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A Base Language Evaluator for  $\lambda$ -Calculus Expressions

by

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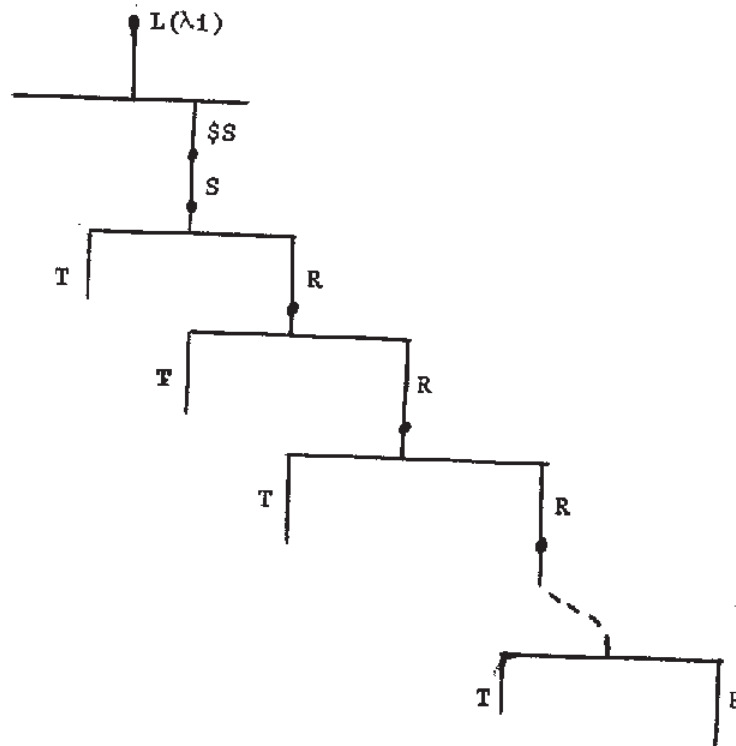
As a sequel to CSG Memo 74 [1], we offer a scheme for translating expressions in the  $\lambda$ -Calculus [2] into procedures structures of the Base Language [3, 4]. The Base Language (BL) interpreter, acting on these control structures, mimics the SECD evaluation [5] of the corresponding  $\lambda$ -Calculus ( $\lambda$ C) expression.

See [1] for brief introductory discussions of  $\lambda$ C expressions and their order of evaluation.

## The Stack

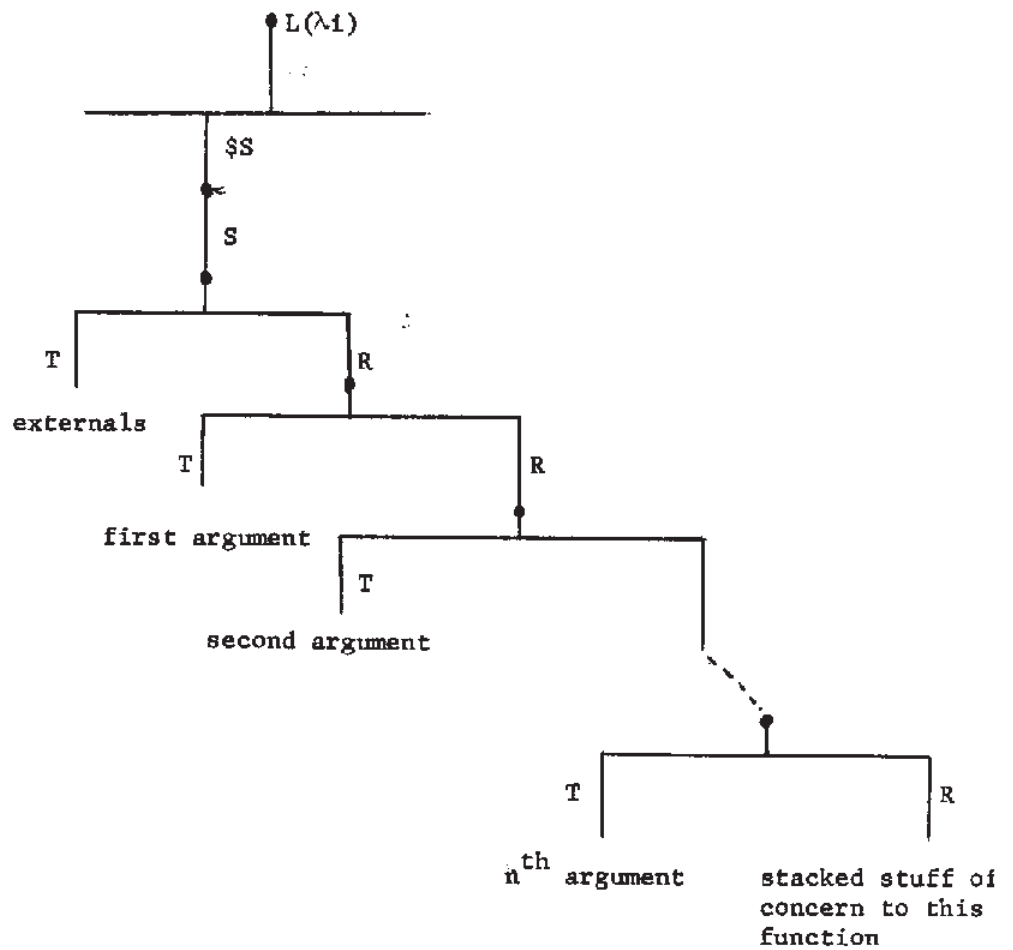
The SECD evaluator is organized around a stack of partially completed results. All computations are carried out from or to this stack. The BL has no such stack, a priori; we therefore establish conventions which maintain a structure fulfilling, by interpretation, the role of the SECD stack.

In each local structure, the stack is selected by  $\$S$ . It has the following structure:

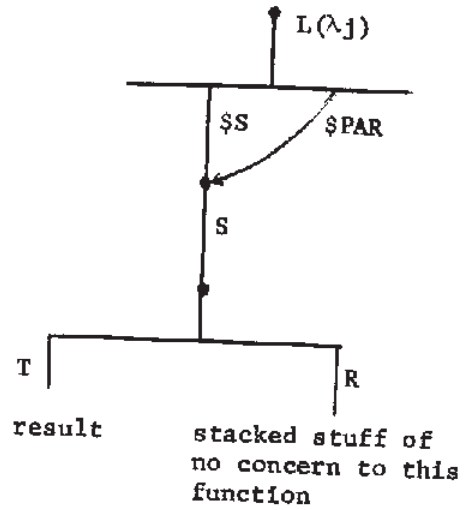


Thus the top-of-stack is selected by  $\$S \cdot S \cdot T$ ; and the  $n^{\text{th}}$  element on the stack (for top:  $n = 0$ ) by  $\$S \cdot S \cdot R^n \cdot T$ .

In the SECD evaluator, each function takes its arguments from the stack, and returns its result by placing it back on the top-of-stack. The BL interpreter passes an argument structure which contains parameters and bindings for external (free) variables of the function being called. We combine these two sets of conventions by placing the external binds on the top-of-stack and passing the resulting stack as the argument structure. Thus just before apply is evaluated the local structure in part looks like:

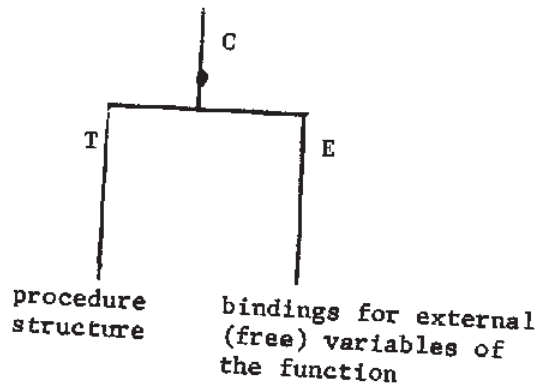


and just before return is executed (in the called function) the local structure in part looks like:



Closures

Functions in the BL are represented by C-structures:



We will use the same structure for representing closures of  $\lambda$ -expressions.

At translation time, the external variables of each  $\lambda$ -expression is known, and so BL instruction can be composed to appropriately determine the bindings of these externals. Specifically when a closure is being formed, the externals are gathered into the E-component of the C-structure; when the closure is called, the E-component is placed on top-of-stack; at the beginning of the code of a function, the E-component (top-of-stack) is torn apart and made part of the local structure of the function, thus providing the external bindings necessary for its evaluation.

Overview of Translation

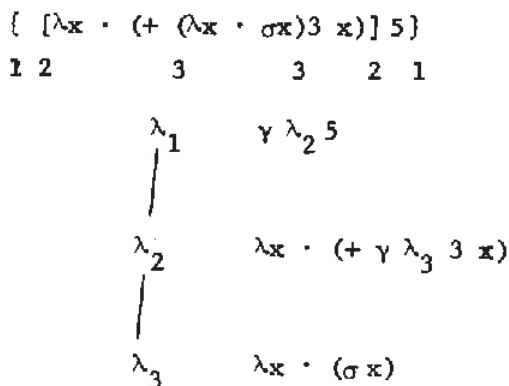
It is convenient to describe the rules for translating a  $\lambda$ C-expression into a BL procedure structure as a three-step process.

1. Produce a hierarchical structure representing the procedures to be produced and their nesting.
2. Translate the body of each procedure into a sequence of macro calls
3. Expand the macro calls into BL instructions.

Hierarchical Structure (Step 1)

This step is identical to part of the process used in the translation process from  $\lambda$ C-expressions to Contour Model algorithms. See Steps 1 and 2 of [1]. It results in a tree of  $\lambda$ -expressions reflecting the nesting of the given  $\lambda$ C-expression. The body for each expression is presented near the appropriate node in the tree, and is expressed in Prefix-Polish form with all the apply operators expressed.

Example:



Body Translation (Step 2)

The body of each node in the hierarchical structure is translated from Prefix-Polish form to a sequence of calls on a collection of macros. These macros embody the conventions used to mimic to SECD evaluation.

There are two cases: the top level expression, and all other expressions. They differ in that the top-level expression does not need to concern itself with parameters or externals, and needs to "output" a final result rather than "return" it to a caller.

Case 1 (top level): The translation is:

```
crstack ; create stack initially
<translate the body>
output ; "output" the final result
```

Case 2 ( $\lambda$ -expressions): The translation is:

```
setstack ; access and unstack externals
ext {{list of free variables}} ; select externals
arg ; unstack and select arguments
<translate the body>
result is ; return value to caller
```

Common body translation: Translation is done right-to-left on the Prefix-Polish string representing the body. The rules are as follows:

<u>Type of Thing</u>	<u>Translation</u>	<u>Purpose of Macro</u>
constants:	value <constant> push \$AC	; create constant ; stack new value
variable:	push <variable>	; stack value of variable
$\lambda$ -expression:	close ( $\lambda$ -expr), {{list of free variables}} push \$AC	; compute a closure ; stack closure
application:	call	; apply a closure
primitive operator:	<primitive oper- ator macro>	; execute primitive operator

Example: We use the example we started in Step 1. It uses two primitives operators, addition and the successor function, + and  $\sigma$ . The corresponding primitive macros are plus and succ. There are no free variables in this example.

```
 $\lambda_1$ :  crstack
       value 5
       push $AC
       close  $\lambda_2$ , { }
       push $AC
       call
       output
```

```
 $\lambda_2$ :  set stack
       ext { }
       arg x
       push x
       value 3
       push $AC
       close  $\lambda_3$ , { }
       push $AC
       call
       plus
       resultsis
```

```
 $\lambda_3$ :  setstack
       ext { }
       arg x
       push x
       succ
       resultis
```

Macro Expansion (Step 3)

The result of Step 2 is a series of macro calls. This step involves expanding these macros into BL instructions. \$AC is used to hold temporary results, such as those produced by value and close.

Note that some macros are used in the definition of others. The macro definitions are:

crstack		create	\$S · S
		create	\$AC
setstack		share	\$PAR, \$S
		create	\$AC
ext {e <sub>1</sub> , e <sub>2</sub> , ..., e <sub>n</sub> }	for each e <sub>i</sub> :	pop	\$E
		link	\$E, e <sub>i</sub> , e <sub>i</sub>
		delete	\$E
arg n		pop	n
resultis		return	
output		pop	\$AC
		print	\$AC
value n		const	n, \$AC
close λ <sub>i</sub> , {e <sub>1</sub> , e <sub>2</sub> , ..., e <sub>n</sub> }		delete	\$AC
		create	\$AC
		move	λ <sub>i</sub> , \$AC · C · T
		create	\$AC · C · E
	for each e <sub>i</sub> :	link	\$AC · C · E, e <sub>i</sub> , e <sub>i</sub>
call		select	\$S · S, T, \$F
		delete	\$S · S, T
		link	\$S · S, T, \$F · C · E
		apply	\$F, \$S
		delete	\$F



push n		select	\$S, S, \$T
		delete	\$S, S
		assign	n, \$S · S · T
		link	\$S · S, R, \$T
		delete	\$T
pop n		select	\$S · S, T, n
		select	\$S · S, R, \$T
		delete	\$S, S
		link	\$S, S, \$T
		delete	\$T
plus	either:	pop	\$A1
		pop	\$A2
		add	\$A1, \$A2, \$AC
		push	\$AC
	or:	pop	\$AC
		add	\$S · S · T, \$AC, \$S · S · T
succ	either:	pop	\$A1
		add	\$A1, 1, \$A1
		push	\$A1
	or:	add	\$S · S · T, 1, \$S · S · T

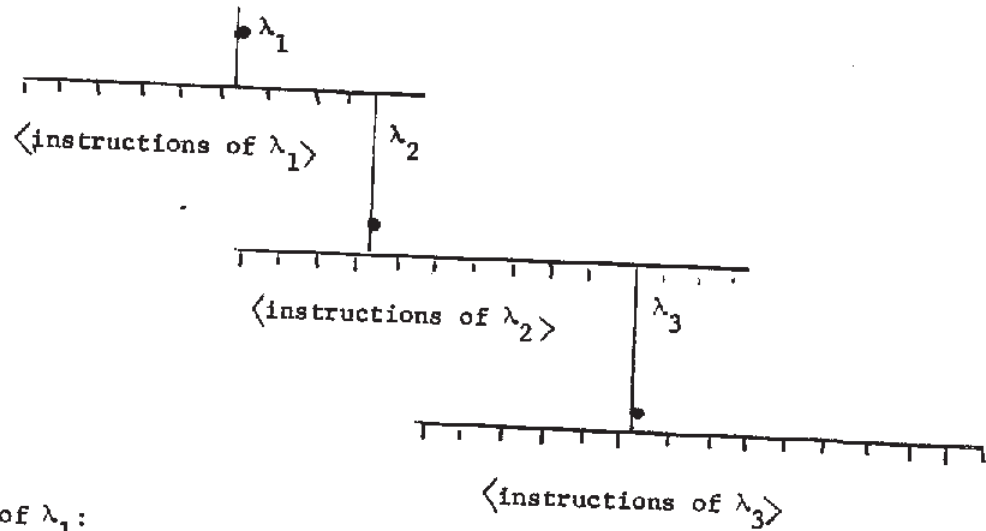
A study of the actions of a program will indicate that these macros do in fact enforce the stack and closure conventions described above.

The share primitive used in setstack is simply a way of renaming the \$PAR component of the local structure. Thus all the macros can be written in terms of \$S. Of course, \$PAR could be substituted every where for \$S to achieve the same result. Notice that share is necessary because link provides sharing only at one level removed from the local structure. [Question: Should a generalized share primitive be used to accomplish both these kinds of sharing?].

Note that some care is taken to assure that the temporaries \$AC and \$T are defined properly for the primitives of the BL as given in [3] and [4].

The two expansions of plus and succ are provided so as 1) to make clear the actions of these macros and 2) be a little less inefficient in accomplishing those actions. The final configurations of the stack are identical.

Example: To complete the example used above the macros are expanded. Integer selectors are added to the instructions generated, and the procedure structures nested as indicated by Step 1, to yield a single translated procedure structure.



Instructions of  $\lambda_1$ :

0	create	\$S.S		
1	create	\$AC		; crstack
3	const	5, \$AC		
3	select	\$S, S, \$T		; value 5
4	delete	\$S, S		; push \$AC
5	assign	\$AC, \$S.S.T		
6	link	\$S.S, R, \$T		
7	delete	\$T		
8	delete	\$AC		
9	create	\$AC		; close $\lambda_2$ , { }
10	move	$\lambda_2$ , \$AC.C.T		
11	create	\$AC.C.E		
12	select	\$S, S, \$T		
13	delete	\$S, S		; push \$AC
14	assign	\$AC, \$S.S.T		
15	link	\$S.S, R, \$T		

```
16  delete  $T
17  select  $$·S, T, $F                ; call
18  delete  $$·S, T
19  link    $$·S, T, $F·C·E
20  apply   $F, $S
21  delete  $F
22  select  $$·S, T, $AC              ; output ... ; pop $AC
23  select  $$·S, R, $T
24  delete  $$, S
25  link    $$, S, $T
26  delete  $T
27  print   $AC                      ; print $AC
```

Instructions of  $\lambda_2$ :

```
0   share  $PAR, $S                ; setstack
1   create  $AC
2   select  $$·S, T, $E              ; ext ( ) ; pop $E
3   select  $$·S, R, $T
4   delete  $$, S
5   link    $$, S, $T
6   delete  $T
7   delete  $E
8   select  $$·S, T, x                ; delete $E
9   select  $$·S, R, $T              ; arg x ; pop x
10  delete  $$, S
11  link    $$, S, $T
12  delete  $T
13  select  $$, S, $T                ; push x
14  delete  $$, S
15  assign  x, $$·S·T
16  link    $$·S, R, $T
17  delete  $T
```

```
18   const    3, $AC
19   select   $S, S, $T
20   delete   $S, S
21   assign   $AC, $$S·S·T
22   link     $$S·S, R, $T
23   delete   $T
24   delete   $AC
25   create   $AC
26   move      $\lambda_3$ , $AC·C·T
27   create   $AC·C·E
28   select   $S, S, $T
29   delete   $S, S
30   assign   $AC, $$S·S·T
31   link     $$S·S, R, $T
32   delete   $T
33   select   $$S·S, T, $F
34   delete   $$S·S, T
35   link     $$S·S, T, $F·C·E
36   apply    $F, $$S
37   delete   $F
38   select   $$S·S, T, $AC
39   select   $$S·S, R, $T
40   delete   $S, S
41   link     $S, S, $T
42   delete   $T
43   add      $$S·S·T, $AC, $$S·S·T
44   return
```

; value 3  
; push \$AC  
; else  $\lambda_3$ , [ ]  
; push \$AC  
; call  
; plus ; pop \$AC  
; add  
; resultis

Instructions of  $\lambda_3$ :

```
0   share   $PAR, $S                               ;   setstack
1   create  $AC
2   select  $$·S, T, $E                             ;   ext ( )       ;   pop . $
3   select  $$·S, R, $T
4   delete  $$, S
5   link    $$, S, $T
6   delete  $T
7   delete  $E                                       ;   delete $l
8   select  $$·S, T, x                               ;   arg x       ;   pop x
9   select  $$·S, R, $T
10  delete  $$, S
11  link    $$, S, $T
12  delete  $T
13  select  $$, S, $T                               ;   push x
14  delete  $$, S
15  assign  x, $$·S·T
16  link    $$·S, R, $T
17  delete  $T
18  add     $$·S·T, 1, $$·S·T                       ;   succ
19  return  ;   resultis
```

Efficiency

A study of the above BL code reveals that a certain amount of optimization is possible. For example, instructions 7 through 14 may be deleted from  $\lambda_2$  and 7 through 14 from  $\lambda_3$ . Both sets implement a "pop x" followed by a "push x", and as x is only used once in each piece of code there is no need to have x ever appear in the local structure. However, the translation rule is quite general, and we are not writing an optimizing translator (compiler). Such non-optimal code may be quite common; this does not concern us here.

### More Complex Examples

The reader may wish to check that this translation scheme is successful for some more complex examples. The following examples are used in [1], and afford interesting three-way comparisons between the  $\lambda_C$ , BL, and CM.

$$\{[\lambda f \cdot (\lambda f \cdot f3)(\lambda x \cdot (fx) + 2)][\lambda x \cdot x + 1]\}$$

$$\{[\lambda g \cdot (\lambda a \cdot (ga)5) 4][\lambda y \cdot (\lambda a \cdot (\lambda g \cdot g)(\lambda x \cdot x + a + y)) 3]\}$$

### Recursion

The BL is neither block structured nor "inherently" recursive. Explicit actions necessary to translate recursive programs so that references are correct; namely, that a C-structure can be referred to by the text of the function which is its T-component. Two means are possible for achieving this: some identifier in the E-component can reference the C-structure (thus introducing a cycle to the interpreter state), or the C-structure can be passed as an argument to the function. In either case, the C-structure is accessible from the local structure of the activation of the function, which means that it can be invoked recursively.

As pointed out in [1], there is no need to deal specially with recursion when translating  $\lambda_C$ -expressions for a recursion-making operator, Y, can be expressed as a  $\lambda_C$ -expression itself. The rules we have will thus permit recursion as they stand. However, they do so in a complex way including creation at every level of recursion of new C-structures which represent "the same function." See [6].

We can bypass this circumlocution by giving an explicit rule for translating  $Y(\lambda f \cdot \lambda x \cdot \text{---})$ .



For translation's sake, we re-write  $\lambda_3$  as

$$\lambda x \cdot \delta_1 \delta_2 \beta \leq x \ 1$$

where

$$\delta_1 = 1$$

$$\delta_2 = * \gamma f - x \ 1 x$$

$\lambda_1$  translates:        crstack  
                          rclose  $\lambda_3$ , f, { }  
                          close  $\lambda_2$   
                          call  
                          output

$\lambda_2$  translates:        as before

$\lambda_3$  translates:        setstack  
                          ext {f}  
                          arg x  
                          value 1  
                          push \$AC  
                          push x  
                          le                                ; less than or equal  
                          test  $\delta_1$ ,  $\delta_2$   
                          resultis

$\delta_1$  translates:        value 1  
                          push \$AC

$\delta_2$  translates:        push x  
                          value 1  
                          push \$AC  
                          push x  
                          minus  
                          push f  
                          call  
                          multiply



The expansions are lengthy and straightforward and so are omitted. The expansion of test includes compiling the obvious jumps to include the code for  $\delta_1$  and  $\delta_2$ , as follows:

```
test  $\delta_i, \delta_j$       k      pop      $AC
                      k+4    if        $AC      goto    l+1
                      k+5    <expansion of  $\delta_i$ >
                      l      goto     m
                      l+1    <expansion of  $\delta_j$ >
                      m
```

### Conclusion

This memo gives an algorithm for translating  $\lambda$ -calculus expressions into procedure structures for the Base Language so that the BL interpreter simulates the SECD evaluation of the  $\lambda$ C-expressions. The algorithm depends on supplying names for the  $\lambda$ -expressions in the  $\lambda$ C-expressions.

Although recursion is provided for by the  $\lambda$ -calculus itself, it is more appealing to provide for it explicitly in the Base Language. Consequently, a special rule for translating " $\Upsilon(\lambda f . \lambda x . \text{---})$ " is given which yields algorithms causing the Base Language interpreter to achieve the recursion effect of the  $\lambda$ -calculus " $\Upsilon$ " operator.

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