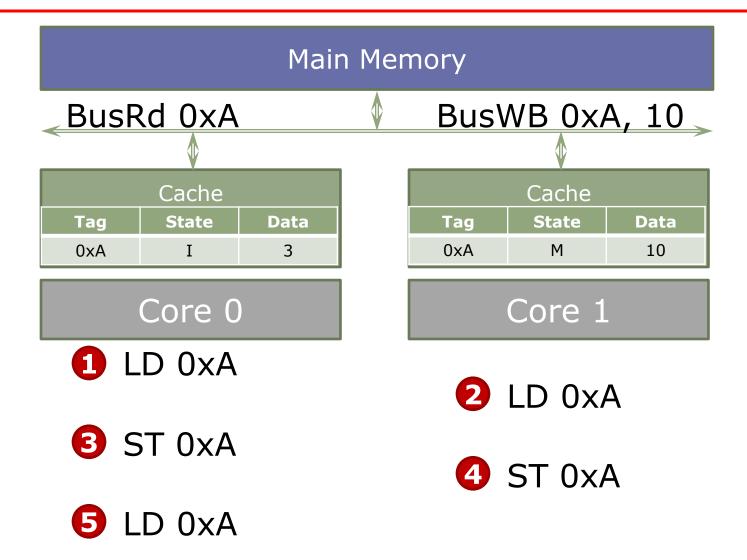


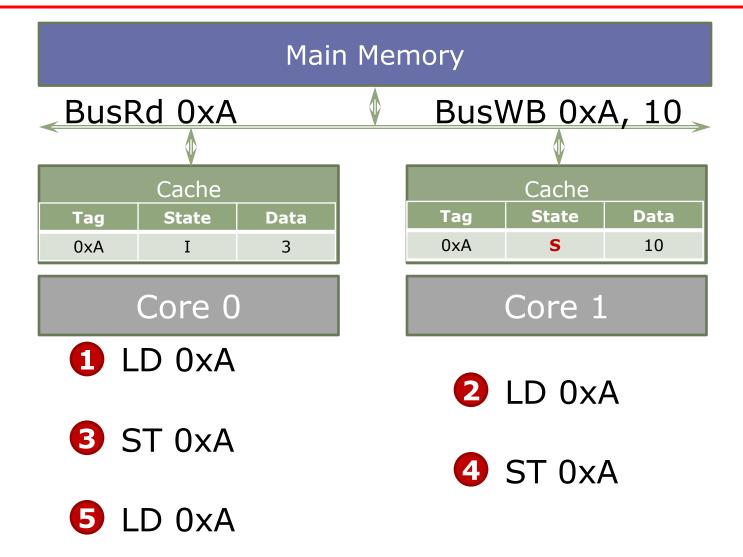
- MSI allows caches to serve writes without updating memory, so main memory can have stale data
 - Core 0's cache needs to supply data
 - But main memory may also respond!
- Cache must override response from main memory

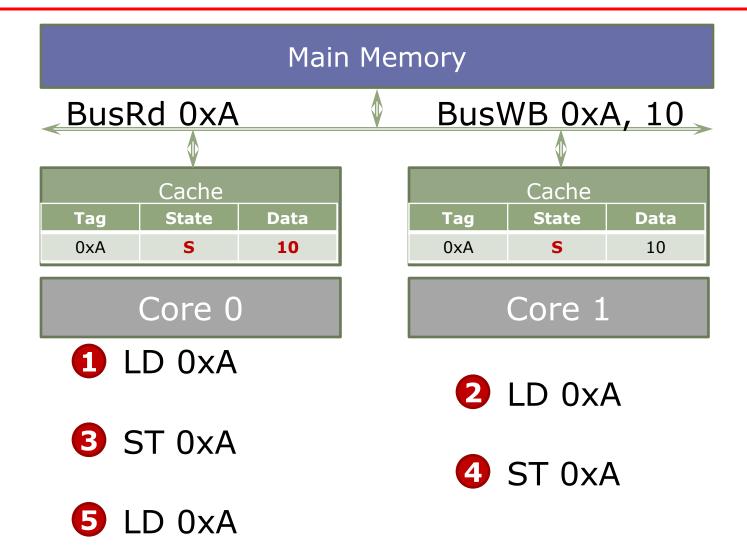












MSI Optimizations: Exclusive State

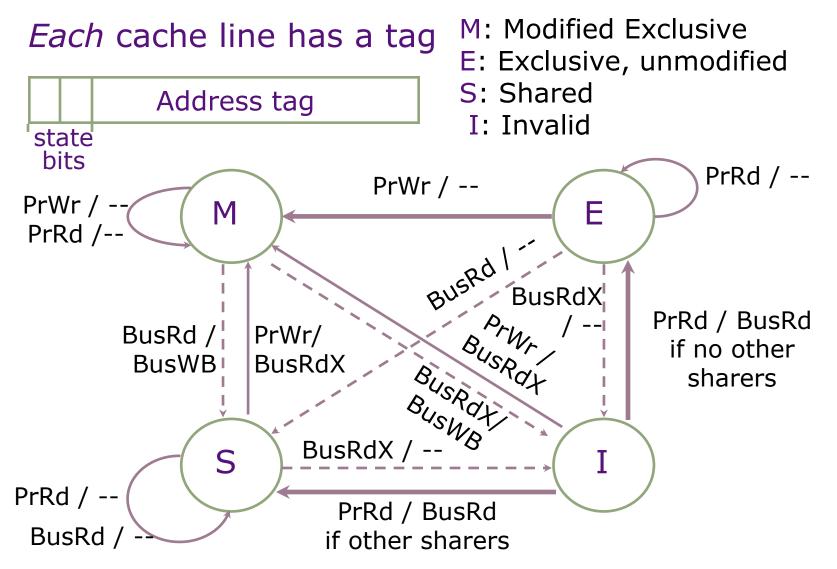
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MSI Optimizations: Exclusive State

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 - What's the problem with MSI?
- Solution: E state (exclusive, clean)
 - If no other sharers, a read acquires line in E instead of S
 - Writes silently cause E→M (exclusive, dirty)

MESI: An Enhanced MSI protocol

increased performance for private read-write data



- Observation: On M→S transitions, must write back line!
 - What happens with frequent read-write sharing?
 - Can we defer the write after S?

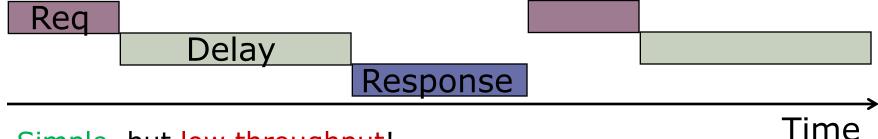
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- MSI, MESI, MOSI, MOESI...
 - Typically E if private read-write >> shared read-only (common)
 - Typically O only if writebacks are expensive (main mem vs L3)

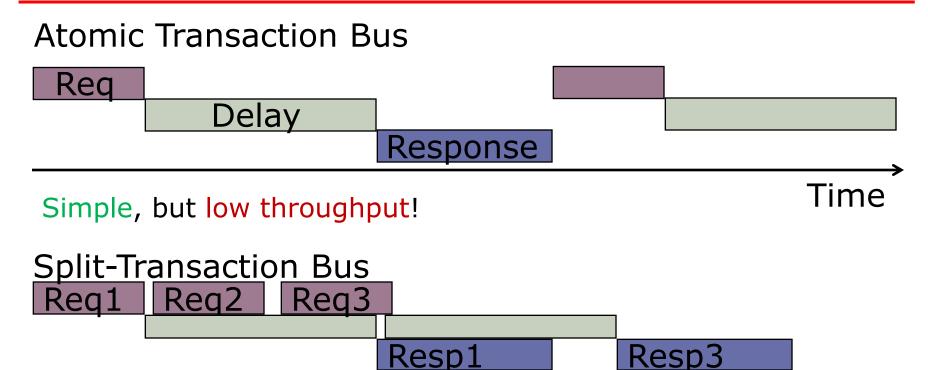
Split-Transaction and Pipelined Buses

Atomic Transaction Bus



Simple, but low throughput!

Split-Transaction and Pipelined Buses



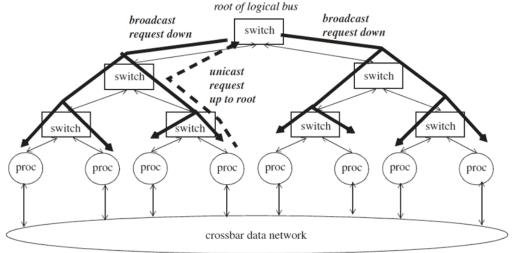
- Supports multiple simultaneous transactions
 - Higher throughput
 - Responses may arrive out of order
- Often implemented as multiple buses (req+resp)

Non-Atomicity → Transient States

Protocol must handle BusGnt / lack of atomicity PrWr / --PrRd BusRdX Two types of states Stable (e.g. MSI) **Transient** BusGnt / Μ Split + race BusInv transitions BusRd / Higher complexity s→M BusWB PrWr / BusRdX BusReq **Actions** S / BusWB **Bus Request** (BusReq) BusGnt / Bu\$RdX / --- $I \rightarrow M$ BusRd **Bus Grant** (BusGnt) I→S PrRd / --BusRd / --PrWr / PrRd / BusReq BusReq

Scaling Cache Coherence

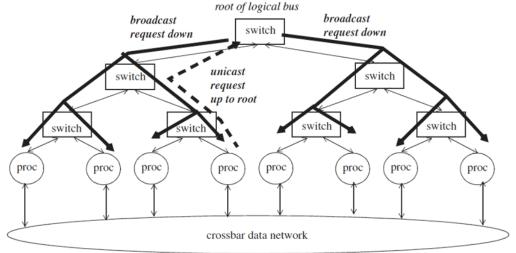
 Can implement ordered interconnects that scale better than buses...



Starfire E10000 (drawn with only eight processors for clarity). A coherence request is unicast up to the root, where it is serialized, before being broadcast down to all processors

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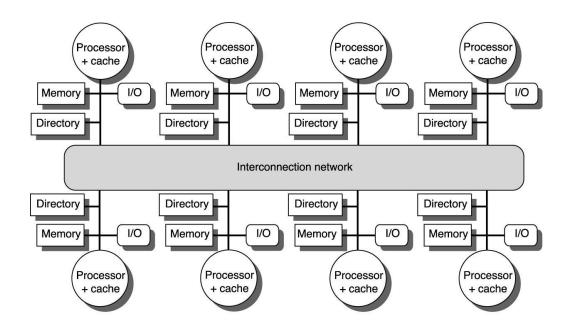
 Can implement ordered interconnects that scale better than buses...



Starfire E10000 (drawn with only eight processors for clarity). A coherence request is unicast up to the root, where it is serialized, before being broadcast down to all processors

- ... but broadcast is fundamentally unscalable
 - Bandwidth, energy of transactions with 100s of cache snoops?

Directory-Based Coherence



- Route all coherence transactions through a directory
 - Tracks contents of private caches → No broadcasts
 - Serves as ordering point for conflicting requests → Unordered networks

(more on next lecture)

CC and False Sharing Performance Issue - 1

state blk addr data0 data1 ... dataN

A cache block contains more than one word and cache coherence is done at the block-level and not word-level

Suppose P_1 writes word_i and P_2 writes word_k and both words have the same block address.

What can happen?

CC and False Sharing Performance Issue - 1

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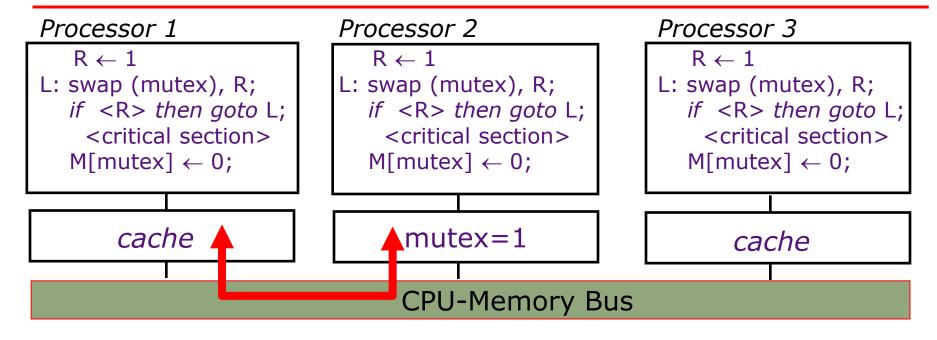
A cache block contains more than one word and cache coherence is done at the block-level and not word-level

Suppose P₁ writes word_i and P₂ writes word_k and both words have the same block address.

What can happen? The block may be invalidated (ping-pong) many times unnecessarily because addresses are in the same block.

CC and Synchronization

Performance Issue - 2



Cache coherence protocols will cause mutex to ping-pong between P1's and P2's caches.

Ping-ponging can be reduced by first reading the mutex location (non-atomically) and executing a swap only if it is found to be zero (test&test&set).

CC and Bus Occupancy Performance Issue - 3

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- ⇒ expensive for simple buses
- ⇒ *very expensive* for split-transaction buses

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modern processors use

load-reserve store-conditional

Load-reserve & Store-conditional

Special register(s) to hold reservation flag and address, and the outcome of store-conditional

```
Load-reserve R, (a):

<flag, adr> \leftarrow <1, a>;

R \leftarrow M[a];
```

```
Store-conditional (a), R:

if <flag, adr> == <1, a>

then cancel other procs'

reservation on a;

M[a] \leftarrow <R>;

status \leftarrow succeed;

else status \leftarrow fail;
```

If the snooper sees a store transaction to the address in the reserve register, the reserve bit is set to 0

- Several processors may reserve 'a' simultaneously
- These instructions are like ordinary loads and stores with respect to the bus traffic

Performance:

Load-reserve & Store-conditional

The total number of memory (bus) transactions is not necessarily reduced, but splitting an atomic instruction into load-reserve & storeconditional:

- increases bus utilization (and reduces) processor stall time), especially in splittransaction buses
- reduces cache ping-pong effect because processors trying to acquire a mutex do not have to perform stores each time