6.823 Computer System Architecture

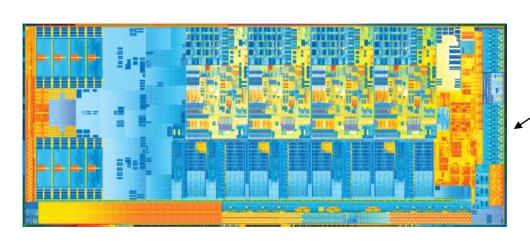
Instructors: Joel Emer

Mengjia Yan

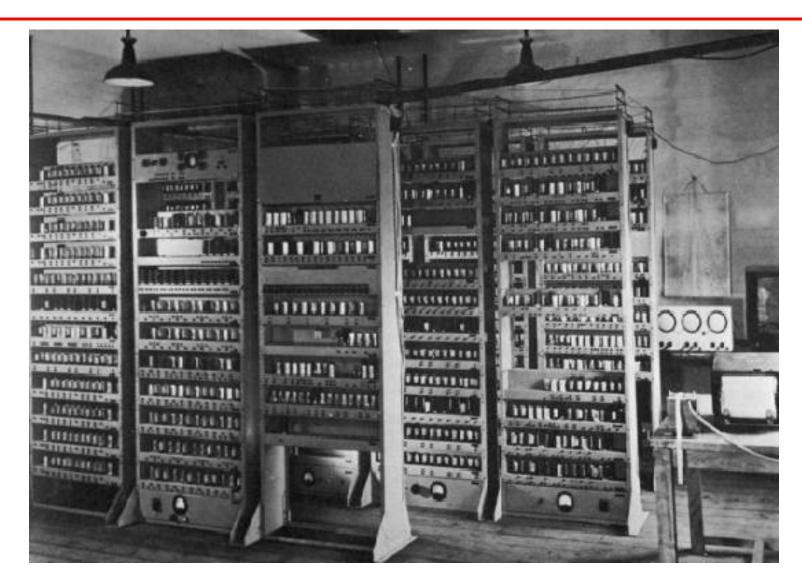
TAs: Atalay Ileri

Miguel Gomez-Garcia

The processor you built in 6.004



Computing devices then...



Computing devices now









A journey through this space

What do computer architects actually do?

A journey through this space

- What do computer architects actually do?
- Illustrate via historical examples
 - Early days: ENIAC, EDVAC, and EDSAC
 - Arrival of IBM 650 and then IBM 360
 - Seymour Cray CDC 6600, Cray 1
 - Microprocessors and PCs
 - Multicores
 - Cell phones

A journey through this space

- What do computer architects actually do?
- Illustrate via historical examples
 - Early days: ENIAC, EDVAC, and EDSAC
 - Arrival of IBM 650 and then IBM 360
 - Seymour Cray CDC 6600, Cray 1
 - Microprocessors and PCs
 - Multicores
 - Cell phones
- Focus on ideas, mechanisms, and principles, especially those that have withstood the test of time

Application

Algorithm

Programming Language

Operating System/Virtual Machine

Instruction Set Architecture (ISA)

Microarchitecture

Register-Transfer Level (RTL)

Circuits

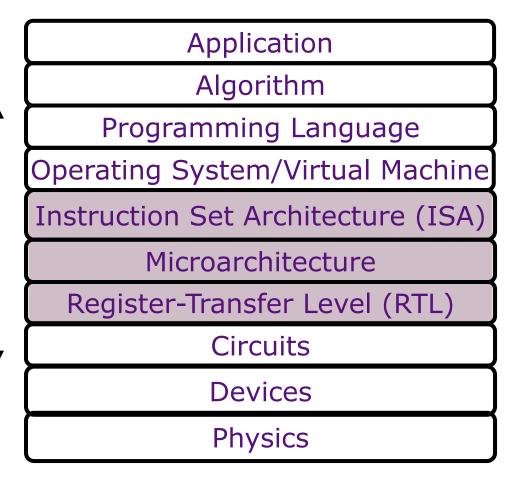
Devices

Physics

Application Algorithm Programming Language Original Operating System/Virtual Machine domain of Instruction Set Architecture (ISA) the computer Microarchitecture architect Register-Transfer Level (RTL) ('50s-'80s) Circuits Devices **Physics**

Application Algorithm Programming Language Original Operating System/Virtual Machine domain of Instruction Set Architecture (ISA) the Domain of computer computer Microarchitecture architect architecture ('90s) Register-Transfer Level (RTL) ('50s-'80s) Circuits Devices **Physics**

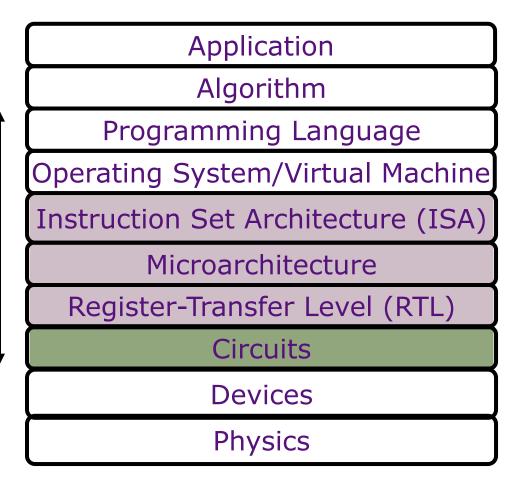
Original domain of the computer architect ('50s-'80s)



Domain of computer architecture ('90s)

Expansion of computer architecture, mid-2000s onward.

Original domain of the computer architect ('50s-'80s)

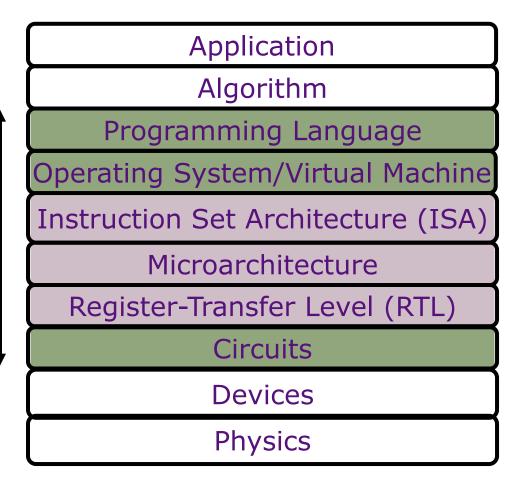


Domain of computer architecture ('90s)

Reliability, power

Expansion of computer architecture, mid-2000s onward.

Original domain of the computer architect ('50s-'80s)



Parallel computing, specialization, security, ...

Domain of computer architecture ('90s)

Reliability, power

Expansion of computer architecture, mid-2000s onward.

Computer Architecture is the design of abstraction layers

Computer Architecture is the design of abstraction layers

- What do abstraction layers provide?
 - Environmental stability within generation
 - Environmental stability across generations
 - Consistency across a large number of units

Computer Architecture is the design of abstraction layers

What do abstraction layers provide?

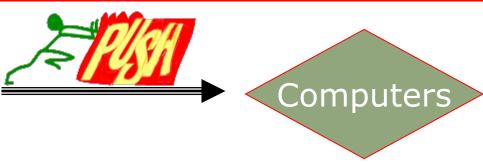
- Environmental stability within generation
- Environmental stability across generations
- Consistency across a large number of units

What are the consequences?

- Encouragement to create reusable foundations:
 - Toolchains, operating systems, libraries
- Enticement for application innovation

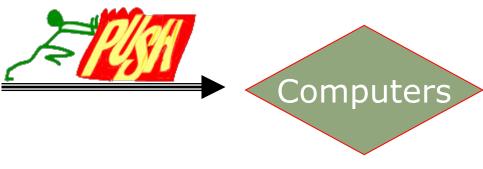
Technology

Transistors
Integrated circuits
VLSI (initially)
Flash memories, ...



Technology

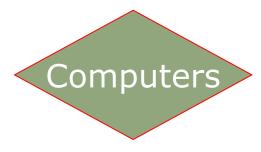
Transistors
Integrated circuits
VLSI (initially)
Flash memories, ...



Technology

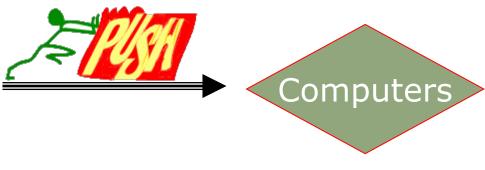
Core memories Magnetic tapes Disks





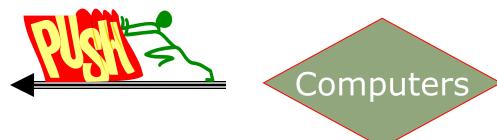
Technology

Transistors
Integrated circuits
VLSI (initially)
Flash memories, ...



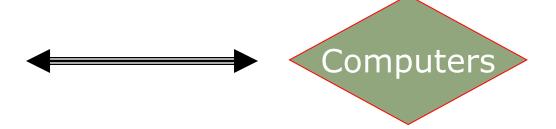
Technology

Core memories Magnetic tapes Disks



Technology

ROMs, RAMs VLSI Packaging Low Power



As people write programs and use computers, our understanding of *programming* and *program behavior* improves.

This has profound though slower impact on computer architecture

As people write programs and use computers, our understanding of *programming* and *program behavior* improves.

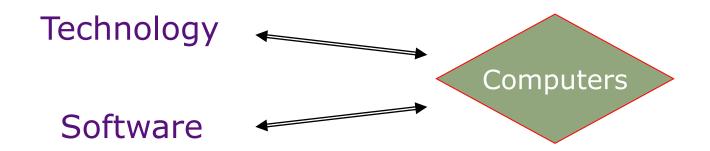
This has profound though slower impact on computer architecture

Modern architects must pay attention to software and compilation issues.

As people write programs and use computers, our understanding of *programming* and *program behavior* improves.

This has profound though slower impact on computer architecture

Modern architects must pay attention to software and compilation issues.



- Performance of whole system on target applications
 - Average case & worst case

- Performance of whole system on target applications
 - Average case & worst case
- Cost of manufacturing chips and supporting system

- Performance of whole system on target applications
 - Average case & worst case
- Cost of manufacturing chips and supporting system
- Power to run system
 - Peak power & energy per operation

- Performance of whole system on target applications
 - Average case & worst case
- Cost of manufacturing chips and supporting system
- Power to run system
 - Peak power & energy per operation
- Reliability of system
 - Soft errors & hard errors

- Performance of whole system on target applications
 - Average case & worst case
- Cost of manufacturing chips and supporting system
- Power to run system
 - Peak power & energy per operation
- Reliability of system
 - Soft errors & hard errors
- Cost to design chips (engineers, computers, CAD tools)
 - Becoming a limiting factor in many situations, fewer unique chips can be justified

- Performance of whole system on target applications
 - Average case & worst case
- Cost of manufacturing chips and supporting system
- Power to run system
 - Peak power & energy per operation
- Reliability of system
 - Soft errors & hard errors
- Cost to design chips (engineers, computers, CAD tools)
 - Becoming a limiting factor in many situations, fewer unique chips can be justified
- Cost to develop applications and system software
 - Often the dominant constraint for any programmable device

Factors to consider:

- Performance of whole system on target applications
 - Average case & worst case
- Cost of manufacturing chips and supporting system
- Power to run system
 - Peak power & energy per operation
- Reliability of system
 - Soft errors & hard errors
- Cost to design chips (engineers, computers, CAD tools)
 - Becoming a limiting factor in many situations, fewer unique chips can be justified
- Cost to develop applications and system software
 - Often the dominant constraint for any programmable device

At different times, and for different applications at the same point in time, the relative balance of these factors can result in widely varying architectural choices

Course Information

All info kept up to date on the website:

http://www.csg.csail.mit.edu/6.5900

Contact times

- Lectures on Monday and Wednesday
 - 1:00pm to 2:30pm in room 32-141
- Tutorial on Friday
 - 1:00pm to 2:00pm in room 32-141
 - Attendance is optional
 - Additional tutorials will be held in evenings before quizzes
- Quizzes on Friday (except last quiz)
 - 1:00pm to 2:30pm in room 32-141
 - Attendance is NOT optional
- Instructor office hours
 - After class or by email appointment
- TA office hours
 - Monday 10:00 am-12:00 pm @ Stata 9th floor lounge
 - Wednesday 3:00-5:00 pm @ Stata 9th floor lounge

"New normal" policies

- We're excited to be back in a classroom, but want everyone to be and feel safe
- We'll record videos of lectures and tutorials for students who need to miss a lecture
 - Due to isolation/quarantine, visa issues, case spikes, etc.
 - However, these videos will be best-effort
 - They are not aimed to serve as an online course
- If you feel uncomfortable with any aspect of our inperson interactions, please let us know

Online resources & help

- We use Piazza extensively
 - Fastest way to get your questions answered
 - All course announcements are made on Piazza
- This is still not quite a normal term;
 If you need help, let us know!
 - We can be accommodating

The course has three modules

Module 1

- ISA and Simple In-Order Pipelines
- Caches and Virtual Memory
- Complex Pipelining and Out-of-Order Execution
- Branch Prediction and Speculative Execution

Module 2

- Multithreading and Multiprocessors
- Coherence and consistency
- On-chip networks

Module 3

- Microcoding and VLIW
- Vector machines and GPUs
- Hardware accelerators
- Hardware security

The course has three modules

Module 1

- ISA and Simple In-Order Pipelines
- Caches and Virtual Memory
- Complex Pipelining and Out-of-Order Execution
- Branch Prediction and Speculative Execution

Module 2

- Multithreading and Multiprocessors
- Coherence and consistency
- On-chip networks

Module 3

- Microcoding and VLIW
- Vector machines and GPUs
- Hardware accelerators
- Hardware security

Textbook and readings

- "Computer Architecture: A Quantitative Approach", Hennessy & Patterson, 5th / 6th ed.
 - 5th edition available online through MIT Libraries
 - Recommended, but not necessary

 Course website lists H&P reading material for each lecture, and optional readings that provide more in-depth coverage

Grading

- Grades are not assigned based on a predetermined curve
 - Most of you are capable of getting an A
- 75% of the grade is based on three closed book
 1.5 hour quizzes
 - The first two quizzes will be held during the tutorials; the last one during the last lecture (dates on web syllabus)
 - We'll have makeups if needed
- 25% of the grade is based on four laboratory exercises
- No final exam
- No final project

Problem sets & labs

Problem sets

- One problem set per module, not graded
- Intended for private study and for tutorials to help prepare for quizzes
- Quizzes assume you are very familiar with the content of problem sets

Labs

- Four graded labs
- Based on widely-used PIN tool
- Labs 2 and 4 are open-ended challenges

You must complete labs & quizzes individually

Please review the collaboration & academic honesty policy

Self evaluation take-home quiz

- Goal is to help you judge for yourself whether you have prerequisites for this class, and to help refresh your memory
- We assume that you understand digital logic, a simple 5-stage pipeline, and simple caches
- Please work by yourself on this quiz not in groups
- Remember to complete self-evaluation section at end of the quiz
- Due by Friday (on recitation or send answers to TA mailing list)

Please contact us if you have concerns about your ability to take the class

Early Developments: From ENIAC to the mid 50's

Prehistory

- 1800s: Charles Babbage
 - Difference Engine (conceived in 1823, first implemented in 1855 by Scheutz)
 - Analytic Engine, the first conception of a general-purpose computer (1833, never implemented)
- 1890: Tabulating machines
- Early 1900s: Analog computers
- 1930s: Early electronic (fixed-function) digital computers

Electronic Numerical Integrator and Computer (ENIAC)

- Designed and built by Eckert and Mauchly at the University of Pennsylvania during 1943-45
- The first, completely digital, electronic, operational, general-purpose analytical calculator!
 - 30 tons, 72 square meters, 200KW
- Performance
 - Read in 120 cards per minute
 - Addition took 200 μs, Division 6 ms
- Not very reliable!

Electronic Numerical Integrator and Computer (ENIAC)

- Designed and built by Eckert and Mauchly at the University of Pennsylvania during 1943-45
- The first, completely digital, electronic, operational, general-purpose analytical calculator!
 - 30 tons, 72 square meters, 200KW
- Performance
 - Read in 120 cards per minute
 - Addition took 200 μs, Division 6 ms
- Not very reliable!

WW-2 Effort

Application: Ballistic calculations



Electronic Discrete Variable Automatic Computer (EDVAC)

- ENIAC's programming system was external
 - Sequences of instructions were executed independently of the results of the calculation
 - Human intervention required to take instructions "out of order"

Electronic Discrete Variable Automatic Computer (EDVAC)

- ENIAC's programming system was external
 - Sequences of instructions were executed independently of the results of the calculation
 - Human intervention required to take instructions "out of order"
- EDVAC was designed by Eckert, Mauchly, and von Neumann in 1944 to solve this problem
 - Solution was the *stored program computer*
 - ⇒ "program can be manipulated as data"

Electronic Discrete Variable Automatic Computer (EDVAC)

- ENIAC's programming system was external
 - Sequences of instructions were executed independently of the results of the calculation
 - Human intervention required to take instructions "out of order"
- EDVAC was designed by Eckert, Mauchly, and von Neumann in 1944 to solve this problem
 - Solution was the stored program computer
 - ⇒ "program can be manipulated as data"
- First Draft of a report on EDVAC was published in 1945, but just had von Neumann's signature!
 - Without a doubt the most influential paper in computer architecture

Program = A sequence of instructions

Program = A sequence of instructions

How to control instruction sequencing?

Program = A sequence of instructions

How to control instruction sequencing?

manual control calculators

Program = A sequence of instructions

How to control instruction sequencing?

manual control calculators

automatic control external (paper tape)

Harvard Mark I, 1944

Program = A sequence of instructions

How to control instruction sequencing?

manual control calculators

automatic control

external (paper tape) Harvard Mark I, 1944

Zuse's Z1, WW2

internal

plug board ENIAC 1946

read-only memory ENIAC 1948 read-write memory EDVAC 1947 (concept)

 The same storage can be used to store program and data

Program = A sequence of instructions

How to control instruction sequencing?

manual control calculators

automatic control external (paper tape

external (paper tape) Harvard Mark I, 1944

Zuse's Z1, WW2

1947 *(concept)*

internal

plug board ENIAC 1946 read-only memory ENIAC 1948

read-write memory EDVAC

 The same storage can be used to store program and data

EDSAC 1950 Maurice Wilkes

The Spread of Ideas

ENIAC & EDVAC had immediate impact

brilliant engineering: Eckert & Mauchly

lucid paper: Burks, Goldstein & von Neumann

IAS	Princeton	46-52	Bigelow
EDSAC	Cambridge	46-50	Wilkes
MANIAC	Los Alamos	49-52	Metropolis
JOHNIAC	Rand	50-53	•
ILLIAC	Illinois	49-52	
	Argonne	49-53	
SWAC	UCLA-NBS		

The Spread of Ideas

ENIAC & EDVAC had immediate impact

brilliant engineering: Eckert & Mauchly

lucid paper: Burks, Goldstein & von Neumann

IAS Princeton 46-52 Bigelow
EDSAC Cambridge 46-50 Wilkes
MANIAC Los Alamos 49-52 Metropolis
JOHNIAC Rand 50-53
ILLIAC Illinois 49-52
Argonne 49-53
SWAC UCLA-NBS

UNIVAC - the first commercial computer, 1951

The Spread of Ideas

ENIAC & EDVAC had immediate impact

brilliant engineering: Eckert & Mauchly

lucid paper: Burks, Goldstein & von Neumann

IAS Princeton 46-52 Bigelow EDSAC Cambridge 46-50 Wilkes

MANIAC Los Alamos 49-52 Metropolis

JOHNIAC Rand 50-53 ILLIAC Illinois 49-52

Argonne 49-53

SWAC UCLA-NBS

UNIVAC - the first commercial computer, 1951

Alan Turing's direct influence on these developments is often debated by historians.

Dominant Technology Issue: Reliability

ENIAC

18,000 tubes 20 10-digit numbers

EDVAC

4,000 tubes 2000 word storage mercury delay lines

Mean time between failures (MTBF)

MIT's Whirlwind with an MTBF of 20 min. was perhaps the most reliable machine!

Reasons for unreliability:

- 1. Vacuum tubes
- 2. Storage medium
 Acoustic delay lines
 Mercury delay lines
 Williams tubes
 Selections

Dominant Technology Issue: Reliability

ENIAC

18,000 tubes 20 10-digit numbers

EDVAC

4,000 tubes 2000 word storage mercury delay lines

Mean time between failures (MTBF)

MIT's Whirlwind with an MTBF of 20 min. was perhaps the most reliable machine!

Reasons for unreliability:

1. Vacuum tubes

2. Storage medium
Acoustic delay lines
Mercury delay lines
Williams tubes
Selections

CORE J. Forrester 1954

Hardware was expensive

- Hardware was expensive
- Stores were small (1000 words)

- Hardware was expensive
- Stores were small (1000 words)
 - ⇒ No resident system-software!

- Hardware was expensive
- Stores were small (1000 words)
 - ⇒ No resident system-software!
- Memory access time was 10 to 50 times slower than the processor cycle

- Hardware was expensive
- Stores were small (1000 words)
 - ⇒ No resident system-software!
- Memory access time was 10 to 50 times slower than the processor cycle
 - ⇒ Instruction execution time was totally dominated by the memory reference time

- Hardware was expensive
- Stores were small (1000 words)
 - ⇒ No resident system-software!
- Memory access time was 10 to 50 times slower than the processor cycle
 - ⇒ Instruction execution time was totally dominated by the memory reference time
- The ability to design complex control circuits to execute an instruction was the central design concern as opposed to the speed of decoding or an ALU operation

- Hardware was expensive
- Stores were small (1000 words)
 - ⇒ No resident system-software!
- Memory access time was 10 to 50 times slower than the processor cycle
 - ⇒ Instruction execution time was totally dominated by the memory reference time
- The ability to design complex control circuits to execute an instruction was the central design concern as opposed to the speed of decoding or an ALU operation
- Programmer's view of the machine was inseparable from the actual hardware implementation

Accumulator-based computing



Photo: Joel Emer

• Single Accumulator

 Calculator design carried over to computers

Accumulator-based computing



Photo: Joel Emer

• Single Accumulator

 Calculator design carried over to computers

Why?

The Earliest Instruction Sets

Burks, Goldstein & von Neumann ~1946

The Earliest Instruction Sets

Burks, Goldstein & von Neumann ~1946

LOAD	X
STORE	X

$$\begin{array}{ccc} x & & AC \leftarrow M[x] \\ x & & M[x] \leftarrow (AC) \end{array}$$

$$AC \leftarrow 2 \times (AC)$$

 $AC \leftarrow (AC) + M[x]$

The Earliest Instruction Sets

Burks, Goldstein & von Neumann ~1946

LOAD	X	$AC \leftarrow M[x]$
STORE	X	$M[x] \leftarrow (AC)$

ADD
$$x$$
 $AC \leftarrow (AC) + M[x]$ SUB x

SHIFT LEFT
$$AC \leftarrow 2 \times (AC)$$

SHIFT RIGHT

The Earliest Instruction Sets

Burks, Goldstein & von Neumann ~1946

LOAD STORE	X X	$AC \leftarrow M[x]$ $M[x] \leftarrow (AC)$
ADD	X	$AC \leftarrow (AC) + M[x]$
SUB	X	

SHIFT LEFT
$$AC \leftarrow 2 \times (AC)$$

SHIFT RIGHT

JUMPxPC
$$\leftarrow$$
 xJGExif (AC) \geq 0 then PC \leftarrow x

LOAD ADR
$$x$$
 AC \leftarrow Extract address field(M[x]) STORE ADR x

The Earliest Instruction Sets

Burks, Goldstein & von Neumann ~1946

LOAD STORE	X X	$AC \leftarrow M[x]$ $M[x] \leftarrow (AC)$
ADD SUB	X X	$AC \leftarrow (AC) + M[x]$
MUL DIV	X X	Involved a quotient register
SHIFT LEFT SHIFT RIGHT		AC ← 2 × (AC)
JUMP JGE	X X	$PC \leftarrow x$ if $(AC) \ge 0$ then $PC \leftarrow x$
LOAD ADR STORE ADR	X X	$AC \leftarrow Extract \ address \ field(M[x])$

Typically less than 2 dozen instructions!

Programming: Single Accumulator Machine

Programming: Single Accumulator Machine

C _i	$\leftarrow A_i + B_i$	$1 \le i \le n$	Α	
LOOP:	LOAD	N	В	
	JGE ADD	DONE ONE		
	STORE	N	С	
F1: F2:	LOAD ADD	A B		
F3:	STORE	С	N	-n
DONE:	JUMP	LOOP	ONE	1
DONE:	HLI			
			code	

Programming: Single Accumulator Machine

C_{i}	$\leftarrow A_i + B_i$	$1 \le i \le n$	Α	
LOOP:	LOAD	N	В	
	JGE ADD	DONE ONE		
F4	STORE	N	С	
F1: F2:	LOAD ADD	A B		
F3:	STORE	C	N	-n
DONE	JUMP : HLT	LOOP	ONE	1
Problem?			code	

LOOP	LOAD	N
	JGE	DONE
	ADD	ONE
	STORE	N
F1	LOAD	Α
F2	ADD	В
F3	STORE	C
	JUMP	LOOP
DONE	HLT	

 $C_i \leftarrow A_i + B_i, \quad 1 \le i \le n$

LOOP	LOAD	N
	JGE	DONE
	ADD	ONE
	STORE	N
F1	LOAD	Α
F2	ADD	В
F3	STORE	C
	JUMP	LOOP
DONE	HLT	

 $C_i \leftarrow A_i + B_i, \quad 1 \le i \le n$

modify the program for the next iteration

LOOP LOAD N JGE DONE ADD ONE **STORE** N F1 LOAD Α F2 ADD В F3 **STORE** LOAD ADR F1 ONE **ADD** STORE ADR F1 modify the LOAD ADR F2 program ADD ONE for the next STORE ADR F2 iteration LOAD ADR F3 **ADD** ONE STORE ADR F3 **JUMP** LOOP DONE HLT

 $C_i \leftarrow A_i + B_i, \quad 1 \le i \le n$

LOOP LOAD N JGE DONE ADD ONE STORE Ν F1 LOAD Α F2 ADD В F3 **STORE** LOAD ADR F1

modify the program for the next iteration

ONE **ADD** STORE ADR F1 LOAD ADR F2 ADD ONE STORE ADR F2 LOAD ADR F3 **ADD** ONE STORE ADR F3 JUMP LOOP HLT

 $C_i \leftarrow A_i + B_i, \quad 1 \le i \le n$

Each iteration involves total bookkeeping

instruction fetches

operand fetches

stores

LOOP LOAD N JGE DONE **ADD** ONE **STORE** N F1 LOAD Α F2 ADD В F3 **STORE**

modify the program for the next iteration

LOAD ADR F1ONE **ADD** STORE ADR F1 LOAD ADR F2 ONE ADD STORE ADR F2 LOAD ADR F3 **ADD** ONE STORE ADR F3 JUMP LOOP HLT

 $C_i \leftarrow A_i + B_i, \quad 1 \le i \le n$

Each iteration involves total bookkeeping

instruction fetches

operand fetches

stores

Most of the executed instructions are for bookkeeping!

DONE

Tom Kilburn, Manchester University, mid 50's

One or more specialized registers to simplify address calculation

Tom Kilburn, Manchester University, mid 50's

One or more specialized registers to simplify address calculation

Modify existing instructions

LOAD x, IX ADD x, IX

 $X, IX \qquad AC \leftarrow M[X + (IX)]$

 $AC \leftarrow (AC) + M[x + (IX)]$

. . .

Tom Kilburn, Manchester University, mid 50's

One or more specialized registers to simplify address calculation

Modify existing instructions

LOAD x, IX $AC \leftarrow M[x + (IX)]$ ADD x, IX $AC \leftarrow (AC) + M[x + (IX)]$

• • •

Add new instructions to manipulate index registers

JZi x, IX if (IX)=0 then PC \leftarrow x else IX \leftarrow (IX) + 1 LOADi x, IX IX \leftarrow M[x] (truncated to fit IX)

. . .

Tom Kilburn, Manchester University, mid 50's

One or more specialized registers to simplify address calculation

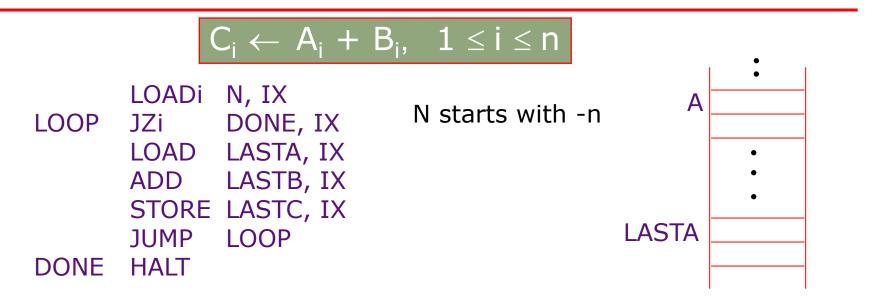
Modify existing instructions

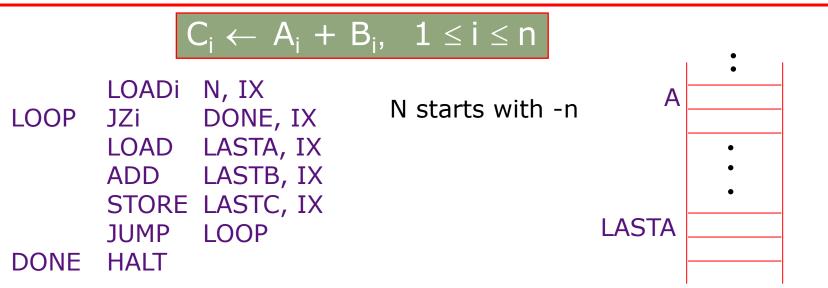
LOAD
$$x$$
, IX $AC \leftarrow M[x + (IX)]$
ADD x , IX $AC \leftarrow (AC) + M[x + (IX)]$

Add new instructions to manipulate index registers

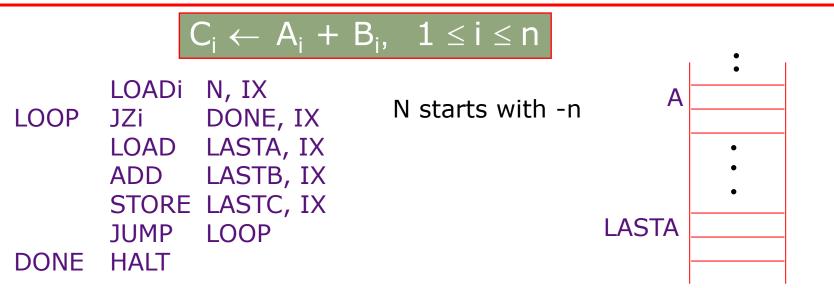
JZi x, IX if
$$(IX)=0$$
 then $PC \leftarrow x$ else $IX \leftarrow (IX) + 1$ LOADi x, IX $IX \leftarrow M[x]$ (truncated to fit IX)

Index registers have accumulator-like characteristics

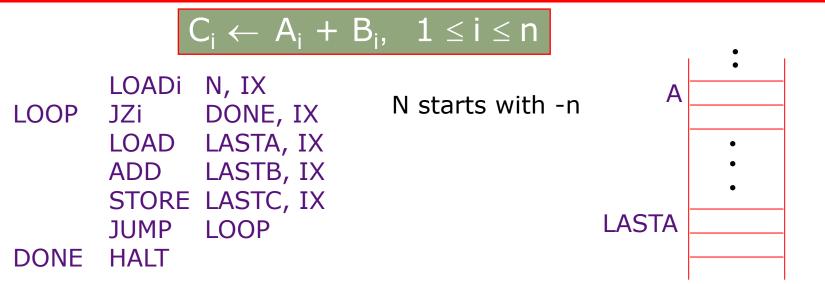




Program does not modify itself

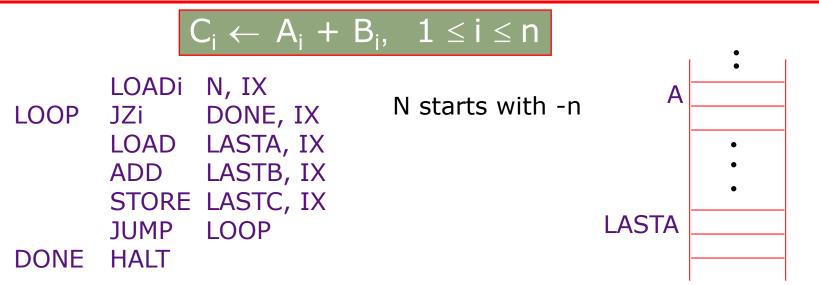


- Program does not modify itself
- Efficiency has improved dramatically (ops / iter)



- Program does not modify itself
- Efficiency has improved dramatically (ops / iter)

```
with index regs without index regs instruction fetch 17 (14) operand fetch 10 (8) store 5 (4)
```



- Program does not modify itself
- Efficiency has improved dramatically (ops / iter)

```
with index regs without index regs instruction fetch 17 (14) operand fetch 10 (8) store 5 (4)
```

Costs?

To increment index register by k

 $AC \leftarrow (IX)$

new instruction

 $AC \leftarrow (AC) + k$

 $IX \leftarrow (AC)$

new instruction

To increment index register by k

 $AC \leftarrow (IX)$ new instruction

 $AC \leftarrow (AC) + k$

 $IX \leftarrow (AC)$ new instruction

also the AC must be saved and restored

To increment index register by k

$$AC \leftarrow (IX)$$
 new instruction

$$AC \leftarrow (AC) + k$$

$$IX \leftarrow (AC)$$
 new instruction

also the AC must be saved and restored

It may be better to increment IX directly INCi k, IX $IX \leftarrow (IX) + k$

To increment index register by k

$$AC \leftarrow (IX)$$
 new instruction

$$AC \leftarrow (AC) + k$$

$$IX \leftarrow (AC)$$
 new instruction

also the AC must be saved and restored

It may be better to increment IX directly

INCi k, IX
$$IX \leftarrow (IX) + k$$

More instructions to manipulate index register

STOREi x, IX
$$M[x] \leftarrow (IX)$$
 (extended to fit a word)

. . .

To increment index register by k

$$AC \leftarrow (IX)$$
 new instruction

$$AC \leftarrow (AC) + k$$

$$IX \leftarrow (AC)$$
 new instruction

also the AC must be saved and restored

It may be better to increment IX directly INCi k, IX $IX \leftarrow (IX) + k$

More instructions to manipulate index register

STOREi x, IX
$$M[x] \leftarrow (IX)$$
 (extended to fit a word)

. . .

IX begins to look like an accumulator

⇒ several index registers several accumulators

⇒ General Purpose Registers

1. Single accumulator, absolute address

LOAD x

1. Single accumulator, absolute address

LOAD x

2. Single accumulator, index registers

LOAD x, IX

1. Single accumulator, absolute address

LOAD x

2. Single accumulator, index registers

LOAD x, IX

3. Indirection

LOAD (x)

1. Single accumulator, absolute address

2. Single accumulator, index registers

3. Indirection

4. Multiple accumulators, index registers, indirection

LOAD R, IX, x or LOAD R, IX, (x) the meaning?
$$R \leftarrow M[M[x] + (IX)]$$
 or $R \leftarrow M[M[x + (IX)]]$

1. Single accumulator, absolute address

2. Single accumulator, index registers

3. Indirection

or

4. Multiple accumulators, index registers, indirection

LOAD R, IX, x

LOAD R, IX, (x) the meaning?

$$R \leftarrow M[M[x] + (IX)]$$
or $R \leftarrow M[M[x + (IX)]]$

5. Indirect through registers

LOAD
$$R_{I}$$
, (R_{J})

1. Single accumulator, absolute address

2. Single accumulator, index registers

3. Indirection

or

4. Multiple accumulators, index registers, indirection

LOAD R, IX, x

LOAD R, IX, (x) the meaning?

$$R \leftarrow M[M[x] + (IX)]$$
or $R \leftarrow M[M[x + (IX)]]$

5. Indirect through registers

LOAD
$$R_{I}$$
, (R_{J})

6. The works

LOAD
$$R_I$$
, R_J , (R_K) R_J = index, R_K = base addr

Instruction sets in the mid 50's

 Great variety of instruction sets, but all intimately tied to implementation details

 Programmer's view of the machine was inseparable from the actual hardware implementation!

Instruction sets in the mid 50's

 Great variety of instruction sets, but all intimately tied to implementation details

 Programmer's view of the machine was inseparable from the actual hardware implementation!

Next Lecture: Instruction Set Architectures and Caches