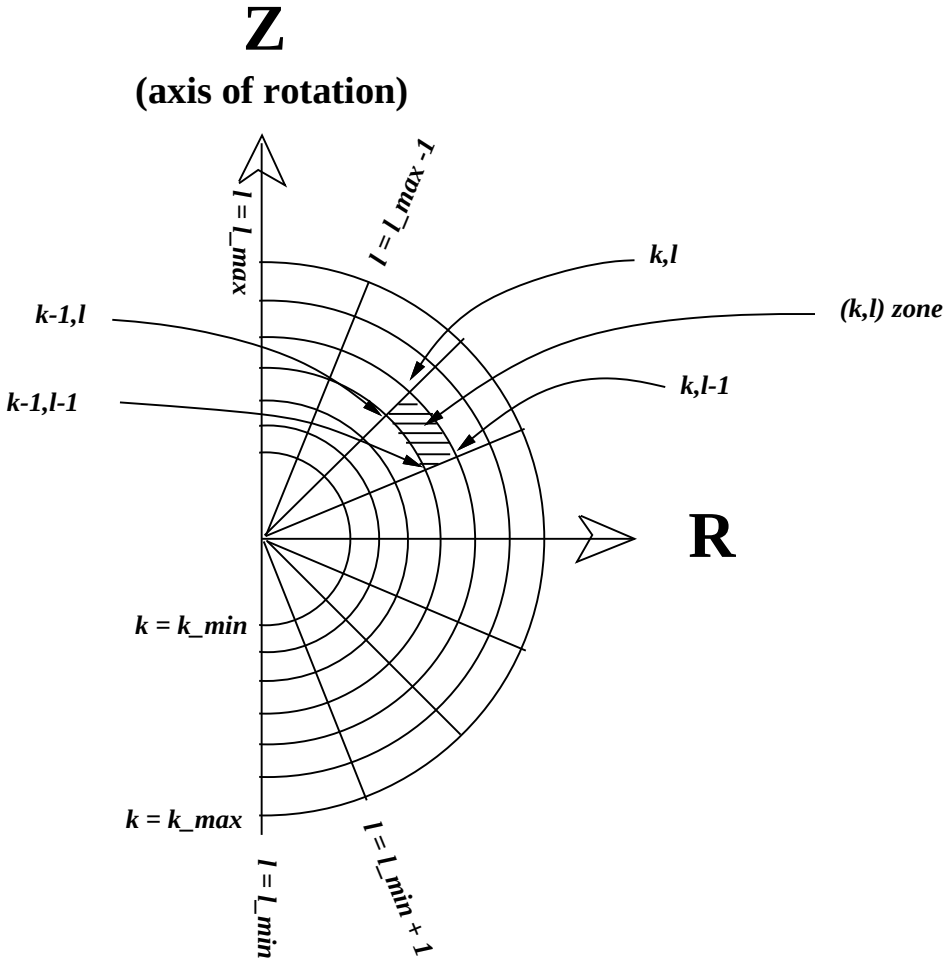
Z
(axis of rotation)
l = l_max
l = l_max -1
k,l
(k,l) zone
k-1,l
k-1,l-1
k,l-1
R
k = k_min
k = k_max
l = l_min
l = l_min + 1