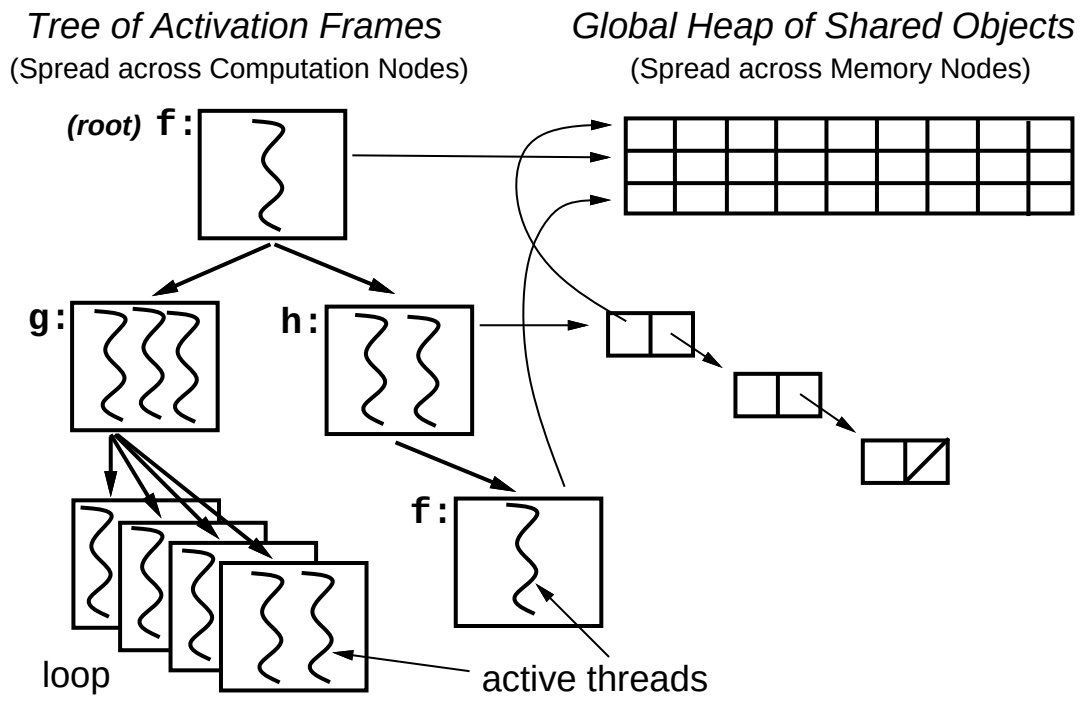
Tree of Activation Frames
(Spread across Computation Nodes)
Global Heap of Shared Objects
(Spread across Memory Nodes)
(root) f:
g:
h:
f:
loop
active threads