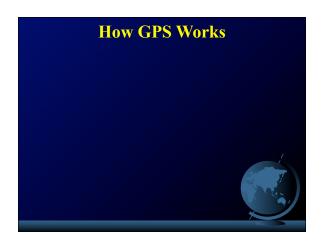
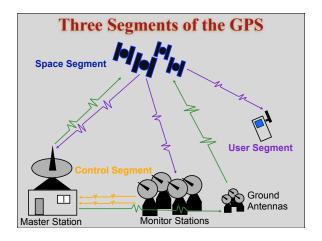


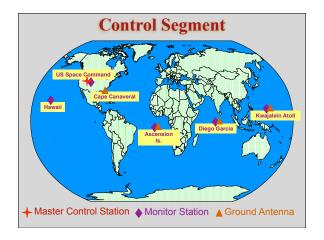
The History of GPS

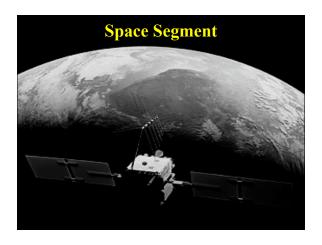
- Ø Feasibility studies begun in 1960's.
- Pentagon appropriates funding in 1973.
- ø First satellite launched in 1978.
- ^Ø System declared fully operational in April, 1995.











User Segment

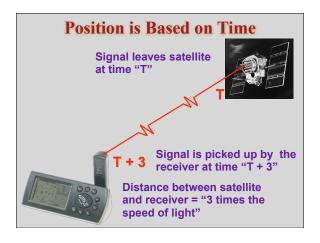
- ø Military.
- Ø Search and rescue.
- ø Disaster relief.
- ø Surveying.
- ^Ø Marine, aeronautical and terrestrial navigation.
- Ø Remote controlled vehicle and robot guidance.
- Satellite positioning and tracking.
- Ø Shipping.
- ⁰ Geographic Information Systems (GIS).
- ø Recreation.

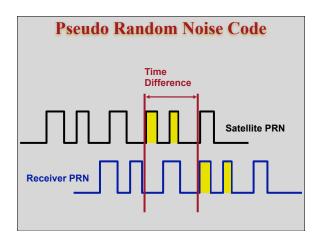


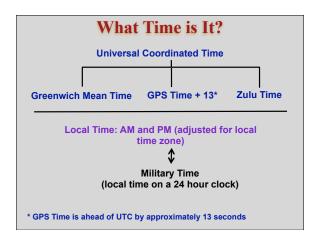
Four Basic Functions of GPS

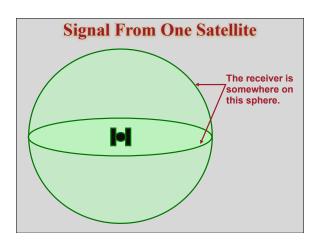
- Ø Position and coordinates.
- O The distance and direction between any two waypoints, or a position and a waypoint.
- Ø Travel progress reports.
- Ø Accurate time measurement.

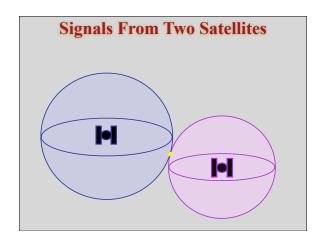


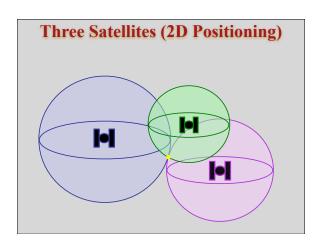


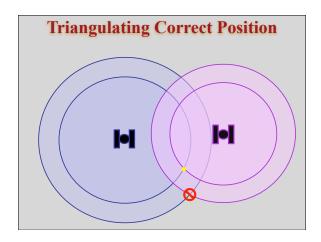


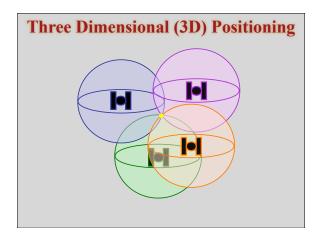












Selective Availability (S/A)

- O The Defense Department dithered the satellite time message, reducing position accuracy to some GPS users.
- S/A was designed to prevent America's enemies from using GPS against us and our allies.
- Ø In May 2000 the Pentagon reduced S/A to zero meters error.
- [©] S/A could be reactivated at any time by the Pentagon.

Sources of GPS Error

Standard Positioning Service (SPS): Civilian Users

Source Amount of Error

Satellite clocks: 1.5 to 3.6 meters

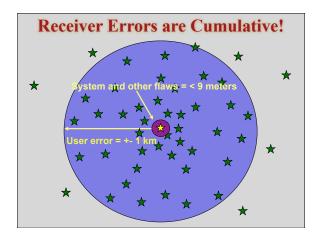
Ø Orbital errors: < 1 meter

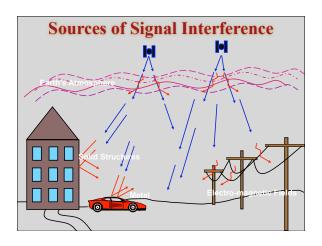
O Ionosphere:
 ○ Troposphere:
 ○ Receiver noise:
 ○ Multipath:
 5.0 to 7.0 meters
 0.5 to 0.7 meters
 0.3 to 1.5 meters
 0.6 to 1.2 meters

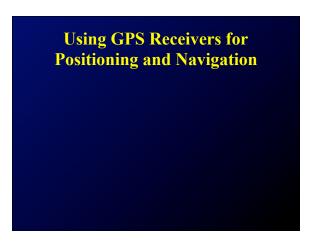
Selective Availability (see notes)

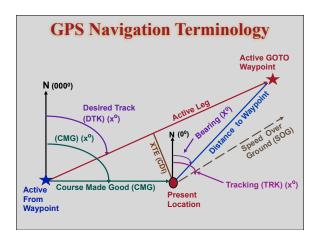
O User error: Up to a kilometer or more

Errors are cumulative and increased by PDOP.











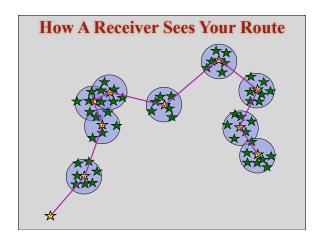
Position Fix

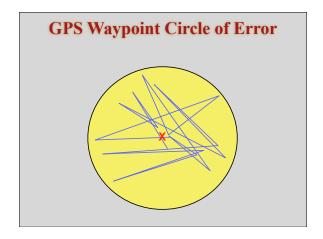
- ø A position is based on real-time satellite tracking.
- ø It's defined by a set of coordinates.
- Ø It has no name.
- O A position represents only an *approximation* of the receiver's true location.
- A position is not static. It changes constantly as the GPS receiver moves (or wanders due to random errors).
- A receiver must be in 2D or 3D mode (at least 3 or 4 satellites acquired) in order to provide a position fix.
- Ø 3D mode dramatically improves position accuracy.

Waypoint

- A waypoint is based on coordinates entered into a GPS receiver's memory.
- It can be either a saved position fix, or user entered coordinates.
- o It can be created for any remote point on earth.
- It must have a receiver designated code or number, or a user supplied name.
- Once entered and saved, a waypoint remains unchanged in the receiver's memory until edited or deleted.







GPS Dilution of Precision and Its Affects On GPS Accuracy

GPS Satellite Geometry

- Satellite geometry can affect the quality of GPS signals and accuracy of receiver trilateration.
- Dilution of Precision (DOP) reflects each satellite's position relative to the other satellites being accessed by a receiver.
- o There are five distinct kinds of DOP.
- O Position Dilution of Precision (PDOP) is the DOP value used most commonly in GPS to determine the quality of a receiver's position.
- It's usually up to the GPS receiver to pick satellites which provide the best position triangulation.
- O Some GPS receivers allow DOP to be manipulated by the user.

